

**Problem 1** Write, test and debug a matlab function

```
function [p, q] = pcoeff( t, n, k )
% t: solution times t(1) < t(2) < ... < t(n) < t( n+1 )
% n+1: new time step
% k: number of previous steps t(n-k+1)..t(n)
```

which computes coefficients  $p$  and  $q$  for the  $k$ -step predictor-corrector method

$$v_{n+1} = u_n + \int_{t_n}^{t_{n+1}} p(t) dt = u_n + p_1 f_n + p_2 f_{n-1} + \cdots p_k f_{n-k+1},$$

$$u_{n+1} = u_n + \int_{t_n}^{t_{n+1}} q(t) dt = u_n + q_1 f(t_{n+1}, v_{n+1}) + q_2 f_n + \cdots q_k f_{n-k+2}.$$

Here  $p(t)$  is the degree  $k-1$  polynomial which interpolates the values  $f_j = f(t_j, u_j)$  for  $n-k+1 \leq j \leq n$  and  $q(t)$  is the degree  $k-1$  polynomial which interpolates the values  $f_j$  for  $n-k+2 \leq j \leq n$  and also the predicted slope  $f(t_{n+1}, v_{n+1})$  at  $t_{n+1}$ . Thus

$$p_j = \int_{t_n}^{t_{n+1}} \prod_{i \neq j} \frac{t - t_{n-i+1}}{t_{n-j+1} - t_{n-i+1}}$$

and

$$q_j = \int_{t_n}^{t_{n+1}} \prod_{i \neq j} \frac{t - t_{n-i+2}}{t_{n-j+2} - t_{n-i+2}}$$

for  $1 \leq j \leq k$ . Tabulate the coefficients  $p$  and  $q$  with constant step size  $h = 1$  and  $k \leq 5$  and verify against Adams-Bashforth and Adams-Moulton methods. (Hint: the integrands are polynomials of degree  $k-1$  for which  $\lceil k/2 \rceil$  Gaussian integration points and weights will give an *exact* result.)

**Problem 2** Write, test and debug a matlab function

```
function [ t, u ] = pcode(a, b, ua, f, r, k, N)
% a,b: interval endpoints with a < b
% ua: vector u_1 = y(a) of initial conditions
% f: function handle f(t, u, r) to integrate
% r: parameters to f
% k: number of previous steps to use at each regular time step
% N: total number of time steps,
% t: output times for numerical solution u_n ~ y(t_n), t(1) = a, t(N) = b
% u: numerical solution at times t
```

which uses `pcoeff` to approximate the solution vector  $y(t)$  of the vector initial value problem

$$y' = f(t, y, r)$$

$$y(a) = y_a$$

by the family of methods you derived in problem 1, with  $u_1 = y_a$ . Start with  $k_1 = 1$  and a tiny step size

$$h_1 = (b - a) \left( \frac{h}{b - a} \right)^{k/2}$$

which brings the one-step error in line with the  $O(h^k)$  error. Increase the step size smoothly (e.g. by  $h_1 \leftarrow (1 + 1/k)h_1$ ) and increase  $k_1$  (e.g. by steps of 1 up to  $k$ ) until  $h_1 \geq h = (b - a)/(N - 1)$  and then continue with uniform step sizes. (To save CPU time, (a) when the most recent  $k$  step sizes are uniform, the predictor-corrector coefficients  $p$  and  $q$  can be frozen and (b) many values of  $f$  can be saved rather than re-evaluated.)

(a) Use `pcode.m` with odd  $k = 1$  through 11 and  $N = 10000, 20000, 40000, 80000$  and 160000 to approximate the final solution vector  $u(T)$  of the initial value problem derived in problem 4 of problem set 8. Tabulate the errors

$$E_{kN} = \max_{1 \leq j \leq 4} |u_j(T) - u_j(0)|.$$

Estimate the constant  $C_k$  such that the error behaves like  $C_k h^k$ .

(b) Measure the CPU time for each run and estimate the total CPU time necessary to obtain an orbit which is periodic to three-digit, six-digit and twelve-digit accuracy.

(c) Plot some inaccurate solutions and some accurate solutions and draw conclusions about values of  $k$  which give three, six or twelve digits of accuracy for minimal CPU time.

(d) Compare to the results of `euler.m` and `idec.m`.

**Problem 3** Consider a differential equation

$$y'(t) = f(t, y(t)),$$

where  $f$  satisfies the condition

$$(u - v)(f(t, u) - f(t, v)) \leq 0$$

for all  $u$  and  $v$ .

(a) Suppose  $U(t)$  and  $V(t)$  are exact solutions. Show that

$$|U(t) - V(t)| \leq |U(0) - V(0)|$$

for all  $t \geq 0$ .

(b) Suppose  $W$  satisfies a perturbed differential equation

$$W'(t) = f(t, W(t)) + r(t)$$

for  $t \geq 0$ . Show that

$$|U(t) - W(t)| \leq |U(0) - W(0)| + \int_0^t |r(s)| ds$$

for  $t \geq 0$ .

