

20220520-机器学习

1.学习内容

1.1 机器学习

CNN类

2.结果描述

1.学习内容

1.1 机器学习

CNN类

```
1  #pragma once
2  #ifndef CNN_H_
3  #define CNN_H_
4
5  #include "Matrix.h"
6  #include <string>
7  #include <fstream>
8  #include <iostream>
9  #include <vector>
10 #include <math.h>
11 #pragma warning(disable:4996)
12 #define PI 3.141592654
13 class CNN
14 {
15 public:
16     CNN();
17     std::vector<std::vector<uint8_t>> GetFeature(std::string
feature_file);
18
19     std::vector<uint8_t> GetLabel(std::string label_file);
20
21     std::vector<std::vector<uint8_t>> labelMatTran(std::vector<uint8_t>&
labelMat);
22
23     std::vector<std::vector<double>> convWeightInl(int num_f,int num_r,
int num_c);
24
25     std::vector<double> convBiasInl();
26
27     std::vector<std::vector<double>> convLayer(
28         std::vector<std::vector<uint8_t>> &FeatureMat,
29         std::vector<std::vector<double>> &filter,
30         std::vector<double> &biasMat,int picIndex);
31
32     std::vector<std::vector<double>> convActivate(
33         std::vector<std::vector<double>> convMat);
34
35     std::vector<std::vector<double>> poolingLayer(
36         std::vector<std::vector<double>>& convMat_);
37
38     std::vector<double> outputBiasInl();
39
40     std::vector<std::vector<std::vector<double>>> outputWeightInl(int
stride);
41
```

```

42     std::vector<double> outputLayer(
43         std::vector<std::vector<double>>& poolingMat,
44         std::vector<std::vector<std::vector<double>>>& outputWeight,
45         std::vector<double>& biasMat);
46
47     std::vector<double> softmax(std::vector<double>& outputMat);
48
49     void paramUpdate(
50         int batchSize,
51         std::vector<std::vector<uint8_t>>& featureMat,
52         std::vector<uint8_t>& labelMat,
53         std::vector<std::vector<uint8_t>>& labelMatZ0,
54         std::vector<std::vector<double>>& filterMat,
55         std::vector<double>& convBias,
56         std::vector<std::vector<std::vector<double>>>& outputWeight,
57         std::vector<double>& outputBias);
58
59     void train(double lr,int epoch,int batchSize,int actiTypein,
60         std::vector<std::vector<uint8_t>>& featureMat,
61         std::vector<uint8_t>& labelMat,
62         std::vector<std::vector<uint8_t>>& labelMatZ0,
63         std::vector<std::vector<double>>& filterMat,
64         std::vector<double>& convBias,
65         std::vector<std::vector<std::vector<double>>>& outputWeight,
66         std::vector<double>& outputBias);
67
68     void test(
69         std::vector<std::vector<uint8_t>>& featureMat,
70         std::vector<uint8_t>& labelMat,
71         std::vector<std::vector<double>>& filterMat,
72         std::vector<double>& convBias,
73         std::vector<std::vector<std::vector<double>>>& outputWeight,
74         std::vector<double>& outputBias);
75
76 public:
77     uint32_t convert_to_little_endian(const unsigned char* bytes);
78     double MaxV(std::vector<double> poolBlock);
79     double GaussRand(double a,double b);
80
81 private:
82
83     int numPic;
84     int testnumPic;
85     int numRowsPixel;
86     int numColPixel;
87     int PicSize;
88     int numFilter;
89     int filterRow;

