MAT1110 - Mandatory assignment 2

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1

 \mathbf{a}

We have

$$\mathbf{F}(x,y) = -\frac{y}{2}\mathbf{i} + \frac{x}{2}\mathbf{j} \tag{1}$$

and the parameterization r of C oriented clockwise. If follows that r is piecewise smooth as C is piecewise smooth. Since C encloses an area including R, and the partial derivatives of F are continuous, we can use Greens' theorem two write the area enclosed by C as

$$\iint_{R} \left| \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA \right| = \oint_{C} |\mathbf{F} \cdot d\mathbf{r}|$$

where we take the absolute value since Green's theorem uses a counter-clockwise parameterization.

b

Since C_k is the line piece connecting the points (a_k, b_k) and (a_{k+1}, b_{k+1}) can we write $\Delta x = a_{k+1} - a_k$ and $\Delta y = b_{k+1} - b_k$ from the point (a_k, b_k) . The change will be linear as C_k are straight lines. If we put all this together, we get the parameterization

$$\mathbf{r}_k(t) = (a_k + t(a_{k+1} - a_k)), b_k + t(b_{k+1} - b_k), \qquad t \in [0, 1]$$

 \mathbf{c}

$$A_k = \int_{C_k} x dy \tag{3}$$

If we use $x = a_k + t(a_{k+1} - a_k)$ and $dy = (b_{k+1} - b_k)dt$ we get

$$A_k = (b_{k+1} - b_k) \int_0^1 (a_k + t(a_{k+1} - a_k)) dt$$
$$= (b_{k+1} - b_k) \left[ta_k + \frac{1}{2} t^2 (a_{k+1} - a_k) \right]_0^1$$
$$= \frac{1}{2} (a_{k+1} + a_k) (b_{k+1} - b_k)$$

If we sum over all line-pieces we get

$$A = \frac{1}{2} \sum_{k=1}^{n} (a_{k+1} + a_k)(b_{k+1} - b_k)$$
(4)

 \mathbf{d}

We will now calculate the area of a triangle with corners (0,0),(a,h) and (g,0) using equation 4.

$$A_{\text{triangle}} = \frac{1}{2}[(g-0)(0-0) + (a+g)(h-0) + (0+a)(0-h)]$$

$$= \frac{1}{2}[ah + gh - ah]$$

$$= \frac{gh}{2}$$

For a rectangle with corners (0,0),(g,0),(g,h) and (0,h) we get

$$A_{\text{rectangle}} = \frac{1}{2} [(g+0)(0-0) + (g+g)(h-0) + (0+g)(h-h) + (0+0)(0-h)]$$

$$= \frac{1}{2} [2gh]$$

$$= gh.$$

 $\mathbf{2}$

a

We let

$$A = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{pmatrix}$$
 (5)

and (x, y, z) be a point on the unit shpere. In other words, $x^2 + y^2 + z^2 = 1$. We introduce the variable

$$u = A \begin{pmatrix} x \\ y \\ z \end{pmatrix}.$$

To show that u is a point on the unit shpere, we need |u| = 1.

$$\begin{aligned} |\boldsymbol{u}| &= \left(\frac{x}{\sqrt{3}} + \frac{y}{\sqrt{2}} + \frac{z}{\sqrt{6}}\right)^2 + \left(-\frac{x}{\sqrt{3}} + \frac{y}{\sqrt{2}} - \frac{z}{\sqrt{6}}\right)^2 + \left(\frac{x}{\sqrt{3}} + \frac{z}{\sqrt{6}}\right)^2 \\ &= \frac{x^2}{3} + \frac{y^2}{2} + \frac{z^2}{6} + \frac{x^2}{3} + \frac{y^2}{2} + \frac{z^2}{6} + \frac{x^2}{3} + \frac{4z^2}{6} \quad \text{(Canceling like terms)} \\ &= x^2 + y^2 + z^2 \\ &= 1 \end{aligned}$$

b

We let

$$B = \begin{pmatrix} \frac{1}{6} & -\frac{1}{6} & 0\\ -\frac{1}{6} & \frac{1}{2} & \frac{2}{3}\\ 0 & \frac{1}{6} & -\frac{1}{6} \end{pmatrix}$$
 (6)

and

$$\mathbf{F} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = B \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}. \tag{7}$$

We define $\{v_n\}$ such that $v_{n+1} = F(v_n)$ and $\lim_{x\to\infty} v_n = v$.

$$F(v) = \lim_{n \to \infty} F(v_n) = \lim_{n \to \infty} v_n = v$$

Since $\{v_n\}$ converges towards v, v is a fixpoint for F.

Since $\{F(x_n)\}$ converges for all x_0 , we start with the zero vector for convenience.

```
1 import numpy as np
   def F(v):
3
       B = np.asarray([
            [1/6, -1/6, 0],
[-1/6, 1/2, 2/3],
5
 6
            [0, 1/6, -1/6]
 7
       ])
8
       return np.einsum('ij, j -> i', B, v) + (1, 0, 1)
10
  def fixpoint(F):
11
       i = 0

x = (0, 0, 0)
12
13
       while np.sum(F(x)-x) > 10e-8:
    x = F(x)
14
15
            i += 1
16
       print(f'Fixpoint: {x}, n = {i}')
18
       return x, i
19
20
21 fixpoint(F)
22
  ....
23
24 Fixpoint: [1.0000001 0.9999997 0.99999994], n = 40
```

The program shows that the vector (1,1,1) is a fixpoint for F.

3

We define $f: \mathbb{R}^2 \to \mathbb{R}^2$ where $f(\boldsymbol{v}) = A\boldsymbol{v} + \boldsymbol{b}$.

a

We let f be an isometry in the xy-plane. It is easy to show that f preserves norms:

$$|\mathbf{v} - \mathbf{w}| = |f(\mathbf{v}) - f(\mathbf{w})|$$

$$= |A\mathbf{v} + \mathbf{b} - (A\mathbf{w} + \mathbf{b})|$$

$$= |A\mathbf{v} - A\mathbf{w}|$$

$$\leq |A| \cdot |\mathbf{v} - \mathbf{w}|$$

$$= |\mathbf{v} - \mathbf{w}|$$

where we have used that $det(A) = \pm 1$.

b

We let $f(\mathbf{v}) = A\mathbf{v} + \mathbf{b}$ be an isometry with $\det(A) = -1$. The vector $A\mathbf{b} + \mathbf{b}$ is an eigenvector if $(A - I)(A\mathbf{b} + \mathbf{b}) = 0$ for all choises of \mathbf{b} . Remembering that $A^2 = I$, we get

$$(A-I)(A\mathbf{b}+\mathbf{b}) = A^2\mathbf{b} + A\mathbf{b} - AI\mathbf{b} - I\mathbf{b} = 0$$

which shows that $A\mathbf{b} + \mathbf{b}$ is an eigenvector.

 \mathbf{c}

The transformation by f on the line perpendicular to \boldsymbol{w} is

$$f(s\boldsymbol{w}) = sA\boldsymbol{w} + \boldsymbol{b}, \qquad s \in \mathbb{R}$$

Since w is an eigenvector $Aw = \lambda w$. Remembering that $\lambda = 1$, we can then scale the transformation down by a half, and get

$$t\boldsymbol{w} + \frac{1}{2}\boldsymbol{b}, \qquad t \in \mathbb{R}$$
 (8)

where we let t = s/2. This shows that f transforms the line in eq 8 on itself.