

# MAT1110 - Mandatory assignment 2

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**1**

**a**

We have

$$\mathbf{F}(x, y) = -\frac{y}{2}\mathbf{i} + \frac{x}{2}\mathbf{j} \quad (1)$$

and the parameterization  $\mathbf{r}$  of  $C$  oriented counter-clockwise. It follows that  $\mathbf{r}$  is piecewise smooth as  $C$  is piecewise smooth. Since  $C$  encloses an area including  $R$ , and the partial derivatives of  $\mathbf{F}$  are continuous, we can use Greens' theorem to write the area enclosed by  $C$  as

$$\iint_R \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \oint_C \mathbf{F} \cdot d\mathbf{r}$$

**b**

Since  $C_k$  is the line piece connecting the points  $(a_k, b_k)$  and  $(a_{k+1}, b_{k+1})$  we can write  $\Delta x = a_{k+1} - a_k$  and  $\Delta y = b_{k+1} - b_k$  from the point  $(a_k, b_k)$ . The change will be linear as  $C_k$  are straight lines. If we put all this together, we get the parameterization

$$\mathbf{r}_k(t) = (a_k + t(a_{k+1} - a_k), b_k + t(b_{k+1} - b_k)), \quad t \in [0, 1] \quad (2)$$

**c**

$$A_k = \int_{C_k} x dy \quad (3)$$

If we use  $x = a_k + t(a_{k+1} - a_k)$  and  $dy = (b_{k+1} - b_k)dt$  we get

$$\begin{aligned} A_k &= (b_{k+1} - b_k) \int_0^1 (a_k + t(a_{k+1} - a_k)) dt \\ &= (b_{k+1} - b_k) \left[ ta_k + \frac{1}{2}t^2(a_{k+1} - a_k) \right]_0^1 \\ &= \frac{1}{2}(a_{k+1} + a_k)(b_{k+1} - b_k) \end{aligned}$$

If we sum over all line-pieces we get

$$A = \frac{1}{2} \sum_{k=1}^{n-1} (a_{k+1} + a_k)(b_{k+1} - b_k) \quad (4)$$

**d**

We will now calculate the area of a triangle with corners  $(0, 0)$ ,  $(a, h)$  and  $(g, 0)$  using equation 4.

$$\begin{aligned} A_{\text{triangle}} &= \frac{1}{2} [(g - 0)(0 - 0) + (a + g)(h - 0) + (0 + a)(0 - h)] \\ &= \frac{1}{2} [ah + gh - ah] \\ &= \frac{gh}{2} \end{aligned}$$

For a rectangle with corners  $(0, 0)$ ,  $(g, 0)$ ,  $(g, h)$  and  $(0, h)$  we get

$$\begin{aligned} A_{\text{rectangle}} &= \frac{1}{2} [(g + 0)(0 - 0) + (g + g)(h - 0) + (0 + g)(h - h) + (0 + 0)(0 - h)] \\ &= \frac{1}{2} [2gh] \\ &= gh. \end{aligned}$$

## 2

### a

We let

$$A = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & -\frac{2}{\sqrt{6}} \end{pmatrix} \quad (5)$$

and  $(x, y, z)$  be a point on the unit sphere. In other words,  $x^2 + y^2 + z^2 = 1$ . We introduce the variable

$$\mathbf{u} = A \begin{pmatrix} x \\ y \\ z \end{pmatrix}.$$

To show that  $\mathbf{u}$  is a point on the unit sphere, we need  $|\mathbf{u}| = 1$ .

$$\begin{aligned} |\mathbf{u}| &= \left( \frac{x}{\sqrt{3}} + \frac{y}{\sqrt{2}} + \frac{z}{\sqrt{6}} \right)^2 + \left( -\frac{x}{\sqrt{3}} + \frac{y}{\sqrt{2}} - \frac{z}{\sqrt{6}} \right)^2 + \left( \frac{x}{\sqrt{3}} + \frac{z}{\sqrt{6}} \right)^2 \\ &= \frac{x^2}{3} + \frac{y^2}{2} + \frac{z^2}{6} + \frac{x^2}{3} + \frac{y^2}{2} + \frac{z^2}{6} + \frac{x^2}{3} + \frac{4z^2}{6} \quad (\text{Canceling like terms}) \\ &= x^2 + y^2 + z^2 \\ &= 1 \end{aligned}$$