```

```
90     int filterCol;
91     int filterSize;
92     int convEleNum;
93     int numLabel;
94     int poolStride;
95     int convMatColNum;
96     int poolMatColNum;
97     int poolMatSize;
98     double learnR;
99     double softmaxMediator;
100    int actiType;
101    std::vector<double> lossMat;
102 };
103
104 #endif
```

```
1  #include "CNN.h"
2
3  CNN::CNN()
4  {
5      numLabel = 10;
6      numPic = 60000;
7      testnumPic = 10000;
8  }
9  //-----<数据读取与存储>-----
10
11  /*获取样本的特征数据*/
12  std::vector<std::vector<uint8_t>> CNN::GetFeature(std::string
13  feature_file)
14  {
15      std::ifstream fp(feature_file, std::ios::binary);
16      while (!fp.is_open())
17      {
18          std::cout << "Can not open feature file!" << std::endl;
19          exit(-1);
20      }
21
22      uint32_t header[4]={};
23      unsigned char bytes[4];
24
25      for (int i = 0; i < 4; i++)
26      {
27          if (fp.read((char*)bytes, sizeof(bytes)))
28          {
29              header[i] = convert_to_little_endian(bytes);
30          }
31      }
32      //numPic = header[1];
33      numRowsPixel = header[2];
34      numColPixel = header[3];
35      PicSize = numRowsPixel * numColPixel;
36      std::vector < std::vector<uint8_t>> featureMat;
37      for (int j = 0; j < numPic; j++)
38      {
39          std::vector<uint8_t> imageF;
40          for (int k = 0; k < PicSize; k++)
41          {
42              uint8_t element[1];
43              if (fp.read((char*)&element, sizeof(element)))
44              {
45                  imageF.push_back(element[0]);
46              }
47          }
48      }
49  }
```

```

44         }
45     }
46     featureMat.push_back(imageF);
47 }
48 //std::cout << static_cast<int>(featureMat[0][159]);
49 return featureMat;
50 }
51 /*获取样本的标签数据*/
52 std::vector<uint8_t> CNN::GetLabel(std::string label_file)
53 {
54     FILE* lp = fopen(label_file.c_str(), "r");
55     while (!lp)
56     {
57         std::cout << "Can not open label file" << std::endl;
58         exit(-1);
59     }
60     uint32_t lheader[2]={};
61     unsigned char lbytes[4];
62     for (int i = 0; i < 2; i++)
63     {
64         if (std::fread(lbytes, sizeof(lbytes), 1, lp))
65         {
66             lheader[i] = convert_to_little_endian(lbytes);
67         }
68     }
69     std::vector<uint8_t> labelData;
70     for (int j = 0; j < lheader[1]; j++)
71     {
72         uint8_t lelement[1];
73         if (std::fread(lelement, sizeof(lelement), 1, lp))
74         {
75             labelData.push_back(lelement[0]);
76         }
77     }
78     //std::cout << static_cast<int>(labelData[2]) << std::endl;
79     return labelData;
80 }
81 /*将标签数据转化为0-1矩阵*/
82 std::vector<std::vector<uint8_t>>
83 CNN::labelMatTran(std::vector<uint8_t>& labelMat)
84 {
85     std::vector<std::vector<uint8_t>> labelMatZ0;
86     for (int i = 0; i < numPic; i++)
87     {
88         std::vector<uint8_t> labelArrayZ0;
89         for (int j = 0; j < numLabel; j++)
90         {
91             if (j == labelMat[i])

```

```

91     {
92         labelArrayZ0.push_back(1);
93     }
94     else
95     {
96         labelArrayZ0.push_back(0);
97     }
98 }
99 labelMatZ0.push_back(labelArrayZ0);
100 }
101 return labelMatZ0;
102 }
103 //-----<参数初始化>-----
-----
104 /*卷积层 (filter) 权重初始化*/
105 std::vector<std::vector<double>> CNN::convWeightInl(int num_f, int
num_r, int num_c)
106 {
107     numFilter = num_f;
108     filterRow = num_r;
109     filterCol = num_c;
110     filterSize = filterRow * filterCol;
111     std::vector<std::vector<double>> filter_matrix;
112     for (int i = 0; i < num_f; i++)
113     {
114         std::vector<double> filter_array;
115         for (int j = 0; j < filterSize; j++)
116         {
117             double randW = GaussRand(0,1/double(5));
118             filter_array.push_back(randW);
119         }
120         filter_matrix.push_back(filter_array);
121     }
122     return filter_matrix;
123 }
124 /*卷积层bias初始化*/
125 std::vector<double> CNN::convBiasInl()
126 {
127     std::vector<double> biasMatrix;
128
129     for (int i = 0; i < numFilter; i++)
130     {
131         double randB = GaussRand(0, 1/double(5));
132
133         biasMatrix.push_back(randB);
134     }
135     return biasMatrix;
136 }

