```
In [1]: import numpy as np
        import pandas as pd
        import cv2
        import matplotlib.pyplot as plt
        from keras.models import Sequential
        from keras.layers import Conv2D, MaxPooling2D, Flatten, Dense
        from keras.optimizers import Adam
        from keras.utils import to_categorical
        from keras.callbacks import EarlyStopping
        from collections import Counter
        from imblearn.over sampling import RandomOverSampler
        from sklearn.metrics import classification report
        # Load the data
        train_data = pd.read_excel("/Users/wkammerait/Desktop/ML Data Sets/data/Tra
        test data = pd.read excel("/Users/wkammerait/Desktop/ML Data Sets/data/Test
        folder_path = "/Users/wkammerait/Desktop/ML Data Sets/data/"
        train data['Path'] = folder path + train data['Path']
        test_data['Path'] = folder_path + test_data['Path']
```

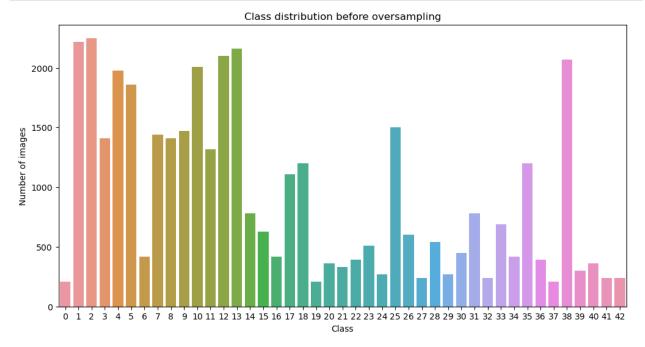
2023-08-08 08:47:39.386673: I tensorflow/core/platform/cpu_feature_guard.cc:182] This TensorFlow binary is optimized to use available CPU instruct ions in performance-critical operations.

To enable the following instructions: AVX2 FMA, in other operations, rebuild TensorFlow with the appropriate compiler flags.

```
In [2]: # Load and resize images
        def load and resize images(data):
            images = []
            for path in data['Path']:
                img = cv2.imread(path)
                img = cv2.resize(img, (30, 30))
                images.append(img)
            return np.array(images)
        train_images = load_and_resize_images(train_data)
        test images = load and resize images(test data)
        train_images_gray = np.array([cv2.cvtColor(img, cv2.COLOR_BGR2GRAY) for img
        test images gray = np.array([cv2.cvtColor(img, cv2.COLOR BGR2GRAY) for img
        # Normalize the pixel values to be in the range [0, 1]
        train images = train images.astype('float32') / 255.0
        train images gray = train images gray.astype('float32') / 255.0
        test_images = test_images.astype('float32') / 255.0
        test images gray = test images gray.astype('float32') / 255.0
        # Convert the labels to categorical format
        y_train = np.array(train_data['ClassId'])
        y_test = np.array(test_data['ClassId'])
        y train cat = to categorical(y train, num classes=43)
        y test cat = to categorical(y test, num classes=43)
```

```
In [3]: import matplotlib.pyplot as plt
import seaborn as sns

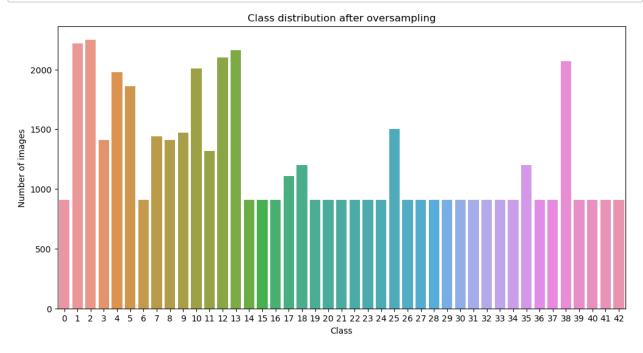
# Prior to oversampling
class_counts = pd.Series(y_train).value_counts()
plt.figure(figsize=(12,6))
sns.barplot(x=class_counts.index, y=class_counts.values)
plt.title("Class distribution before oversampling")
plt.xlabel("Class")
plt.ylabel("Number of images")
plt.show()
```



```
In [4]: # Handle class imbalance with oversampling
    counter = Counter(y_train)
    mean_count = int(np.mean([count for label, count in counter.items()]))
    strategy = {label: max(count, mean_count) for label, count in counter.items
    oversample = RandomOverSampler(sampling_strategy=strategy)
    train_images_res, y_train_res = oversample.fit_resample(train_images.reshap
    train_images_gray_res, y_train_gray_res = oversample.fit_resample(train_images.reshap)
```

```
In [5]: from keras.preprocessing.image import ImageDataGenerator
        # 1. Define the ImageDataGenerator
        datagen = ImageDataGenerator(
            rotation range=15, # Random rotations between -15 to 15 degrees
            width shift range=0.1, # Random shift in width by 10%
            height_shift_range=0.1, # Random shift in height by 10%
            shear_range=0.1,  # Shear transformations
zoom_range=0.1,  # Random zooming up to 10%
            #horizontal_flip=True, # Randomly flip images horizontally
            fill mode='nearest' # Fill missing pixels using nearest neighbours
        )
        # 2. Apply Augmentation to Specific Classes
        under represented classes = [20, 27, 40]
        augmented_images = []
        augmented labels = []
        for class id in under represented classes:
            # Filter images of the specific class
            mask = y_train == class_id
            class_images = train_images[mask]
            # Augment the images. This will generate batches, so we loop through th
            # until we've produced a desired number of augmented samples for the cl
            # For instance, you could double the number of samples with num augment
            num augmented = 0
            for x batch, y batch in datagen.flow(class images, np.zeros(len(class i
                augmented images.extend(x batch)
                augmented_labels.extend([class id]*len(x batch))
                num augmented += len(x batch)
                if num augmented >= len(class images):
                    break
        # Convert augmented data to numpy arrays
        augmented images = np.array(augmented images)
        augmented labels = np.array(augmented labels)
        # Add augmented data to the original data
        train images = np.concatenate([train images, augmented images], axis=0)
        y_train = np.concatenate([y_train, augmented_labels], axis=0)
        # Update the y train cat with the new y train data
        y train cat = to categorical(y train, num classes=43)
```

