micro:bit TPS

This is my implementation of the TPS. The instructions will be compatible to my ArduinoSPS Version. And you will get some nice new Commands, implementing some of the micro:bit features, like images, Soundlevel, Logo...

If you find a bug, feel free to create a issue in the tracker.

Command implementation Chart

The actual command implementation list for the micro:bit V2:

| | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|---|---|----------------|-----------------|---------------------------------|--------------|---------------------|-----------------|-----------------------------|
| | n.n. | Port [DOUT] | Delay [WAIT] | Jump back relative [RJMP] | A=# [LDA] | =A | A= | A=Ausdruck |
| 0 | NOP [NOP] | aus | 1ms | 0 | 0 | A<->B [SWAP] | | |
| 1 | SetPixel(X,Y) X=A, Y=B | 1 | 2ms | 1 | 1 | B=A [MOV] | A=B [MOV] | A=A + 1 [INC] |
| 2 | ClearPixel(X,Y) X=A, Y=B | 2 | 5ms | 2 | 2 | C=A [MOV] | A=C [MOV] | A=A - 1 [DEC] |
| 3 | 0: ClearDisplay 163: show(Image) | 3 | 10ms | 3 | 3 | D=A [MOV] | A=D [MOV] | A=A + B [ADD] |
| 4 | | 4 | 20ms | 4 | 4 | Dout=A [STA] | Din [LDA] | A=A - B [SUB] |
| 5 | | 5 | 50ms | 5 | 5 | Dout.1=A.1 [STA] | Din.1 [LDA] | A=A * B [MUL] |
| 6 | | 6 | 100ms | 6 | 6 | Dout.2=A.1 [STA] | Din.2 [LDA] | A=A / B [DIV] |
| 7 | | 7 | 200ms | 7 | 7 | Dout.3=A.1 [STA] | Din.3 [LDA] | A=A and B [AND] |
| 8 | | 8 | 500ms | 8 | 8 | Dout.4=A.1 [STA] | Din.4 [LDA] | A=A or B [OR] |
| 9 | | 9 | 1s | 9 | 9 | PWM.1=A [STA] | ADC.1 [LDA] | A=A xor B [XOR] |
| а | | 10 | 2s | 10 | 10 | PWM.2=A [STA] | ADC.2 [LDA] | A= not A [NOT] |
| b | | 11 | 5s | 11 | 11 | Servo.1=A [STA] | RCin.1 [LDA] | A= A % B (Rest) [MOD] |
| С | | 12 | 10s | 12 | 12 | Servo.2=A [STA] | RCin.2 [LDA] | A= A + 16 * B [BYTE] |
| d | | 13 | 20s | 13 | 13 | E=A [MOV] | A=E [MOV] | A= B - A[BSUBA] |
| е | | 14 | 30s | 14 | 14 | F=A [MOV] | A=F [MOV] | A=A SHR 1 [SHR] |
| f | | 15 | 60s | 15 | 15 | Push A [PUSH] | Pop A [POP] | A=A SHL 1 [SHL] |

new commands for the micro:bit

SetPixel: sets a pixel directly with x,y coordinates. X=A Y=B

ClearPixel: clears a pixel

ShowImage(image): if image is set to 0, the display is cleared, otherwise it will set a nice image on the display.

| | 8 | 9 | а | b | С | d | е | f |
|---|----------------|---|---|--|-----------------------|---------------------------------|-------------------|--|
| | Page [PAGE] | Jump absolut (#+16*page) [JMP] | C* C>0: C=C- 1; Jump # + (16*page) [LOOPC] | D* D>0:D=D-1; Jump # + (16*page) [LOOPC] | Skip if | Call # + (16*Page) [Call] | Callsub/Ret | Byte Befehle |
| 0 | 0 | 0 | 0 | 0 | A==0 [SKIP0] | 0 | ret [RTR] | A=ADC.1 [BLDA] |
| 1 | 1 | 1 | 1 | 1 | A>B [AGTB] | 1 | Call 1 [CASB] | A=ADC.2 [BLDA] |
| 2 | 2 | 2 | 2 | 2 | A <b [ALTB]</b | 2 | 2 [CASB] | A=RCin.1 [BLDA] |
| 3 | 3 | 3 | 3 | 3 | A==B [AEQB] | 3 | 3 [CASB] | A=RCin.2 [BLDA] |
| 4 | 4 | 4 | 4 | 4 | Din.1==1 [DEQ1 1] | 4 | 4 [CASB] | PWM.1=A [BSTA] |
| 5 | 5 | 5 | 5 | 5 | Din.2==1 [DEQ1 2] | 5 | 5 [CASB] | PWM.2=A [BSTA] |
| 6 | 6 | 6 | 6 | 6 | Din.3==1 [DEQ1 3] | 6 | 6 [CASB] | Servo.1=A [BSTA] |
| 7 | 7 | 7 | 7 | 7 | Din.4==1 [DEQ1 4] | 7 | | Servo.2=A [BSTA] |
| 8 | 8 | 8 | 8 | 8 | Din.1==0 [DEQ0 1] | 8 | Def 1 [DFSB] | Tone=A [TONE] |
| 9 | 9 | 9 | 9 | 9 | Din.2==0 [DEQ0 2] | 9 | 2 [DFSB] | GetACC a=acc.x, E=acc.y, F=acc.z |
| a | 10 | 10 | 10 | 10 | Din.3==0 [DEQ0 3] | 10 | 3 [DFSB] | A= Compass (in 5°) |
| b | 11 | 11 | 11 | 11 | Din.4==0 [DEQ0 4] | 11 | 4 [DFSB] | A=SoundLevel() |
| С | 12 | 12 | 12 | 12 | S_PRG==0 [PRG0] | 12 | 5 [DFSB] | A=LightLevel (0255) |
| d | 13 | 13 | 13 | 13 | S_SEL==0 [SEL0] | 13 | 6 [DFSB] | A=LogoTouched |
| е | 14 | 14 | 14 | 14 | S_PRG==1 [PRG1] | 14 | | A=Gesture() |
| f | 15 | 15 | 15 | 15 | S_SEL==1 [SEL1] | 15 | restart [REST] | PrgEnd [PEND] |

new commands for the micro:bit

GetACC: get values from the accelerator, A will be the x-axis, E the y-axis, and F the z-axis all Values range form 0..255

Compass: get the value of the compass, the value is in 5° Steps, so $0 = 0^{\circ} 1 = 5^{\circ}$, $2=10^{\circ}$...