```

```

137  /*输出层（池化层到输出层）权重初始化*/
138  std::vector<std::vector<std::vector<double>>> CNN::outputWeightInl(int
    stride)
139  {
140      poolStride = stride;
141      convMatColNum = numRowsPixel - filterRow + 1;
142      poolMatColNum = convMatColNum / poolStride;
143      poolMatSize = poolMatColNum * poolMatColNum;
144      std::vector<std::vector<std::vector<double>>> outputWeightMat;
145      for (int i = 0; i < numLabel; i++)
146      {
147          std::vector<std::vector<double>> outputWeightLabelMat;
148          for (int j = 0; j < numFilter; j++)
149          {
150              std::vector<double> outputWeightArray;
151              for (int p = 0; p < poolMatSize; p++)
152              {
153                  double randW = GaussRand(0, 1/double(5));
154                  outputWeightArray.push_back(randW);
155              }
156              outputWeightLabelMat.push_back(outputWeightArray);
157          }
158          outputWeightMat.push_back(outputWeightLabelMat);
159      }
160      return outputWeightMat;
161  }
162  /*输出层bias初始化*/
163  std::vector<double> CNN::outputBiasInl()
164  {
165      std::vector<double> biasMatrix;
166      for (int i = 0; i < numLabel; i++)
167      {
168          double randB = GaussRand(0, 1/double(5));
169          biasMatrix.push_back(randB);
170      }
171      return biasMatrix;
172  }
173  //-----<forward运算：卷积、池化、全连接输出>-----
  -----
174  /*filter与原始数据进行卷积运算（互相关运算）*/
175  std::vector<std::vector<double>> CNN::convLayer(
176      std::vector<std::vector<uint8_t>> &FeatureMat,
177      std::vector<std::vector<double>> &filter,
178      std::vector<double> &biasMat,
179      int picIndex)
180  {
181      std::vector<std::vector<double>> convMat;

```



```

182     convEleNum = (numRowPixel - filterRow + 1) * (numColPixel -
filterCol + 1);
183     double conValue;
184     for (int i = 0; i < numFilter; i++)
185     {
186         std::vector<double> convArray;
187         for (int j = 0; j < (numRowPixel - filterRow + 1); j++)
188         {
189             for (int k = 0; k < (numColPixel - filterCol + 1); k++)
190             {
191                 conValue = 0;
192                 for (int p = 0; p < filterRow; p++)
193                 {
194                     for (int g = 0; g < filterCol; g++)
195                     {
196                         conValue += FeatureMat[picIndex][j * numRowPixel
+ k + p * numRowPixel + g] * filter[i][p * filterRow + g];
197                     }
198                 }
199                 conValue = conValue + biasMat[i];
200                 convArray.push_back(conValue);
201             }
202         }
203         convMat.push_back(convArray);
204     }
205
206     return convMat;
207 }
208 /*卷积层激活函数应用*/
209 std::vector<std::vector<double>>
CNN::convActivate(std::vector<std::vector<double>> convMat)
210 {
211     if (actiType == 0)
212     {
213         //sigmoid激活
214         for (auto i = convMat.begin(); i != convMat.end(); i++)
215         {
216             for (auto j = (*i).begin(); j != (*i).end(); j++)
217             {
218                 *j = 1 / (1 + std::exp((-1)*(*j)));
219             }
220         }
221         return convMat;
222     }
223     else if (actiType == 1)
224     {
225         //relu激活
226         for (auto i = convMat.begin(); i != convMat.end(); i++)

