**Present:**

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**Outcomes:**

* Open loop centralized repositioning problem achieved with three agents with slung load
* Future tasks for centralized controller
  + Test linear v nonlinear model (computation time)
  + Closed loop with Simscape
  + Add constraints (obstacle, anti-collision) and check computation time and feasibility
* Obstacles:
  + Turn around an obstacle
  + Lift over an obstacle
  + Bubble containing all three agents – could be more generalizable to other types of obstacle situations