**Present:**

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**Outcomes:**

* Report feedback
* ROS and MATLAB
  + publishing and receiving messages
  + data interfaces from ICLOCS
  + topics and services for information sharing
  + Time scales – ICLOCS runs synchronously or asynchronously?
* Outstanding issues with the problem formulation:
  + Equations of motion
  + Zone contracts for localization and avoiding inter-agent collisions
  + **Try modelling the system of bodies using Simscape**
* **Do the problem formulation in parallel with ROS, but prioritize the former**