

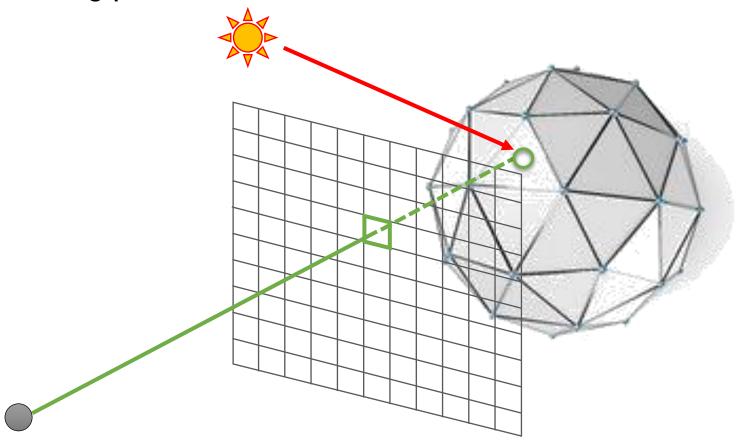
Shadows

Introduction to Computer Graphics Yu-Ting Wu

Shadow Map

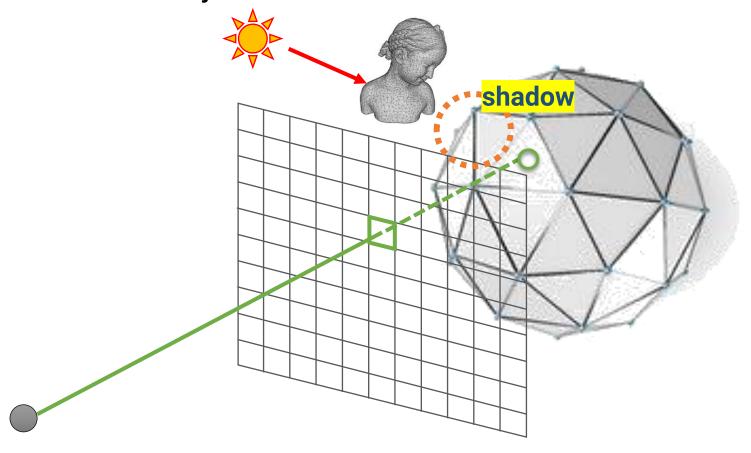
Shadow

 So far, we consider the light to be fully visible to a shading point



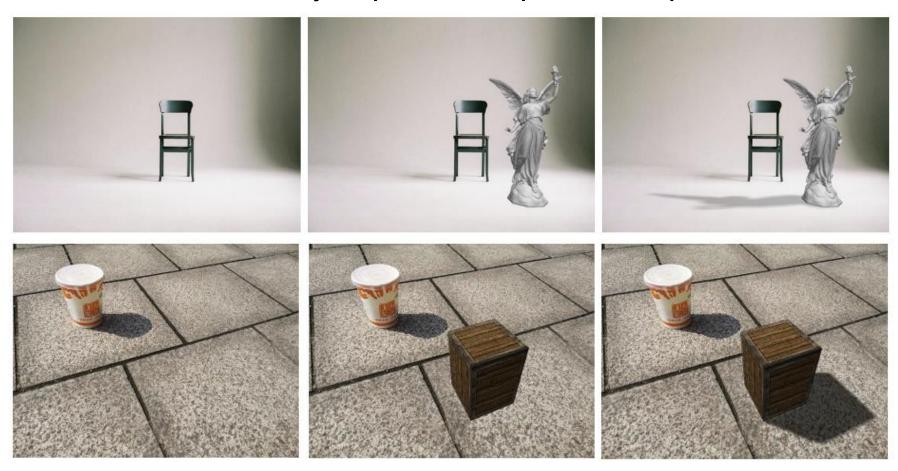
Shadow (cont.)

 It is common that a lighting direction is occluded by some other objects



Shadow (cont.)