```

```

227     {
228         for (auto j = (*i).begin(); j != (*i).end(); j++)
229         {
230             if (*j <= 0)
231             {
232                 *j = 0;
233             }
234             else
235             {
236                 *j = *j;
237             }
238         }
239     }
240     return convMat;
241 }
242 }
243 /*池化层最大池化运算*/
244 std::vector<std::vector<double>> CNN::poolingLayer(
245     std::vector<std::vector<double>> &convMat_)
246 {
247     std::vector<std::vector<double>> poolingMat;
248
249     for (int i = 0; i < numFilter; i++)
250     {
251         std::vector<double> poolingArray;
252         for (int j = 0; j < poolMatColNum; j++)
253         {
254             for (int p = 0; p < poolMatColNum; p++)
255             {
256                 std::vector<double> poolBlock;
257                 for (int q = 0; q < poolStride; q++)
258                 {
259                     for (int d = 0; d < poolStride; d++)
260                     {
261                         poolBlock.push_back(convMat_[i][j *
convMatColNum * poolStride + p * poolStride + convMatColNum * q + d]);
262                     }
263                 }
264                 poolingArray.push_back(MaxV(poolBlock));
265             }
266         }
267         poolingMat.push_back(poolingArray);
268     }
269     return poolingMat;
270 }
271 /*输出层运算*/
272 std::vector<double> CNN::outputLayer(
273     std::vector<std::vector<double>>& poolingMat,

```

```

274     std::vector<std::vector<std::vector<double>>>& outputWeight,
275     std::vector<double>& biasMat
276 )
277 {
278     std::vector<double> outputMat;
279     for (int i = 0; i < numLabel; i++)
280     {
281         double outputValue = 0;
282         for (int j = 0; j < numFilter; j++)
283         {
284             for (int p = 0; p < poolMatSize; p++)
285             {
286                 outputValue += outputWeight[i][j][p] * poolingMat[j][p];
287             }
288         }
289         outputValue += biasMat[i];
290         outputMat.push_back(outputValue);
291     }
292     return outputMat;
293 }
294 /*softmax函数应用*/
295 std::vector<double> CNN::softmax(std::vector<double> &outputMat)
296 {
297
298     double sum = double(0);
299     for (int i = 0; i < numLabel; i++)
300     {
301         sum += std::exp(outputMat[i]);
302     }
303     softmaxMediator = sum;
304     for (int j = 0; j < numLabel; j++)
305     {
306         outputMat[j] = std::exp(outputMat[j]) / sum;
307     }
308     return outputMat;
309 }
310 /*参数更新*/
311 void CNN::paramUpdate(
312     int batchSize,
313     std::vector<std::vector<uint8_t>>& featureMat,
314     std::vector<uint8_t>& labelMat,
315     std::vector<std::vector<uint8_t>>& labelMatZ0,
316     std::vector<std::vector<double>>& filterMat,
317     std::vector<double>& convBias,
318     std::vector<std::vector<std::vector<double>>>& outputWeight,
319     std::vector<double>& outputBias)
320 {
321     int numPerBatch = numPic / batchSize;

```

```

322     double predLabel = 0;
323     uint8_t trueLabel = 0;
324
325     for (int i = 0; i < batchSize - 11; i++)
326     {
327         lossMat.clear();
328         double EntropyLoss = 0;
329         std::vector<std::vector<std::vector<double>>> deltaWeightOutput;
330         std::vector<double> deltaBiasOutput;
331         std::vector<std::vector<double>> deltaWeightFilter;
332         std::vector<double> deltaBiasFilter;
333         //输出层参数更新值初始化
334         for (int ii = 0; ii < numLabel; ii++)
335         {
336             std::vector<std::vector<double>> vec1;
337             for (int jj = 0; jj < numFilter; jj++)
338             {
339                 std::vector<double> vec2;
340                 for (int kk = 0; kk < poolMatSize; kk++)
341                 {
342                     vec2.push_back(0);
343                 }
344                 vec1.push_back(vec2);
345             }
346             deltaWeightOutput.push_back(vec1);
347             deltaBiasOutput.push_back(0);
348         }
349         //卷积层参数更新值初始化
350         for (int qq = 0; qq < numFilter; qq++)
351         {
352             std::vector<double> vec3;
353             for (int dd = 0; dd < filterSize; dd++)
354             {
355                 vec3.push_back(0);
356             }
357             deltaWeightFilter.push_back(vec3);
358             deltaBiasFilter.push_back(0);
359         }
360         //开始训练
361         for (int j = 0; j < numPerBatch / 100; j++)
362         {
363             //forward
364             std::vector<std::vector<double>> convMat =
convLayer(featureMat, filterMat, convBias, i * numPerBatch + j);
365             std::vector<std::vector<double>> activatedMat =
convActivate(convMat);
366             std::vector<std::vector<double>> poolingMat =
poolingLayer(activatedMat);

