

Semantic segmentation

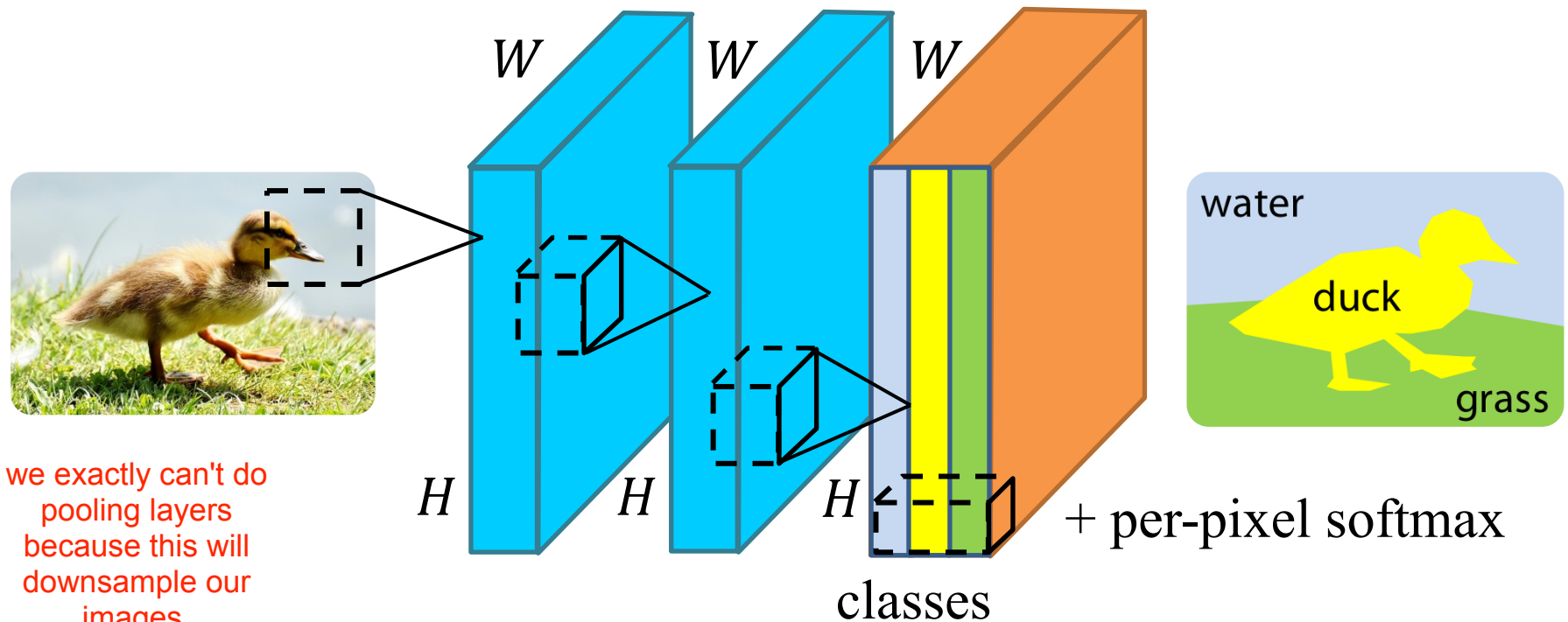
We need to classify each pixel



image classification + localization.
Not only what is the image, but where we see it.

Semantic segmentation

We need to classify each pixel



we exactly can't do pooling layers because this will downsample our images.

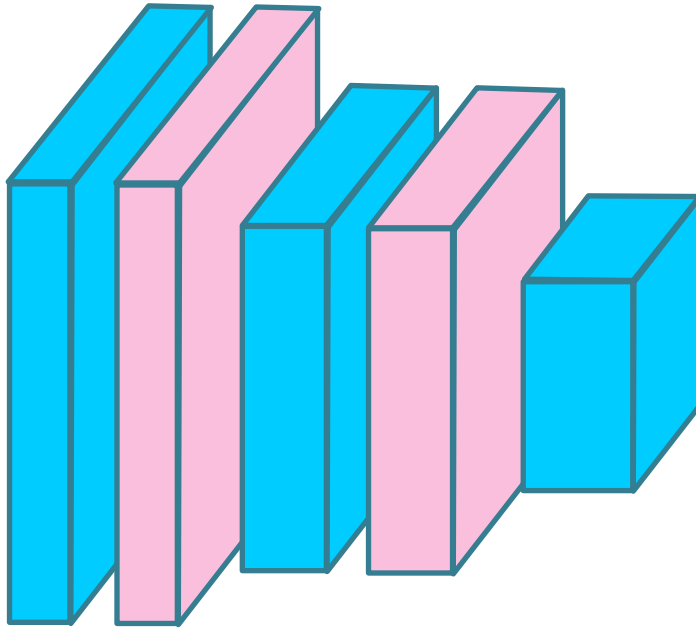
We want our segmentation to be crisp, not low quality.