• Shadows are very important to provide depth cues

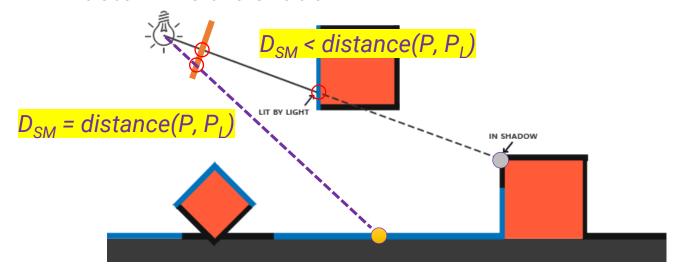


Shadow Map Overview

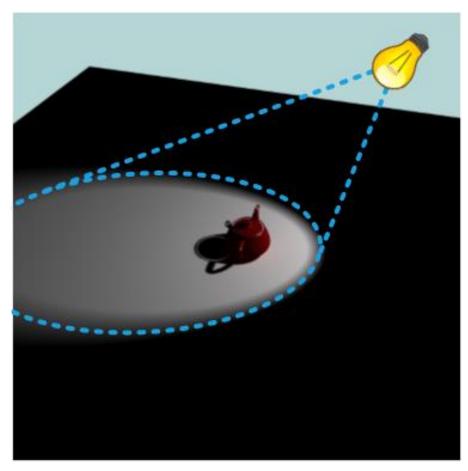
- Like the case of transparency, rendering shadows is difficult for rasterization because each polygon only has its own information
 - It does not know which triangle blocks the light, so it cannot determine the shadow attenuation in its fragment shader
- Shadow map is a two-pass rendering technique for simulating shadows using rasterization

Shadow Map Overview (cont.)

- Major concept
 - First pass: rendering a depth map from the light position
 - Record the closest surface from the light and generate a shadow map
 - Second pass: rendering from the camera
 - During lighting computation, lookup the shadow map to determine the shadow



Shadow Map Overview (cont.)



final rendering (rendering from the camera view)



shadow map (rendering from the light view)

Shadow Map Overview (cont.)

- Major concept
 - https://learnopengl.com/Advanced-Lighting/Shadows/Shadow-Mapping

rendering from the light view

```
// 1. first render to depth map
glViewport(0, 0, SHADOW_WIDTH, SHADOW_HEIGHT);
glBindFramebuffer(GL_FRAMEBUFFER, depthMapFBO);
    glClear(GL_DEPTH_BUFFER_BIT);
    ConfigureShaderAndMatrices();
    RenderScene();
glBindFramebuffer(GL_FRAMEBUFFER, 0);
// 2. then render scene as normal with shadow mapping (using depth map)
glViewport(0, 0, SCR_WIDTH, SCR_HEIGHT);
glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
ConfigureShaderAndMatrices();
glBindTexture(GL_TEXTURE_2D, depthMap);
RenderScene();
```

rendering from the camera view

Shadow Map for Directional Lights

First pass: shadow map generation

rendering from the light view

```
// 1. first render to depth map
glViewport(0, 0, SHADOW_WIDTH, SHADOW_HEIGHT);
glBindFramebuffer(GL_FRAMEBUFFER, depthMapFBO);
    glClear(GL_DEPTH_BUFFER_BIT);
    ConfigureShaderAndMatrices();
    RenderScene();
glBindFramebuffer(GL_FRAMEBUFFER, 0); bind to default screen
// 2. then render scene as normal with shadow mapping (using depth map)
glViewport(0, 0, SCR_WIDTH, SCR_HEIGHT);
glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
ConfigureShaderAndMatrices();
glBindTexture(GL_TEXTURE_2D, depthMap);
RenderScene();
```

