



This state diagram shows the life cycle of a Timer Object. When the object is created and set to run with QThreadPool::globalinstance()->start(), it first calls the timerLoop(). At first its default for isNotPaused is true, meaning that the timer remain on a state of waiting for commands.

When the CES calls Timer::start(), it changes isNotPaused to false which begins the flow of sending a tick() signal and decreasing the counter value. If the counter value reaches 0, it sends a end() signal to the CES which the CES can interpret how ever it wants. Because the counter is now 0, the timer goes back to a state of waiting. The counter can be reset with calling Timer::setTime(int). Timer::pause() will also set the timer to a waiting state.

The object is destroyed when the CES call Timer::stop()