```

```

367         std::vector<double>          outputMat =
outputLayer(poolingMat, outputWeight, outputBias);
368         std::vector<double>          softmaxed =
softmax(outputMat);
369         /*
370         std::cout << "convMat" << std::endl;
371         for (auto it = convMat.begin(); it != convMat.end(); it++)
372         {
373             for (auto i = (*it).begin(); i != (*it).end(); i++)
374             {
375                 std::cout << *i << " ";
376             }
377             std::cout << std::endl;
378         }
379         std::cout << "activatedMat" << std::endl;
380         for (auto it = activatedMat.begin(); it !=
activatedMat.end(); it++)
381         {
382             for (auto i = (*it).begin(); i != (*it).end(); i++)
383             {
384                 std::cout << *i << " ";
385             }
386             std::cout << std::endl;
387         }
388         exit(-1);
389         */
390
391         //输出层参数更新
392         double Mediator = 1 / (softmaxMediator * softmaxMediator) *
(-1) * 1 / double(numPerBatch);
393         for (int k = 0; k < numLabel; k++)
394         {
395             double output = outputMat[k];
396             double softmaxValue = softmaxed[k];
397             double backBar = 0;
398             for (int d = 0; d < numLabel; d++)
399             {
400
401                 if (d == k)
402                 {
403                     backBar += labelMatZ0[i * numPerBatch + j][d] *
(softmaxMediator - std::exp(output)) / softmaxed[d];
404                 }
405                 else
406                 {
407                     backBar += (-1) * labelMatZ0[i * numPerBatch +
j][d] * std::exp(outputMat[d]) / softmaxed[d];
408                 }

```

```

409         }
410         for (int p = 0; p < numFilter; p++)
411         {
412             for (int q = 0; q < poolMatSize; q++)
413             {
414                 double delW = Mediator * poolingMat[p][q] *
std::exp(output) * backBar;
415                 deltaWeightOutput[k][p][q] += delW;
416             }
417         }
418         double delB = Mediator * std::exp(output) * backBar;
419         deltaBiasOutput[k] += delB;
420     }
421     //filter权重及bias更新
422     std::vector<double> filterBackBarVec;
423     double filterBackBarMed = softmaxMediator * softmaxMediator
* (-1) * 1 / double(numPerBatch);
424     for (int a1 = 0; a1 < numLabel; a1++)
425     {
426         double filterBackBar = 0;
427         for (int a2 = 0; a2 < numLabel; a2++)
428         {
429             if (a2 == a1)
430             {
431                 filterBackBar += labelMatZ0[i * numPerBatch + j]
[a2] * (softmaxMediator - std::exp(outputMat[a1])) *
std::exp(outputMat[a1]) / softmaxed[a2];
432             }
433             else
434             {
435                 filterBackBar += (-1) * labelMatZ0[i *
numPerBatch + j][a2] * std::exp(outputMat[a2]) * std::exp(outputMat[a1])
/ softmaxed[a2];
436             }
437         }
438         filterBackBar = (1 / filterBackBarMed) * filterBackBar;
439         filterBackBarVec.push_back(filterBackBar);
440     }
441
442     //卷积层的元素对filter的权重参数的求导
443     std::vector<std::vector<double>> filToPixMat;
444     for (int fw = 0; fw < filterSize; fw++)
445     {
446         std::vector<double> filToPixArray;
447         for (int ele = 0; ele < convEleNum; ele++)
448         {
449             int index = (fw / filterRow) * numRowsPixel +
(filterRow - 1) * (ele / convMatColNum) + ele + (fw + filterRow) %