- First pass: shadow map generation
 - Create a FBO for the shadow map

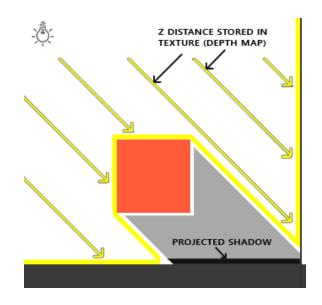
```
const unsigned int SHADOW_WIDTH = 1024, SHADOW_HEIGHT = 1024; shadow map resolution
unsigned int depthMapFBO;
glGenFramebuffers(1, &depthMapFBO);
// create depth texture
unsigned int depthMap;
                                        DL_DEPTH_COMPONENT(16/24/32F)
glGenTextures(1, &depthMap);
glBindTexture(GL TEXTURE 2D, depthMap);
glTexImage2D(GL TEXTURE 2D, 0, GL DEPTH COMPONENT, SHADOW WIDTH, SHADOW HEIGHT, 0, GL DEPTH COMPONENT, GL FLOAT, NULL);
glTexParameteri(GL TEXTURE 2D, GL TEXTURE MIN FILTER, GL NEAREST);
glTexParameteri(GL TEXTURE 2D, GL TEXTURE MAG FILTER, GL NEAREST);
glTexParameteri(GL TEXTURE 2D, GL TEXTURE WRAP S, GL CLAMP TO BORDER);
glTexParameteri(GL TEXTURE 2D, GL TEXTURE WRAP T, GL CLAMP TO BORDER);
float borderColor[] = { 1.0, 1.0, 1.0, 1.0 };
glTexParameterfv(GL TEXTURE 2D, GL TEXTURE BORDER COLOR, borderColor);
// attach depth texture as FBO's depth buffer
glBindFramebuffer(GL FRAMEBUFFER, depthMapFBO);
glFramebufferTexture2D(GL FRAMEBUFFER, GL DEPTH ATTACHMENT, GL TEXTURE 2D, depthMap, ∅);
glDrawBuffer(GL NONE);
glReadBuffer(GL_NONE); tell OpenGL we don't need a color buffer
glBindFramebuffer(GL FRAMEBUFFER, ∅);
```

- First pass: shadow map generation
 - Choose a proper resolution





- First pass: shadow map generation
 - A directional light does not have a light position
 - We set the camera to a position somewhere along the lines of the light direction
 - Use orthogonal projection



```
glm::mat4 lightProjection, lightView;
glm::mat4 lightSpaceMatrix;
float near_plane = 1.0f, far_plane = 7.5f;
//lightProjection = glm::perspective(glm::radians(45.0f), (GLfloat)SHADOW_WIDTH / (
lightProjection = glm::ortho(-10.0f, 10.0f, -10.0f, 10.0f, near_plane, far_plane);
lightView = glm::lookAt(lightPos, glm::vec3(0.0f), glm::vec3(0.0, 1.0, 0.0));
lightSpaceMatrix = lightProjection * lightView;
```

- First pass: shadow map generation
 - Vertex Shader

Fragment Shader (do nothing)

```
#version 330 core

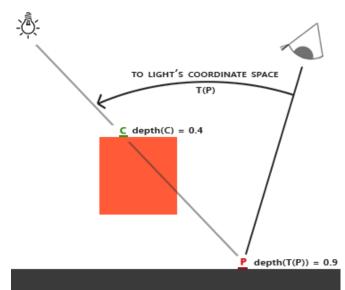
void main()
{
     // gl_FragDepth = gl_FragCoord.z;
}
```



- Second pass: normal rendering
 - Render the scene from the camera
 - Look up the shadow map to determine shadows during lighting computation

```
// 1. first render to depth map
glViewport(0, 0, SHADOW_WIDTH, SHADOW_HEIGHT);
glBindFramebuffer(GL_FRAMEBUFFER, depthMapFBO);
    glClear(GL_DEPTH_BUFFER_BIT);
    ConfigureShaderAndMatrices();
    RenderScene();
glBindFramebuffer(GL_FRAMEBUFFER, 0);
// 2. then render scene as normal with shadow mapping (using depth map)
glViewport(0, 0, SCR_WIDTH, SCR_HEIGHT);
glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT);
ConfigureShaderAndMatrices();
glBindTexture(GL_TEXTURE_2D, depthMap);
RenderScene();
```





- Second pass: normal rendering
 - Vertex Shader

```
#version 330 core
layout (location = 0) in vec3 aPos;
layout (location = 1) in vec3 aNormal;
layout (location = 2) in vec2 aTexCoords;
out VS OUT {
   vec3 FragPos;
   vec3 Normal;
   vec2 TexCoords;
   vec4 FragPosLightSpace;
} vs out;
uniform mat4 projection;
uniform mat4 view;
uniform mat4 model;
uniform mat4 lightSpaceMatrix;
void main()
                                                               Clip Space coordinate in
   vs out.FragPos = vec3(model * vec4(aPos, 1.0));
   vs out.Normal = transpose(inverse(mat3(model))) * aNormal;
                                                                    the shadow map
   vs out.TexCoords = aTexCoords;
   vs out.FragPosLightSpace = lightSpaceMatrix * vec4(vs out.FragPos, 1.0);
    gl Position = projection * view * vec4(vs out.FragPos, 1.0);
```