In [6]: # After oversampling class_counts_res = pd.Series(y_train_res).value_counts() plt.figure(figsize=(12,6)) sns.barplot(x=class_counts_res.index, y=class_counts_res.values) plt.title("Class distribution after oversampling") plt.xlabel("Class") plt.ylabel("Number of images") plt.show()



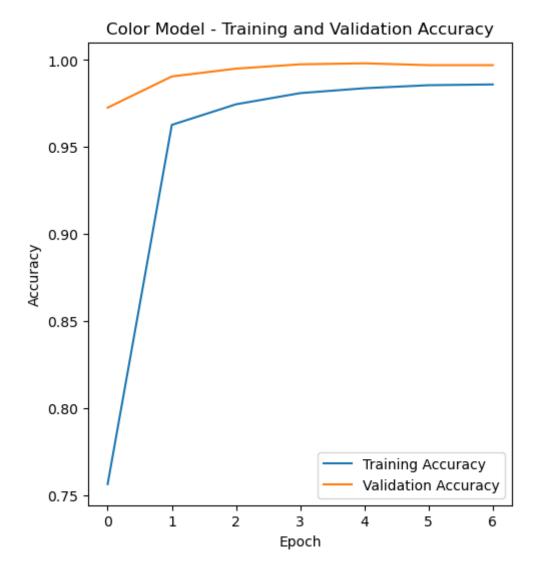
```
In [9]: # Reshape data
    train_images_res = train_images_res.reshape(-1, 30, 30, 3)
    train_images_gray_res = train_images_gray_res.reshape(-1, 30, 30, 1)
    y_train_res_cat = to_categorical(y_train_res, num_classes=43)
    y_train_gray_res_cat = to_categorical(y_train_gray_res, num_classes=43)
```

```
In [16]: from tensorflow.keras.layers import Dropout
         from keras.callbacks import EarlyStopping
         early_stopping = EarlyStopping(monitor='val_loss', patience=2)
         # Define and compile the color model
         model color = Sequential()
         model color.add(Conv2D(64, kernel size=(3, 3), activation='relu', input sha
         model_color.add(Conv2D(64, kernel_size=(3, 3), activation='relu'))
         model color.add(MaxPooling2D(pool_size=(2, 2)))
         model color.add(Dropout(0.25)) # Dropout layer added
         model_color.add(Conv2D(128, kernel_size=(3, 3), activation='relu'))
         model_color.add(Conv2D(128, kernel_size=(3, 3), activation='relu'))
         model color.add(MaxPooling2D(pool size=(2, 2)))
         model color.add(Dropout(0.25)) # Dropout layer added
         model_color.add(Flatten())
         model_color.add(Dense(256, activation='relu'))
         model color.add(Dropout(0.5)) # Dropout layer added
         model_color.add(Dense(43, activation='softmax'))
         model color.compile(optimizer=Adam(), loss='categorical crossentropy', metr
         # Train the color model
         history color = model color.fit(train images res, y train res cat, batch si
         # Define and compile the grayscale model
         model_gray = Sequential()
         model gray.add(Conv2D(64, kernel size=(3, 3), activation='relu', input shap
         model gray.add(Conv2D(64, kernel size=(3, 3), activation='relu'))
         model gray.add(MaxPooling2D(pool size=(2, 2)))
         model gray.add(Dropout(0.25)) # Dropout layer added
         model gray.add(Conv2D(128, kernel size=(3, 3), activation='relu'))
         model gray.add(Conv2D(128, kernel size=(3, 3), activation='relu'))
         model gray.add(MaxPooling2D(pool size=(2, 2)))
         model gray.add(Dropout(0.25)) # Dropout layer added
         model gray.add(Flatten())
         model gray.add(Dense(256, activation='relu'))
         model gray.add(Dropout(0.5)) # Dropout layer added
         model gray.add(Dense(43, activation='softmax'))
         model gray.compile(optimizer=Adam(), loss='categorical crossentropy', metri