```

```

filterRow;
450         filToPixArray.push_back(featureMat[i * numPerBatch +
j][index]);
451     }
452     filToPixMat.push_back(filToPixArray);
453 }
454
455     for (int a3 = 0; a3 < numFilter; a3++)
456     {
457         //权重更新
458         for (int a4 = 0; a4 < filterSize; a4++)
459         {
460             //激活函数对filter权重的求导
461             std::vector<double> actTowMat;
462             for (int actw = 0; actw < convEleNum; actw++)
463             {
464                 double actwV = 0;
465                 if (actiType == 0)
466                 {
467                     actwV = activatedMat[a3][actw] * (1 -
activatedMat[a3][actw]) * filToPixMat[a4][actw];
468                 }
469                 else if (actiType == 1)
470                 {
471                     if (activatedMat[a3][actw] != 0)
472                     {
473                         actwV = 1 * filToPixMat[a4][actw];
474                     }
475                     else
476                     {
477                         actwV = 0;
478                     }
479                 }
480             }
481             actTowMat.push_back(actwV);
482         }
483         //池化矩阵对filter权重的求导
484         std::vector<double> poolTow;
485         for (int poolindex = 0; poolindex < poolMatSize;
poolindex++)
486         {
487             double poolTowV = 0;
488             std::vector<double> poolCmp;
489             std::vector<int> poolCmpIndex;
490             for (int poolstr = 0; poolstr < 2 * poolStride;
poolstr++)
491             {

```

```

492         int cuteIndex = (poolindex / poolMatColNum)
* (2 * poolMatColNum) + (poolStride * poolindex) +
493         (2 * poolMatColNum) * (poolstr /
poolStride) + (poolstr + poolStride) % poolStride;
494         poolCmpIndex.push_back(cuteIndex);
495         poolCmp.push_back(activatedMat[a3]
[cuteIndex]);
496     }
497     for (int poolcmpI = 0; poolcmpI < 2 *
poolStride; poolcmpI++)
498     {
499         if (poolCmp[poolcmpI] == poolingMat[a3]
[poolindex])
500         {
501             poolTowV = 1 *
actTowMat[poolCmpIndex[poolcmpI]];
502             poolTow.push_back(poolTowV);
503         }
504         else
505         {
506             poolTow.push_back(0);
507         }
508     }
509 }
510 double filterWeightUpdate = 0;
511 for (int a5 = 0; a5 < numLabel; a5++)
512 {
513     double filterForeBarW = 0;
514     for (int a6 = 0; a6 < poolMatSize; a6++)
515     {
516         filterForeBarW += outputWeight[a5][a3][a6] *
poolTow[a6];
517     }
518     filterWeightUpdate += filterForeBarW *
filterBackBarVec[a5];
519 }
520 }
521 deltaWeightFilter[a3][a4] += filterWeightUpdate;
522 }
523 //bias更新
524 std::vector<double> actTobMat;
525 for (int actb = 0; actb < convEleNum; actb++)
526 {
527     double actbV=0;
528     if (actiType == 0)
529     {

```



```

532         actbV = activatedMat[a3][actb] * (1 -
activatedMat[a3][actb]);
533     }
534     else if (actiType == 1)
535     {
536         if (activatedMat[a3][actb] != 0)
537         {
538             actbV = 1;
539         }
540         else
541         {
542             actbV = 0;
543         }
544     }
545     actTobMat.push_back(actbV);
546 }
547 std::vector<double> poolTob;
548 for (int poolindex = 0; poolindex < poolMatSize;
poolindex++)
549 {
550     double poolTobV = 0;
551     std::vector<double> poolCmp;
552     std::vector<int> poolCmpIndex;
553     for (int poolstr = 0; poolstr < 2 * poolStride;
poolstr++)
554     {
555         int cuteIndex = (poolindex / poolMatColNum) * (2
* poolMatColNum) + (poolStride * poolindex) +
556             (2 * poolMatColNum) * (poolstr / poolStride)
+ (poolstr + poolStride) % poolStride;
557         poolCmpIndex.push_back(cuteIndex);
558         poolCmp.push_back(activatedMat[a3][cuteIndex]);
559     }
560     for (int poolcmpI = 0; poolcmpI < 2 * poolStride;
poolcmpI++)
561     {
562         if (poolCmp[poolcmpI] == poolingMat[a3]
[poolindex])
563         {
564             poolTobV = 1 *
actTobMat[poolCmpIndex[poolcmpI]];
565             poolTob.push_back(poolTobV);
566         }
567         else
568         {
569             poolTob.push_back(0);
570         }
571     }