- Second pass: normal rendering
 - Fragment Shader

```
#version 330 core
out vec4 FragColor;
in VS OUT {
    vec3 FragPos;
    vec3 Normal;
    vec2 TexCoords;
    vec4 FragPosLightSpace;
} fs in;
uniform sampler2D diffuseTexture;
uniform sampler2D shadowMap;
uniform vec3 lightPos;
uniform vec3 viewPos;
float ShadowCalculation(vec4 fragPosLightSpace)
    [\ldots]
void main()
    FragColor = vec4(lighting, 1.0);
```

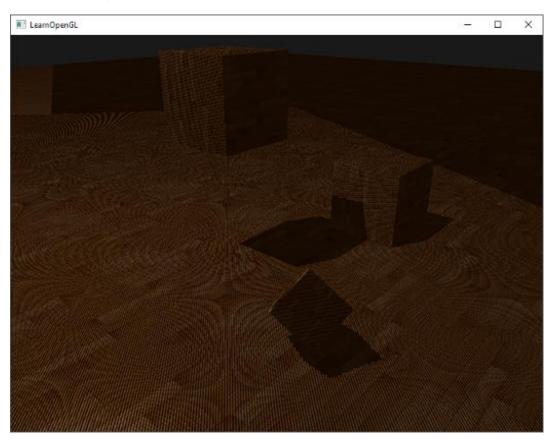
- Second pass: normal rendering
 - Fragment Shader

```
void main()
    vec3 color = texture(diffuseTexture, fs in.TexCoords).rgb;
    vec3 normal = normalize(fs in.Normal);
    vec3 lightColor = vec3(1.0);
    vec3 ambient = 0.15 * lightColor;
    // diffuse
    vec3 lightDir = normalize(lightPos - fs in.FragPos);
    float diff = max(dot(lightDir, normal), 0.0);
    vec3 diffuse = diff * lightColor;
    // specular
    vec3 viewDir = normalize(viewPos - fs in.FragPos);
    float spec = 0.0;
    vec3 halfwayDir = normalize(lightDir + viewDir);
    spec = pow(max(dot(normal, halfwayDir), 0.0), 64.0);
    vec3 specular = spec * lightColor;
   // calculate shadow
   float shadow = ShadowCalculation(fs in.FragPosLightSpace);
    vec3 lighting = (ambient + (1.0 - shadow) * (diffuse + specular)) * color;
    FragColor = vec4(lighting, 1.0);
```

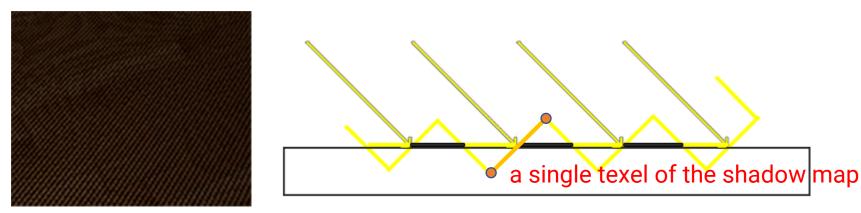
- Second pass: normal rendering
 - Fragment Shader

```
float ShadowCalculation(vec4 fragPosLightSpace)
    // perform perspective divide
    vec3 projCoords = fragPosLightSpace.xyz / fragPosLightSpace.w; to NDC [-1, 1]
    // transform to [0,1] range
    projCoords = projCoords * 0.5 + 0.5; to [0, 1] for looking up the shadow map
    // get closest depth value from light's perspective (using [0,1] range fragPosLight as coords)
    float closestDepth = texture(shadowMap, projCoords.xy).r;
    // get depth of current fragment from light's perspective
    float currentDepth = projCoords.z;
    // check whether current frag pos is in shadow
    float shadow = currentDepth > closestDepth ? 1.0 : 0.0;
                                                                                  TO LIGHT'S COORDINATE SPACE
    return shadow;
                                                                                 C depth(C) = 0.4
                                                                                               depth(T(P)) = 0
```

- Halfway result
 - Almost there, but with undesired artifacts



Avoid shadow acne



- Multiple fragments can sample the same location from the shadow map when they're relatively far away from the light source
- Become an issue when the light source looks at an angle towards the surface
 - Several fragments access the same tilted depth texel while some are above and some below the floor

