**Present:**

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**Outcomes:**

After much trouble, IPOPT and ICLOCS2 are now installed.

Current focus: understanding the structure of ICLOCS2 scripts, formulating problem for single agent trajectory optimization in minimum time (double-integrator model), simulation using ICLOCS2-MATLAB.

Next: bringing ICLOCS2-MATLAB and ROS-Gazebo together for the single agent model, then extension to the KAUST dual-agent model.