Naïve approach: stack convolutional layers and add per-pixel softmax

We go deep but don't add pooling, too expensive

Semantic segmentation

Let's add pooling, which acts like **down-sampling**



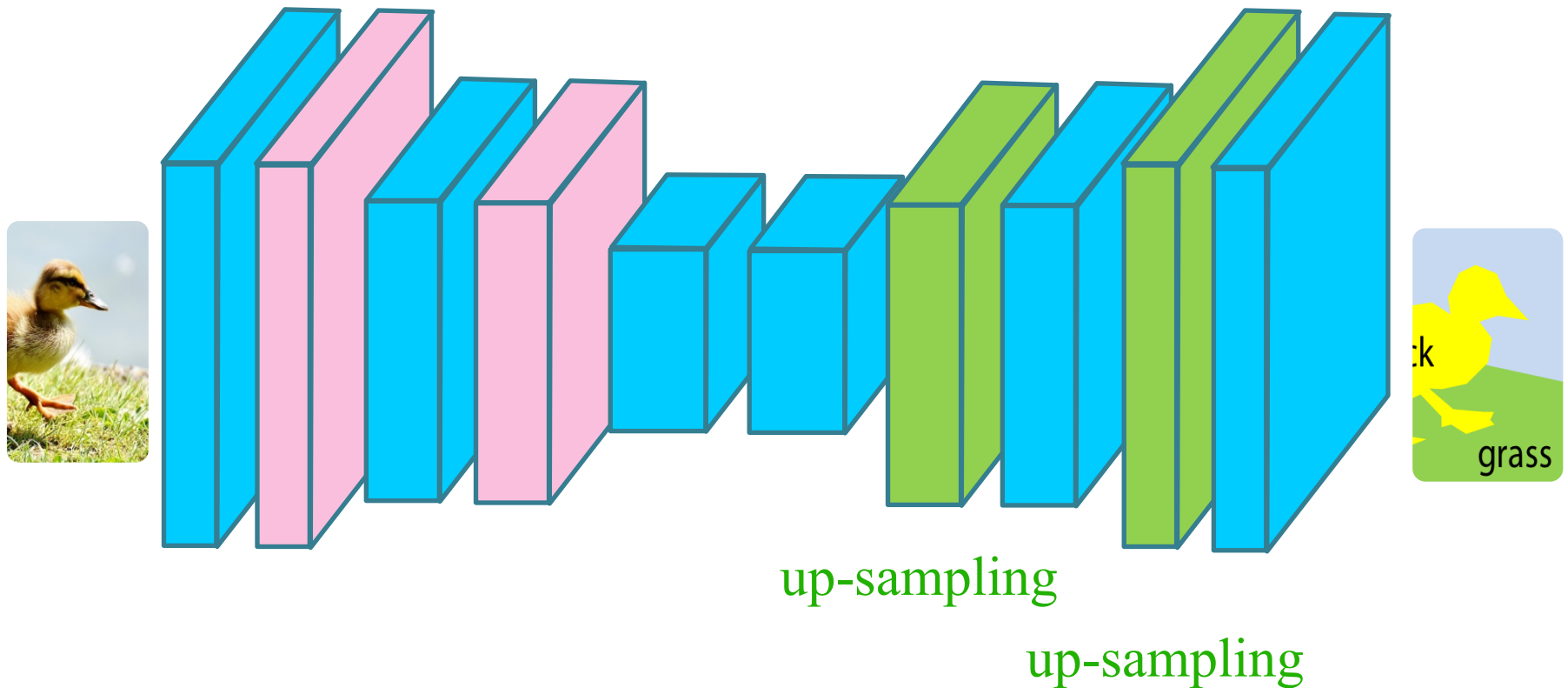
Wait a second!
We need to classify
each pixel!

Need to do **unpooling**!