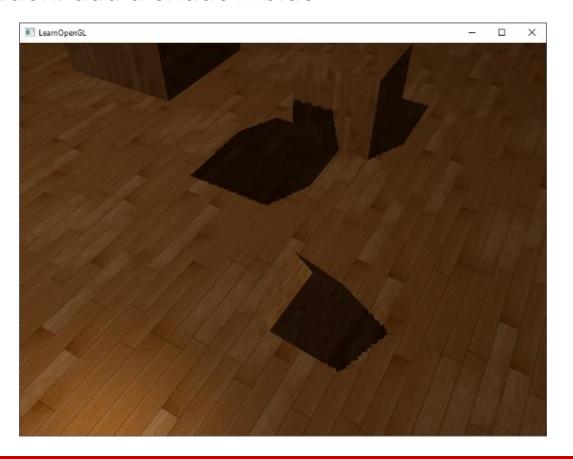
- Avoid shadow acne
 - Solution: add a shadow bias
 - Offset the depth of the surface (or the shadow map) by a small bias amount

```
float bias = 0.005;
float shadow = currentDepth - bias > closestDepth ? 1.0 : 0.0;
```

Or make it more robust by considering the lighting direction

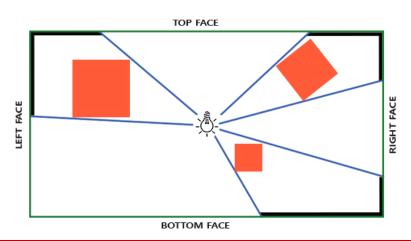
```
float bias = max(0.05 * (1.0 - dot(normal, lightDir)), 0.005);
```

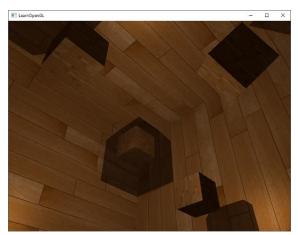
- Avoid shadow acne
 - Solution: add a shadow bias



Shadow Map for Point / Spot Lights

- Generate a shadow map for a spotlight is intuitive
 - Locate the camera at the position of the spotlight
 - Use the direction of the spotlight for viewing direction
 - Use perspective projection instead of orthogonal projection
- For a point light, you need to render the scene depth into a cubemap because the light emits in omni directions
 - https://learnopengl.com/Advanced-Lighting/Shadows/Point-Shadows



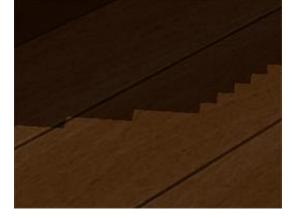


Percentage Closer Filtering

The shadow map has a fixed (and limited) resolution

A single lookup of a shadow map often produces jagged

blocky edges

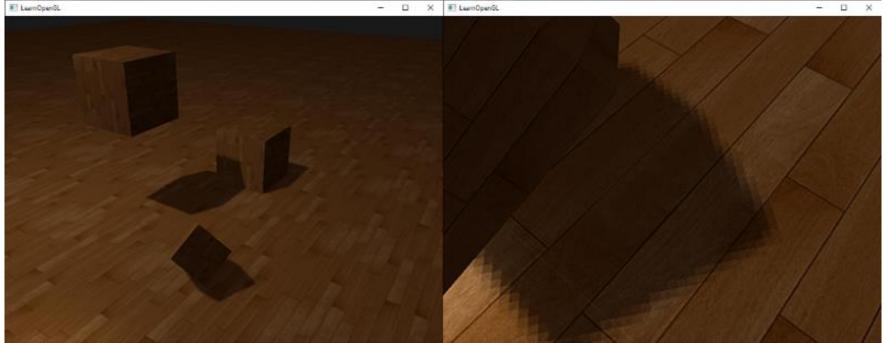


- We can reduce these blocky shadows by increasing the depth map resolution, or
- Sampling more than once from the depth map, each time with slightly different texture coordinates, and averaging the results

Percentage Closer Filtering



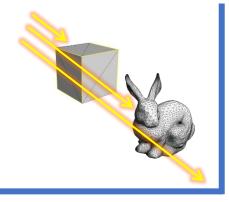
```
float shadow = 0.0;
vec2 texelSize = 1.0 / textureSize(shadowMap, 0);
for(int x = -1; x <= 1; ++x)
{
    for(int y = -1; y <= 1; ++y)
    {
        float pcfDepth = texture(shadowMap, projCoords.xy + vec2(x, y) * texelSize).r;
        shadow += currentDepth - bias > pcfDepth ? 1.0 : 0.0;
    }
}
shadow /= 9.0;
```



