**Present:**

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**Outcomes:**

* Have read IPOPT tutorial to understand how path equality constraints are handled
* Debugging ICLOCS code (single agent repositioning, single agent with slung load, single agent with slung load plus two extra agents)
  + Numerous constraints on states and inputs inconsistent
* Future tasks
  + **implementation of closed-loop problem in Simulink,**
  + **comparison with Simscape model (results, computation time)**