Yes. so we do the
'reverse'. Upsampling.

Semantic segmentation

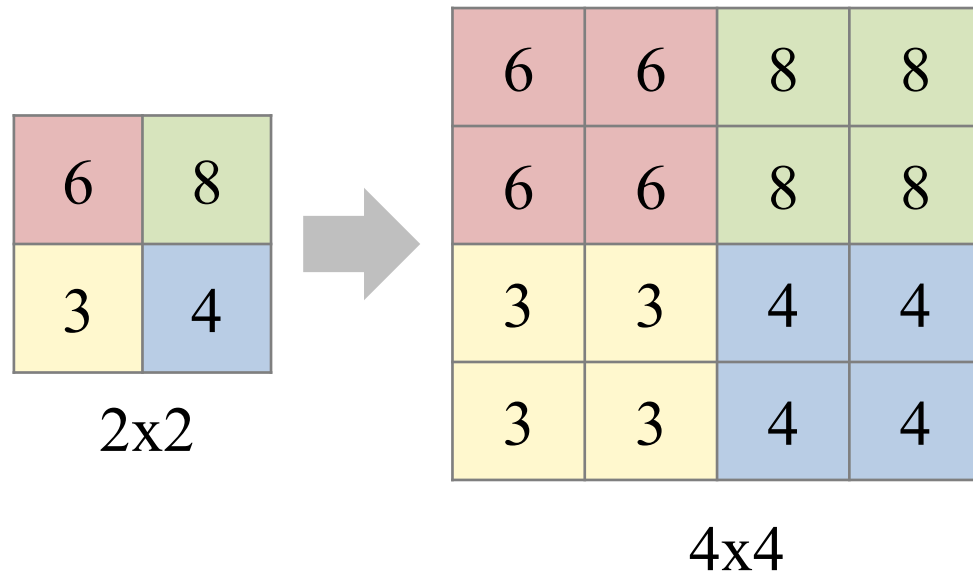
Let's add pooling, which acts like **down-sampling**



But how do we do up-sampling?

Nearest neighbor unpooling

Fill with nearest neighbor values

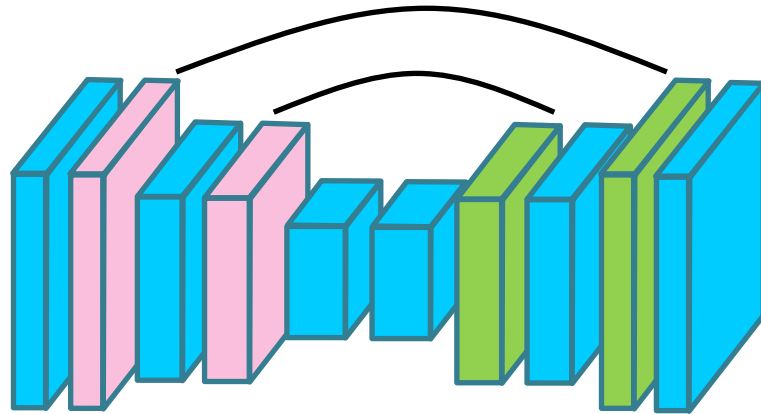


Pixelated and not crisp!

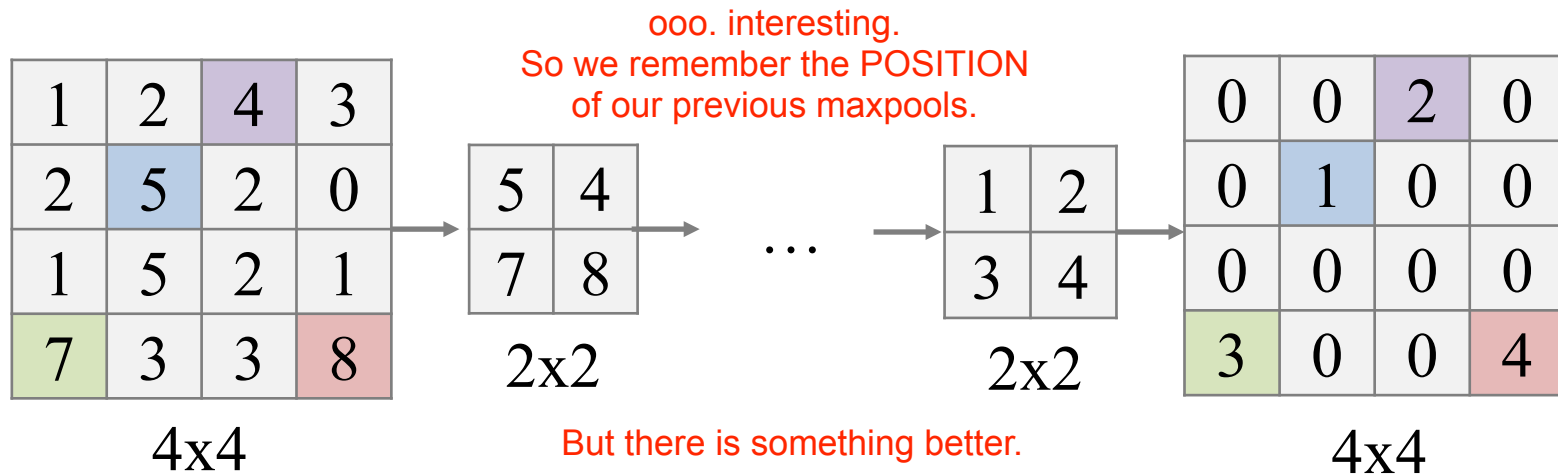
Can't just use this.

