**Present:**

Daniel Williams, Ian McInerney

**Outcomes:**

* Simscape model
  + One agent + cable + payload: issues with speed, positive feedback leading to a singularity
  + Try ode23t
  + Consider adding joint friction, gravity
  + Add the other agents
  + Goal: move from one place to another
* **Derive model of state space for ICLOCS**
* **Incorporate Simscape model into ICLOCS-Simulink system**