**Present:**

Daniel Williams, Ian McInerney

**Outcomes:**

Query about Simulink model for closed-loop trajectory planning; breakdown of components, role of ICLOCS in the system, UAV representation as a block.

InitSim - run this first.

ICLOCS\_NLPSolver - backend for Simulink, contains the conditions for the ICLOCS solution.

> Replace 'Aircraft and other dynamics' block completely with the UAV model.

> Try obstacles (path constraints), velocity constraints, other general constraints

> Make a list of the typos for the ICLOCS website