

Introduction and Preliminaries

Distributions

Joint Distribution

Assume we have three random variables.

- Intelligence(I), we have two possible values i^0 and i^1
- Difficulty(D), we have two possible values d^0 and d^1
- Grade(G), we have three possible values g^0 , g^1 and g^2

Here is a chart of possible distribution of these 3 random variables. This is an example of $P(I, D, G)$.

I	D	G	Prob.
i^0	d^0	g^1	0.126
i^0	d^0	g^2	0.168
i^0	d^0	g^3	0.126
i^0	d^1	g^1	0.009
i^0	d^1	g^2	0.045
i^0	d^1	g^3	0.126
i^1	d^0	g^1	0.252
i^1	d^0	g^2	0.0224
i^1	d^0	g^3	0.0056
i^1	d^1	g^1	0.06
i^1	d^1	g^2	0.036
i^1	d^1	g^3	0.024

There are $2*2*3 = 12$ entries in this distribution. There are total 12 parameters to represent this distribution.

Independent parameters are parameters whose value is not completely determined by the value of other parameters. So in this case, since the sum of prob. is 1. So we can know the independent parameters is 11.

Conditioning

Assume we got the information g^1 . Then the chart becomes:

I	D	G	Prob.
i^0	d^0	g^1	0.126
i^0	d^1	g^1	0.009
i^1	d^0	g^1	0.252
i^1	d^1	g^1	0.06

We remove the distribution that not agree with our observation. This process called **Redcution**.

We can see that the remaining distribution do not satisfy with the defination of distribution since the sum of all prob. is not 1. Then we need a action called **Normalized measure**. We calculate the sum of all prob. is 0.447, and we make every entry in the chart divided by 0.447.

Marginalization

This operation take a subset of a distribution over large number of random variables. Like following example. We have original distribution over I and D . Now we only want the distribution over D , that means we need marginalize I .

I	D	Prob.
i ⁰	d ⁰	0.282
i ⁰	d ¹	0.02
i ¹	d ⁰	0.564
i ¹	d ¹	0.134

D	Prob.
d ⁰	0.846
d ¹	0.154

The computation process over this example is $P(D) = \sum_I P(I, D)$

Factors

Basically, factor can be seen as a function or a table. It takes arguments, like random variables, and take all possible assignments over scope and return a real value.

$$\phi(X_1..X_k) \rightarrow R, \text{ Scope} = \{X_1, \dots, X_k\}$$

- As we already known joint distribution. We can see a joint distribution as a factor.
- Besides that, we can see an unnormalized measure $P(I, D, g^1)$ as a factor, whose scope is $\{I, D\}$
- Conditional Probability Distribution(CPD), $P(G|I, D)$ can also be seen as a factor.

General Factors, In theses factors the real value it return may not represent the probability.

a ¹	b ¹	0.5
a ¹	b ²	0.8
a ²	b ¹	0.1
a ²	b ²	0
a ³	b ¹	0.3
a ³	b ²	0.9

b ¹	c ¹	0.5
b ¹	c ²	0.7
b ²	c ¹	0.1
b ²	c ²	0.2

a ¹	b ¹	c ¹	0.5 0.5 = 0.25
a ¹	b ¹	c ²	0.5 0.7 = 0.35
a ¹	b ²	c ¹	0.8 0.1 = 0.08
a ¹	b ²	c ²	0.8 0.2 = 0.16
a ²	b ¹	c ¹	0.1 0.5 = 0.05
a ²	b ¹	c ²	0.1 0.7 = 0.07
a ²	b ²	c ¹	0 0.1 = 0
a ²	b ²	c ²	0 0.2 = 0
a ³	b ¹	c ¹	0.3 0.5 = 0.15
a ³	b ¹	c ²	0.3 0.7 = 0.21
a ³	b ²	c ¹	0.9 0.1 = 0.09
a ³	b ²	c ²	0.9 0.2 = 0.18

Factor Product

In this example, we have ϕ_1 , whose scope is A, B , and ϕ_2 , whose scope is B, C . We product these two factor together we can get a factor ϕ_3 , whose scope is A, B, C .

If we want to get a value in ϕ_3 , for example we want $\phi_3(a^1, b^1, c^1)$, we can calculate by $\phi_1(a^1, b^1) * \phi_2(b^1, c^1)$

Factor Marginalization Factor marginalization is similar to the marginalization in the distribution. In the following example, if we want to get $\phi(a^1, b^1)$, we need to sum over all possible assignments over b

a ¹	b ¹	c ¹	0.25
a ¹	b ¹	c ²	0.35
a ¹	b ²	c ¹	0.08
a ¹	b ²	c ²	0.16
a ²	b ¹	c ¹	0.05
a ²	b ¹	c ²	0.07
a ²	b ²	c ¹	0
a ²	b ²	c ²	0
a ³	b ¹	c ¹	0.15
a ³	b ¹	c ²	0.21
a ³	b ²	c ¹	0.09
a ³	b ²	c ²	0.18

a ¹	c ¹	0.33
a ¹	c ²	0.51
a ²	c ¹	0.05
a ²	c ²	0.07
a ³	c ¹	0.24
a ³	c ²	0.39

Factor Reduction It's pretty same as reduction in distribution. For example we want to see the context c^1 , we only focus on the entries that satisfy the c^1 .

Why Factor

- Fundamental building block for defining distributions in high-dimensional spaces.
- Set of basic operations for manipulating these probability distributions