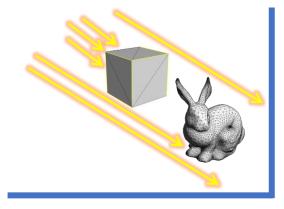
Ambient Occlusion

Recap: Global Illumination

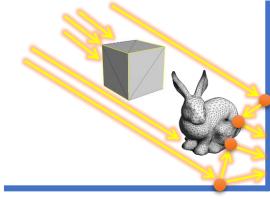
- Global illumination includes multi-bounce lighting
- Very expensive to compute
- In Phong lighting model, a constant ambient term is used to account for disregarded illumination
 - However, this produces a "flat", "non-photo-realistic" appearance



local illumination



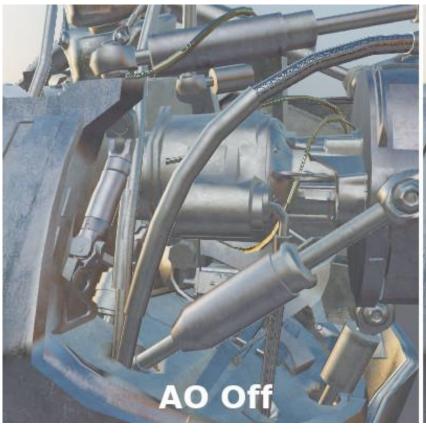
direct illumination



global illumination

Ambient Occlusion

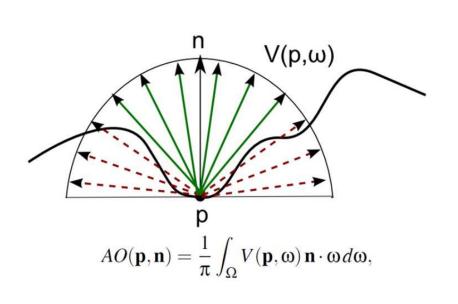
 Ambient occlusion (AO) is a popular technique to approximate global illumination

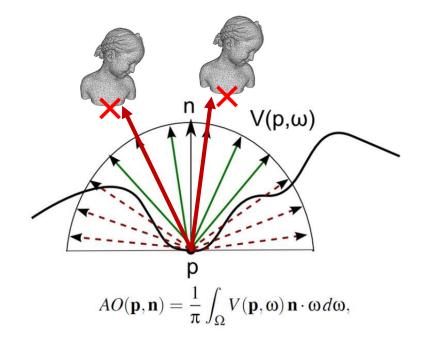




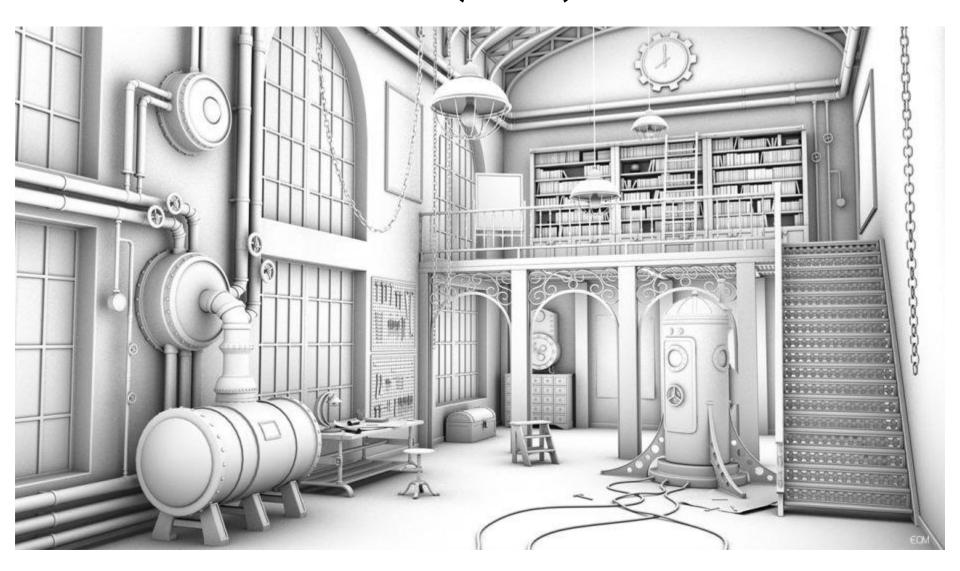
Ambient Occlusion (cont.)