         # Train the grayscale model
         history gray = model gray.fit(train images gray res, y train gray res cat,
```

```
Epoch 1/10
0 - accuracy: 0.7563 - val loss: 0.1172 - val accuracy: 0.9726
Epoch 2/10
63 - accuracy: 0.9627 - val_loss: 0.0349 - val_accuracy: 0.9906
Epoch 3/10
77 - accuracy: 0.9745 - val_loss: 0.0182 - val_accuracy: 0.9950
Epoch 4/10
32 - accuracy: 0.9810 - val_loss: 0.0125 - val_accuracy: 0.9975
Epoch 5/10
64 - accuracy: 0.9838 - val loss: 0.0080 - val accuracy: 0.9981
Epoch 6/10
87 - accuracy: 0.9855 - val loss: 0.0135 - val accuracy: 0.9970
84 - accuracy: 0.9859 - val_loss: 0.0116 - val_accuracy: 0.9970
Epoch 1/10
58 - accuracy: 0.6995 - val_loss: 0.1822 - val_accuracy: 0.9479
Epoch 2/10
97 - accuracy: 0.9549 - val loss: 0.0481 - val accuracy: 0.9887
Epoch 3/10
89 - accuracy: 0.9733 - val loss: 0.0171 - val accuracy: 0.9961
Epoch 4/10
23 - accuracy: 0.9776 - val loss: 0.0144 - val accuracy: 0.9968
Epoch 5/10
55 - accuracy: 0.9831 - val loss: 0.0127 - val accuracy: 0.9965
09 - accuracy: 0.9841 - val loss: 0.0056 - val accuracy: 0.9986
Epoch 7/10
11 - accuracy: 0.9872 - val loss: 0.0040 - val accuracy: 0.9993
Epoch 8/10
98 - accuracy: 0.9876 - val loss: 0.0014 - val accuracy: 0.9999
Epoch 9/10
55 - accuracy: 0.9889 - val loss: 0.0015 - val accuracy: 0.9994
Epoch 10/10
43 - accuracy: 0.9898 - val loss: 0.0025 - val accuracy: 0.9996
```

```
In [17]: # Plot the training and validation accuracy
    plt.figure(figsize=(12, 6))
    plt.subplot(1, 2, 1)
    plt.plot(history_color.history['accuracy'], label='Training Accuracy')
    plt.plot(history_color.history['val_accuracy'], label='Validation Accuracy'
    plt.legend()
    plt.xlabel('Epoch')
    plt.ylabel('Accuracy')
    plt.title('Color Model - Training and Validation Accuracy')
```

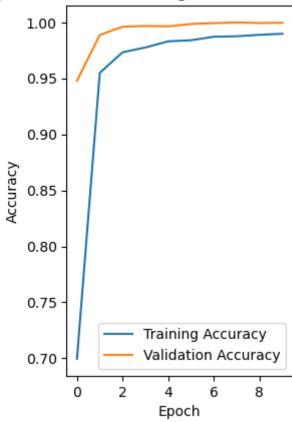
Out[17]: Text(0.5, 1.0, 'Color Model - Training and Validation Accuracy')



```
In [18]: plt.subplot(1, 2, 2)
   plt.plot(history_gray.history['accuracy'], label='Training Accuracy')
   plt.plot(history_gray.history['val_accuracy'], label='Validation Accuracy')
   plt.legend()
   plt.xlabel('Epoch')
   plt.ylabel('Accuracy')
   plt.title('Grayscale Model - Training and Validation Accuracy')
```

Out[18]: Text(0.5, 1.0, 'Grayscale Model - Training and Validation Accuracy')

Grayscale Model - Training and Validation Accuracy



```
In [20]: # Get predictions for both models
    y_pred_color = np.argmax(model_color.predict(test_images), axis=-1)
    y_pred_gray = np.argmax(model_gray.predict(test_images_gray), axis=-1)

# Print the classification report for both models
    print("Classification report for color model:")
    print(classification_report(y_test, y_pred_color))

print("Classification_report for grayscale model:")
    print(classification_report(y_test, y_pred_gray))
```