### b

We let

$$B = \begin{pmatrix} \frac{1}{6} & -\frac{1}{6} & 0 \\ -\frac{1}{6} & \frac{1}{2} & \frac{2}{3} \\ 0 & \frac{1}{6} & -\frac{1}{6} \end{pmatrix} \quad (6)$$

and

$$\mathbf{F} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = B \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}. \quad (7)$$

We define  $\{\mathbf{v}_n\}$  such that  $\mathbf{v}_{n+1} = \mathbf{F}(\mathbf{v}_n)$  and  $\lim_{n \rightarrow \infty} \mathbf{v}_n = \mathbf{v}$ .

$$\mathbf{F}(\mathbf{v}) = \lim_{n \rightarrow \infty} \mathbf{F}(\mathbf{v}_n) = \lim_{n \rightarrow \infty} \mathbf{v}_n = \mathbf{v}$$

Since  $\{\mathbf{v}_n\}$  converges towards  $\mathbf{v}$ ,  $\mathbf{v}$  is a fixpoint for  $\mathbf{F}$ .

**C**

Since  $\{F(x_n)\}$  converges for all  $x_0$ , we start with the zero vector for convenience.

```
1 import numpy as np
2
3 def F(v):
4     B = np.asarray([
5         [1/6, -1/6, 0],
6         [-1/6, 1/2, 2/3],
7         [0, 1/6, -1/6]
8     ])
9     return np.einsum('ij, j -> i', B, v) + (1, 0, 1)
10
11 def fixpoint(F):
12     i = 0
13     x = (0, 0, 0)
14     while np.sum(F(x)-x) > 10e-8:
15         x = F(x)
16         i += 1
17
18     print(f'Fixpoint: {x}, n = {i}')
19     return x, i
20
21 fixpoint(F)
22
23 """
24 Fixpoint: [1.0000001  0.9999997  0.99999994], n = 40
25 """
```

The program shows that the vector  $(1, 1, 1)$  is a fixpoint for  $F$ .

### 3

We define  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  where  $f(\mathbf{v}) = A\mathbf{v} + \mathbf{b}$ .

#### a

We let  $f$  be an isometry in the xy-plane. It is easy to show that  $f$  preserves norms:

$$\begin{aligned} |\mathbf{v} - \mathbf{w}| &= |f(\mathbf{v}) - f(\mathbf{w})| \\ &= |A\mathbf{v} + \mathbf{b} - (A\mathbf{w} + \mathbf{b})| \\ &= |A\mathbf{v} - A\mathbf{w}| \\ &\leq |A| \cdot |\mathbf{v} - \mathbf{w}| \\ &= |\mathbf{v} - \mathbf{w}| \end{aligned}$$

where we have used that  $\det(A) = \pm 1$ .

#### b

We let  $f(\mathbf{v}) = A\mathbf{v} + \mathbf{b}$  be an isometry with  $\det(A) = -1$ . The vector  $A\mathbf{b} + \mathbf{b}$  is an eigenvector if  $(A - I)(A\mathbf{b} + \mathbf{b}) = 0$  for all choices of  $\mathbf{b}$ . Remembering that  $A^2 = I$ , we get

$$(A - I)(A\mathbf{b} + \mathbf{b}) = A^2\mathbf{b} + A\mathbf{b} - A\mathbf{b} - \mathbf{b} = 0$$

which shows that  $A\mathbf{b} + \mathbf{b}$  is an eigenvector.

#### c

The transformation by  $f$  on the line perpendicular to  $\mathbf{w}$  is

$$f(s\mathbf{w}) = sA\mathbf{w} + \mathbf{b}, \quad s \in \mathbb{R}$$

Since  $\mathbf{w}$  is an eigenvector  $A\mathbf{w} = \lambda\mathbf{w}$ . Remembering that  $\lambda = -1$ , we can then scale the transformation down by a half, and get

$$t\mathbf{w} + \frac{1}{2}\mathbf{b}, \quad t \in \mathbb{R} \tag{8}$$

where we let  $t = s/2$ . This shows that  $f$  transforms the line in eq 8 on itself.