- Ambient occlusion (AO) is a popular technique to approximate global illumination
 - Modulate ambient light by the surface's accessibility
 - Greatly enhance depth perception with a relatively low cost





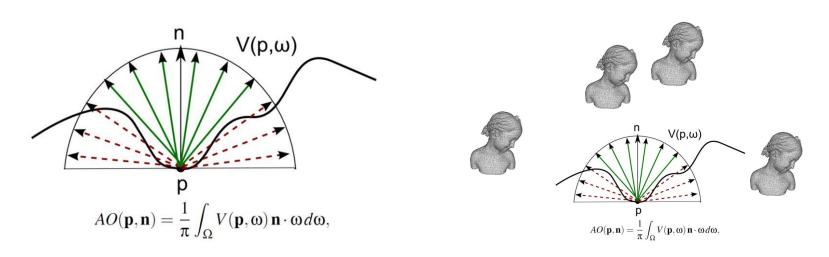
Ambient Occlusion (cont.)



Ambient Occlusion (cont.)

Ambient Occlusion

- To compute AO, you need to know whether the ambient light is occluded in a direction
- In ray tracing, you can trace rays to determine the visibility
- For rasterization; however, this is difficult because each polygon only knows its information (again!)
 - Performance is also an issue!



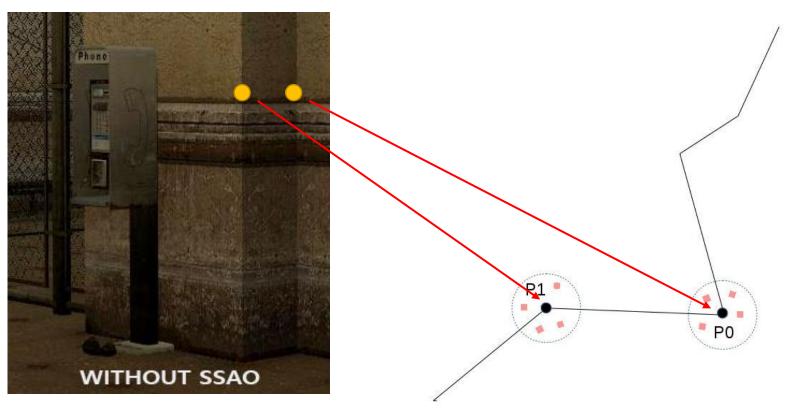
Screen-space Ambient Occlusion

- Crytek implemented a real-time solution for Crysis
 - Quickly became the yardstick for game graphics
 - Known as screen-space ambient occlusion (SSAO)
- Major idea
 - Find nearby occluders in the depth buffer (screen-space)

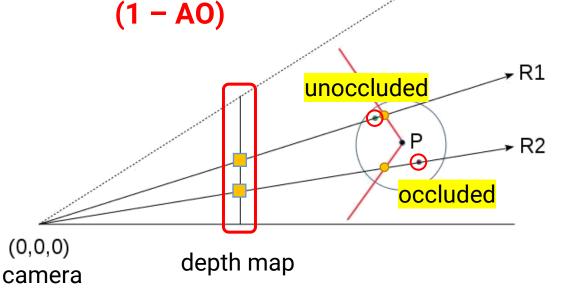


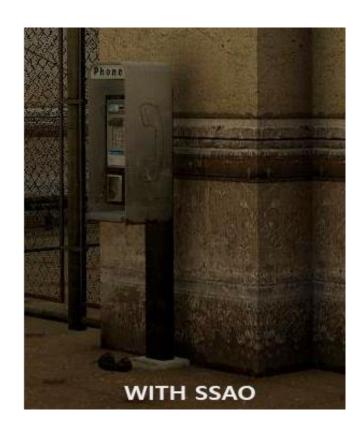


- Method
 - Generate samples within a sphere around the shading point (fragment)

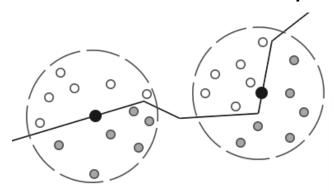


- Method
 - Project the samples back to the depth map from the camera
 - Compare the depth values
 - Average the testing results (AO)
 - Modulate the ambient term with





- Strike a balance for the sample count (a compromise between quality and performance)
- Use some techniques to trade artifacts (banding) with noise, and later removed them by filtering
 - Obtain acceptable results with few samples