395/395 [=======] - 8s 20ms/step 395/395 [==========] - 8s 19ms/step 395/395 [===========] - 8s 19ms/step

Classification				
	precision	recall	f1-score	support
0	1.00	1.00	1.00	60
1	0.96	0.99	0.97	720
2	0.98	0.99	0.99	750
3	0.98	0.95	0.96	450
4	0.99	1.00	0.99	660
5	0.93	0.99	0.96	630
6	1.00	0.87	0.93	150
7	1.00	0.98	0.99	450
8	0.97	0.99	0.98	450
9	0.98	1.00	0.99	480
10	1.00	0.98	0.99	660
11	0.96	0.99	0.97	420
12	0.98	0.99	0.99	690
13	0.98	1.00	0.99	720
14	1.00	1.00	1.00	270
15	0.95	1.00	0.97	210
16	1.00	1.00	1.00	150
17	1.00	0.96	0.98	360
18	0.98	0.92	0.95	390
19	1.00	1.00	1.00	60
20	0.98	1.00	0.99	90
21	0.97	0.71	0.82	90
22	1.00	0.95	0.97	120
23	0.85	0.99	0.91	150
24	1.00	0.97	0.98	90
25	0.98	0.99	0.98	480
26	0.93	0.89	0.91	180
27	0.89	0.52	0.65	60
28	1.00	0.96	0.98	150
29	0.95	1.00	0.97	90
30	1.00	0.69	0.81	150
31	0.92	0.99	0.95	270
32	1.00	1.00	1.00	60
33	1.00	0.99	0.99	210
34	0.89	0.99	0.94	120
35	1.00	0.99	0.99	390
36	0.99	0.95	0.97	120
37	1.00	0.98	0.99	60
38	0.97	0.99	0.98	690
39	0.92	0.98	0.95	90
40	0.97	0.99	0.98	90
41	1.00	0.87	0.93	60
42	1.00	1.00	1.00	90
42	1.00	1.00	1.00	70
accuracy			0.97	12630
macro avg	0.97	0.95	0.96	12630
weighted avg	0.97	0.97	0.97	12630

Classification report for grayscale model:

precision recall f1-score support

0.98 0.98 0.98

60

localhost:8888/notebooks/Street Signs Take 4_Kammerait.ipynb

		Street Signs Tak	.c +_ixammeran - j	upyter riotebook
1	0.96	0.99	0.97	720
2	0.96	0.99	0.97	750
3	0.95	0.98	0.97	450
4	0.98	0.98	0.98	660
5	0.97	0.93	0.95	630
6	1.00	0.85	0.92	150
7	0.98	0.98	0.98	450
8	1.00	0.94	0.97	450
9	0.98	1.00	0.99	480
10	1.00	0.99	0.99	660
11	0.97	0.99	0.98	420
12	0.96	0.97	0.96	690
13	1.00	1.00	1.00	720
14	0.99	1.00	1.00	
15	0.86	1.00	0.93	210
16	0.99	1.00	0.99	
17	1.00	0.97	0.98	
18	0.99	0.93	0.96	
19	0.98	1.00	0.99	
20	0.78	1.00	0.88	
21	1.00	0.79	0.88	
22	1.00	0.86	0.92	
23	0.98	1.00	0.99	
24	0.95	0.96	0.95	
25	0.98	0.98	0.98	
26	0.88	0.97	0.92	
27	0.86	0.52	0.65	
28	0.96	0.99	0.98	
29	1.00	0.99	0.99	
30	1.00	0.87	0.93	
31	0.99	0.99	0.99	
32	0.97	1.00	0.98	
33	0.91	1.00	0.95	
34	0.93	1.00	0.96	
35	1.00	0.98	0.99	
36	0.98	1.00	0.99	
37	0.98	1.00	0.99	
38	0.99	0.98	0.99	
39	0.99	0.98	0.98	
40	0.83	0.88	0.85	
41	0.95	0.87	0.90	
42	0.97	1.00	0.98	
12	0.57	1.00	0.50	50
accuracy			0.97	
macro avg	0.96	0.95	0.96	12630
weighted avg	0.97	0.97	0.97	12630

Looking at the classification reports, the color model performed with slightly better macro precision and otherwise performed the same (for overall metrics). Increasing the patience would further separate the color model from the grayscale model (meaning I tried this and the model performed better), but the project requires we set the patience = 2 for early stopping.

Additionally, while both models poorly identified pedestrians with excessive false negatives, the color model performed much better at identifying "Dangerous Curve Right" signs and roundabout mandatory signs.

Relatively strong F1 scores (> 0.9, as specified in the instructions) indicate a relatively healthy balance between precision and recall.