```

```

572         }
573     }
574     double filterBiasUpdate = 0;
575     for (int a5 = 0; a5 < numLabel; a5++)
576     {
577         double filterForeBarB = 0;
578         for (int a6 = 0; a6 < poolMatSize; a6++)
579         {
580             filterForeBarB += outputWeight[a5][a3][a6] *

```

2.结果描述

今天主要还是优化了CNN的代码，发现了几个比较不显眼的问题。但还是很容易出现NAN的问题。查了下大概有几种情况，其中前三种主要跟梯度爆炸有关：

- 1.参数初始化问题
- 2.网络结构设计
- 3.激活函数的选择
- 4.出现分母为零的情况

针对参数初始化的问题，目前用的比较多的Xavier初始化，为此参考了一些生成服从正态分布随机数的代码，并加入到CNN类中。虽然感觉通过调节正态分布的方差可以取得一定效果，但实测下来还是经常出现NAN的问题。网络结构设计这块感觉应该不是主要问题，毕竟这只是一个最基本的卷积神经网络，比起那些好几百层的网络还差得远。激活函数的不同所带来的影响目前还不是很清楚，虽然Relu用的比sigmoid多，但在加入代码后并没有带来什么改善，反而出现了loss inf的情况，也没收敛过哪怕一次。至于分母为零的情况，在实测中确实出现过，比如最后softmax的输出。但从softmax的公式出发，按理说不应出现为零的情况，具体是为什么目前也没搞懂。

此外，还有几个比较让人摸不着头脑的现象。在某些学习率下，几轮学习的loss会一直保持一样，说明参数没有更新；测试数据经常出现只识别某个特定数字的情况，除了该数字以外的其它数字都没能成功识别，也挺tricky的。明天再想办法优化一轮，包括加入其它激活函数、进行批初始化等。之后学习一下下一个youtuber写的C++ deep learning的代码。

此外，在写参数更新部分代码的时候感觉选择了一种最蠢的方式，即把链式求导的过程一个个展开。虽然思路没错，但总感觉没有应用到之前读的日本作者写的深度学习的书里提到的两个关键的求导中间量。后续也得好好再复习一下。

在完成基本的CNN类的编写之后，之后有三块想主要学习的：

- 计算机网络（看完书之后已经很久没复习了，这可是以后的饭碗
- C++软件开发（主要是带界面的。之前学习过一点点QT，但感觉挺枯燥的。还是得学起来
- C++机器学习（想把主要得机器学习算法都实现一遍，但感觉不一定有足够的时间。毕竟七八月份就要入职当社畜了，在那之前还想pick一些其它的技能，包括吉他 德语等等。机器学习是一个大大的坑，真要学到一点皮毛确实没那么简单，不应该有太多不切实际的幻想，比如吃透每种算法的内在数学逻辑。这次简单的CNN实现就已经花了快一周的时间，其它的估计也大差不差。如果只是简

单的使用，用python的很多工具包应该足够应付（这也需要对算法有足够的熟悉度），但这确实不够cool。

- 数据结构与算法（这部分之前学的毫无章法，也没能坚持把书跟视频看完，基础还十分薄弱
- C++高级编程（在编写CNN类的过程，明显感觉到自己的C++水平停留在一个很低的程度，写来写去都是vector跟for循环，像指针、map、模板、多态等基本没有使用，这其实会让自己的程序编写水平一直被锁死在一个low level的水准。虽然目前而言好像还勉强够用，但已经面临到代码低水平重复的情况。理应用一种更合理、更简洁的方式进行表示