**Present:**

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**Outcomes:**

* Coordinates scheme
* Zone contracts
  + Central computation vs. Individual computation
  + Extent of communication
  + Safety cones around the agent’s attachment points
  + Peer-centric safety zones
  + **Focus on individual computation, with minimal communication with peers and safety cones centered on the attachment points to the payload.**
* Outstanding issues with the problem formulation:
  + **Equations of motion using Euler-Lagrange equations**
  + **Try modelling the system of bodies using Simscape**
* **Do the problem formulation in parallel with ROS, but prioritize the former**