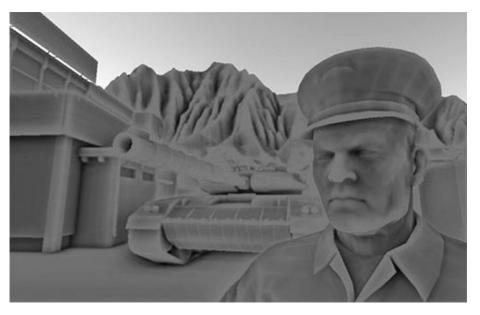


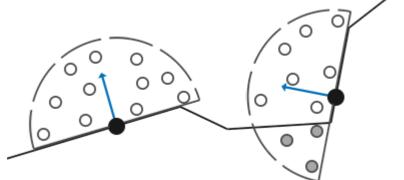
low sample 'banding'

random rotation = noise

+ blur = acceptable

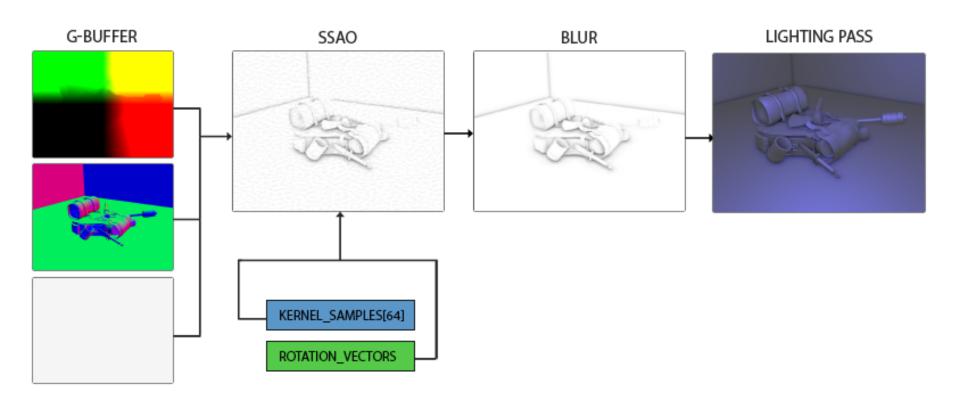
- Problem and improvement
 - Generate samples within a sphere produces results that are too dark
 - Why? Half of the samples are underneath the surface
 - Solution: use hemisphere (oriented by normal) instead



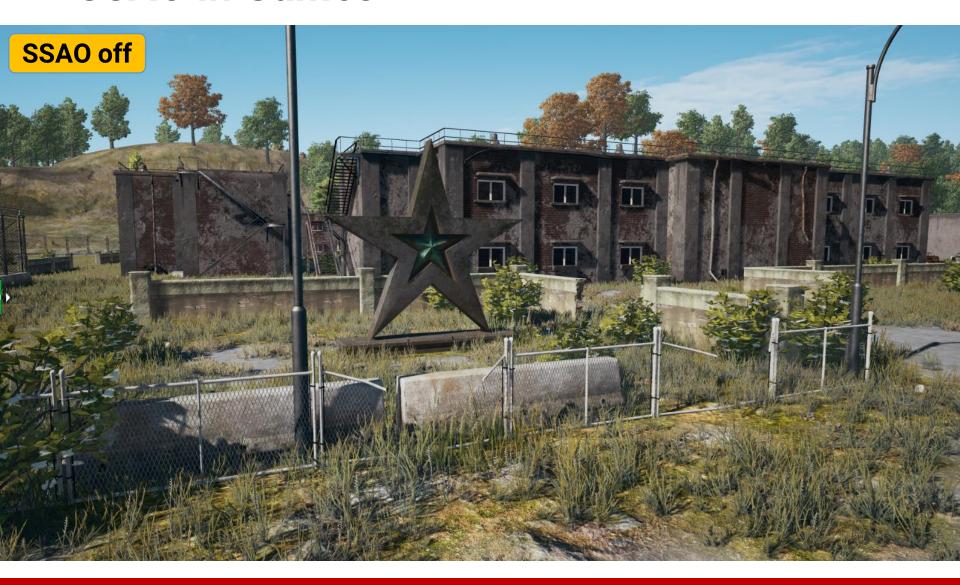


rotate by the TBN matrix!

- An implementation
 - https://learnopengl.com/Advanced-Lighting/SSAO



SSAO in Games



SSAO in Games (cont.)



Any Questions?