**Present:**

Daniel Williams, Ian McInerney

**Outcomes:**

Annotated bibliography and summary of the state of the art discussed.

Contrast regulation control with optimal control. Look at works in which the trajectory planner and control are split, and where they are unified. Can we integrate the control requirements into the trajectory problem?

Consider how will the formulation assumptions constrain the solution. What information and capabilities will be lost?

The general problem is what we want to solve; make specific assumptions to formulate a sub-problem that we will try to solve.

Install ICLOCS, install and play around with it.

*For Friday: state the general problem + specific assumptions (maths formulation not required yet).*