SoundLevel: level of the microfon

LightLevel: level of the ambiant light

Gesture: is the gesture you where making with the micro:bit. The following gestures will be detected:

| No. | Gesture | No. | Gesture |
|-----|--------------|-----|-----------|
| 0 | nothing | 6 | face down |
| 1 | moving up | 7 | freefall |
| 2 | moving down | 8 | 3g |
| 3 | moving left | 9 | 6g |
| 4 | moving right | 10 | 8g |
| 5 | face up | 11 | shake |

LogoTouched: the logo is touched.

Hardware assignments:

Caution: Due to the dual assignment of pins (especially the two A / D converters) can cause effects on the circuit in both directions. Protective diodes may be required there.

Button A is PRG or S1 (pin 5) Button B is SEL or S2 (pin 11)

servo pins: Servo 1: pin 8, Servo 2: pin 9

ppm pins: not implemented yet

Micro:bit pin mapping table

| pin number | micro:bit function | TPS function |
|------------|--------------------|--------------|
| 0 | a/d | DOut.1 |
| 1 | a/d | DOut.2 |
| 2 | a/d | DOut.3 |
| 3 | LED Col 3 a/d | A/D 1 |
| 4 | LED Col 1 a/d | A/D 2 |
| 5 | Button A | PRG/S1 |
| 6 | LED Col 4 | unusable |
| 7 | LED Col 2 | unusable |
| 8 | | D/A 1 |
| 9 | | D/A 2 |
| 10 | LED Col 5 a/d | unusable |
| 11 | Button B | SEL/S2 |
| 12 | reserved | DOut.4 |
| 13 | | Dln.1 |
| 14 | | DIn.2 |
| 15 | | Dln.3 |
| 16 | | DIn.4 |
| 19 | I2C | unusable |
| 20 | I2C | unusable |

Debug mode

This micro: bit TPS version supports debug and single step mode. In debug mode, additional information is made available on the serial interface while the program is being executed. A terminal program (such as hterm: https://www.der-hammer.info/pages/terminal.html) is required for this. Settings: 115200 baud 8N1.

```
PC: 0000
INST: 1, DATA: 1
Register:
A: 00, B: 00, C: 00
D: 00, E: 00, F: 00
Page: 00, Ret: 0000
```

PC is the program counter. INST and DATA are the nibbles of the command. The current status of the registers is shown under Register. PAGE is the page register and RET contains the return address for a subroutine call (via command 0xD #).

While the single step mode can only be set via source code, the pure debug mode can be started by touching the logo during a reset.

Apendix

Image List:

Here is the image list:

- 1: Image.HEART,
- 2: Image.HAPPY,
- 3: Image.SMILE,
- 4: Image.SAD,
- 5: Image.CONFUSED,
- 6: Image.ANGRY,
- 7: Image.ASLEEP,
- 8: Image.SURPRISED,
- 9: Image.SILLY,
- 10: Image.FABULOUS,
- 11: Image.MEH,
- 12: Image.YES,
- 13: Image.NO,
- 14: Image.CLOCK1,
- 15: Image.CLOCK2,
- 16: Image.CLOCK3,
- 17: Image.CLOCK4,
- 18: Image.CLOCK5,
- 19: Image.CLOCK6,
- 20: Image.CLOCK7,
- 21: Image.CLOCK8,
- 22: Image.CLOCK9,
- 23: Image.CLOCK10,
- 24: Image.CLOCK11,
- 25: Image.CLOCK12,
- 26: Image.ARROW_N,
- 27: Image.ARROW_NE,
- 28: Image.ARROW_E,
- 29: Image.ARROW_SE,
- 30: Image.ARROW_S,
- 31: Image.ARROW_SW,
- 32: Image.ARROW_W,
- 33: Image.ARROW_NW,
- 34: Image.TRIANGLE,
- 35: Image.TRIANGLE_LEFT,
- 36: Image.CHESSBOARD,
- 37: Image.DIAMOND,
- 38: Image.DIAMOND_SMALL,
- 39: Image.SQUARE,
- 40: Image.SQUARE_SMALL,
- 41: Image.RABBIT,

- 42: Image.COW,
- 43: Image.MUSIC_CROTCHET,
- 44: Image.MUSIC_QUAVER,
- 45: Image.MUSIC_QUAVERS,
- 46: Image.PITCHFORK,
- 47: Image.XMAS,
- 48: Image.PACMAN,
- 49: Image.TARGET,
- 50: Image.TSHIRT,
- 51: Image.ROLLERSKATE,
- 52: Image.DUCK,
- 53: Image.HOUSE,
- 54: Image.TORTOISE,
- 55: Image.BUTTERFLY,
- 56: Image.STICKFIGURE,
- 57: Image.GHOST,
- 58: Image.SWORD,
- 59: Image.GIRAFFE,
- 60: Image.SKULL,
- 61: Image.UMBRELLA,
- 62: Image.SNAKE,
- 63: Image.HEART_SMALL