(c) Show that two numerical solutions  $u_n$  and  $v_n$  generated by implicit Euler (e.g. with different initial values) satisfy

$$|u_n - v_n| \leq |u_0 - v_0|$$

for all  $n \geq 0$ .

(d) Show that the local truncation error  $\tau_{n+1}$  of the implicit Euler method

$$u_{n+1} = u_n + hf(t_{n+1}, u_{n+1})$$

is given by

$$\tau_{n+1} = \frac{y_{n+1} - y_n}{h} - f(t_{n+1}, y_{n+1}) = -\frac{h}{2}y''(\zeta)$$

where  $y_n = y(t_n)$  is the exact solution and  $\zeta$  is an unknown point.

(e) Show that the numerical solution  $u_n$  generated by implicit Euler with  $u_0 = y_0$  satisfies

$$|u_n - y_n| \leq nh\tau$$

for  $0 \leq nh < \infty$ , where  $\tau = Mh/2$  and  $|y''| \leq M$ .

**Problem 4** Consider the linear initial value problem

$$y' = -L(y(t) - \varphi(t)) + \varphi'(t)$$

$$y(0) = y_0$$

where  $\varphi(t) = \cos(30t)$ .

(a) Solve the initial value problem exactly.

(b) Use `euler.m` to solve the initial value problem with  $y(0) = 2$  for  $0 \leq t \leq 1$  with  $L = 10^k$  for  $k = 1$  to 5. For each  $L$  use  $h = 10^{-j}$  with  $j = 1$  to 6. Tabulate the errors.

(c) Write a matlab script `ieuler.m` which uses the implicit Euler method to solve the initial value problem with  $y(0) = 2$  for  $0 \leq t \leq 1$  with  $L = 10^k$  for  $k = 1$  to 5. For each  $L$  use  $h = 10^{-j}$  with  $j = 1$  to 6. Tabulate the errors. Plot an accurate solution for each  $L$ .

**Problem 5** (cf. BFB 6.1.12) Write, test and debug a matlab code

```
function [t, u] = solveinteq( a, b, kernel, rhs, p, n )
% a, b: endpoints of interval
% kernel: function handle for kernel K = kernel( t, s ) of integral equation
% rhs: function handle for right-hand side f = rhs( t, p ) of integral equation
% p: parameters for rhs
% n: number of quadrature points and weights
% t: evaluation points in [a,b]
% u: solution values at evaluation points
```

which uses  $n$ -point Gaussian quadrature points  $t_i$  and weights  $w_i$  on  $[a, b]$  (generated by `gaussint.m`) to approximate the solution  $y(t)$  of the integral equation

$$y(t) + \int_a^b K(t, s)y(s) ds = f(t, p) \quad (1)$$

on the interval  $a \leq t \leq b$ . Your code should set up the  $n \times n$  linear system

$$u_i + \sum_{j=1}^n K(t_i, t_j)w_j u_j = f(t_i, p) \quad (2)$$

for approximate values  $u_i \approx y(t_i)$  and solve it by Gaussian elimination with partial pivoting.

(a) Suppose  $[a, b] = [0, 1]$  and the kernel  $K$  is given by  $K(t, s) = \cos(t)\sin(s)$ . For any positive real number  $m$ , find a right-hand side  $f(t, m)$  such that the exact solution  $y(t)$  of the integral equation (1) is given by  $y_m(t) = \cos(mt)$ .

(b) Solve the problem in (a) numerically by `solveinteq`, using even  $n = 2$  through 16 and odd integers  $m = 1$  through 9. Tabulate the errors at integration points

$$E_n = \max_{1 \leq i \leq n} |u_i - y_m(t_i)|$$

vs.  $m$  and  $n$ .

(c) For an arbitrary right-hand side  $f$  and the specific kernel  $K(t, s) = \cos(t)\sin(s)$  in (a), find a formula for the exact solution  $u$  of the linear system of equations (2).

(d) Use the error formula for Hermite interpolation to show that the local truncation error in (a)

$$\tau_i = y(t_i) + \sum_{j=1}^n w_j K(t_i, t_j)y(t_j) - f(t_i)$$

is bounded by

$$|\cos(t_i)| \left( \int_0^1 \prod_{i=1}^n (t - t_i)^2 dt \right) \left| \frac{v^{(2n)}(\xi)}{(2n)!} \right|$$

as  $n \rightarrow \infty$ , where  $v(s) = \sin(s)y(s)$ .

(e) Assume that all the derivatives of the exact solution  $y$  in (a) are bounded by

$$|y^{(n)}(t)| \leq m^n$$

for some fixed  $m > 0$ . Use (d) and (c) to prove that

$$E_n \leq 2 \max_i |\tau_i| \rightarrow 0$$

as  $n \rightarrow \infty$ .