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Greetings!

-----PROJECT ANALYSIS REPORT-----

PROJECT TITLE: DESIGN AND DEVELOPMENT OF A ROBOTIC ARM GRIPPER FOR
TRANSPLANTING TOMATO SEEDLINGS

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Research focus

Design and Prototype a robotic arm gripper

- *Conduct a comprehensive analysis of gripper's motion dynamics
- *Establish a coherent causal relationship among operational variables

21 Optimised Parameters (a, b, c): [0.20783886 -0.03604994 2.1157152]

Invalid parameters in the fitted curve.

Correlation Coefficient of gear ratio and angular displacement: 0.8101

Correlation Coefficient of rack displacement and angular displacement: 0.9999

Correlation Coefficient of rack displacement and gear ratio: 0.8060

R-squared for the fitted curve is: 0.9956760742919778

The covariance of the parameters a,b,c are:

Covariance of a: 3.676523078947466e-05

Covariance of b: 4.252209593786408e-07

Covariance of c: 1.0795514658339364e-05

Standard Deviations of a, b, c respectively: [0.00606343 0.00065209 0.00328565]

p_values: [0. 0. 0.]

a: Estimate=0.2078,SE=0.0061, t=34.2774, p=0.000000e+00

b: Estimate=-0.0360,SE=0.0007, t=-55.2837, p=0.000000e+00

c: Estimate=2.1157,SE=0.0033, t=643.9254, p=0.000000e+00

Average gear ratio in the range 0.0s to 0.8s is: 1.8233159949968 + 0.00936572314321749*I*pi

The value of y Intercept: -0.0227

The value of Slope: 38.6685

Average radius: 6.0

Maximum tomato strain: 0.48

Total cross section area: 113.1

The constant c is: 6.73877396706786

validation correlation value: 0.9998977422

Validation of prediction model with R squared using corrcoef(): 0.9997954948653242

Validation of prediction model with R squared using linregress(): 0.9997954948653242

Validation of prediction model with standard error using linregress(): 0.0032804309114066958

slope: 0.9997954948653242

intercept 0.02333599750494697