

Using Python/Anaconda in Fire Research

I. Introduction

- A. Type of work done in Fire Research Division at NIST [kickass fire picture]
- B. Areas in which Python/Anaconda is used
 - i. Realtime plotting helmet data
 - ii. FF LODI/LODD interactive map
 - iii. Realtime plotting of data from FDS model rendering

II. Portable Measurement and Data Acquisition System

- A. Overview of system [pic of entire system together]
 - i. Helmet portion [pic of helmet]
 - a. Thermocouple
 - b. Heat flux gauge
 - c. Cooling water lines
 - ii. Pack portion [pic of pack]
 - a. Miniature pump
 - b. Water reservoir
 - c. Arduino Yun as data logger
- B. Setting up Arduino Yun and host computer
 - i. Arduino Yun
 - a. *Details about all the packages and other shit to set up Yun?*
 - b. SD Card
 - ii. Host Computer
 - a. RabbitMQ message broker server
 - b. Run `receive_helmet_data`
 - c. Deploy Bokeh server
 - d. Run `plot_helmet_data.py`
- C. Plotting heat flux and temperature data in real time [fig of previous workflow and new work flow using arduino/bokeh]
 - i. Arduino Yun
 - a. Adafruit + arduino code to receive voltages from sensors
 - b. `send_helmet_data.py` executed using Yun's Linux distribution (OpenWrt-Yun) and following tasks are performed:
 - Sensor voltages converted to significant measurement (temperature or heat flux value)

- Arduino Yun connects to message broker on host computer using Yun's built-in WiFi support, IP address specified by user, and Pika package
- Message containing data at current time-step is constructed and published to message broker on host computer and locally to Yun's SD card

ii. Host Computer

- a. `receive_helmet_data.py` connects to the message broker, receives message sent to the broker from the Yun, prints message in terminal, and writes data to `.csv` file on host computer
- b. `plot_helmet_data.py` reads `.csv` file and plots corresponding data every second; new line of data added to `.csv` file every second