Max unpooling

Corresponding pairs of
downsampling and
upsampling layers



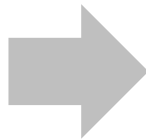
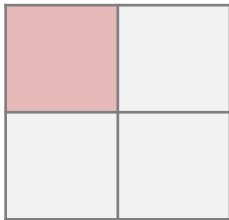
Remember which element was max during pooling, and fill that position during unpooling:



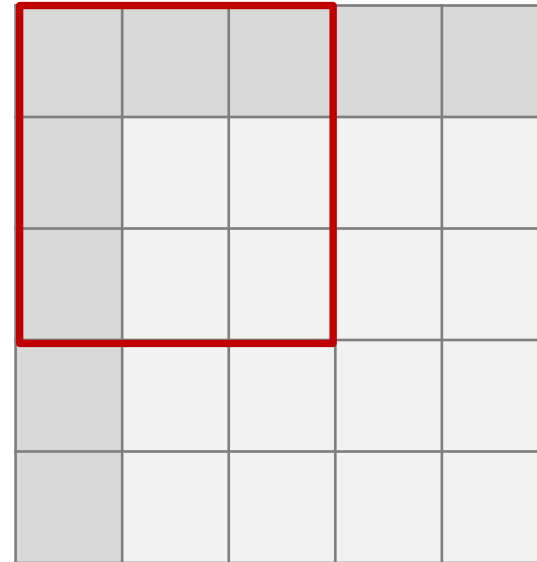
Learnable unpooling

- Previous approaches are not data-driven!
- We can replace max pooling layer with convolutional layer that has a bigger stride!
- What if we can apply convolutions to do unpooling?

Input: 2x2



Input gives
weight for
filter



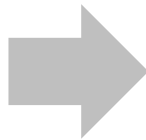
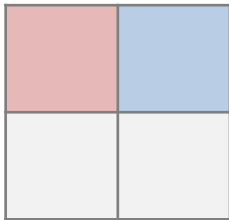
Output: 4x4

The step is to take the value from the red input cell, and then multiply it with the kernel's values to give the output in the red outlined box in the output 4x4.

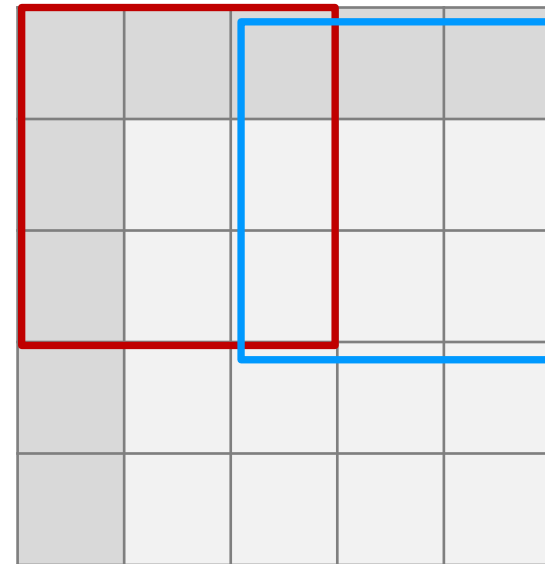
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Stride: 2

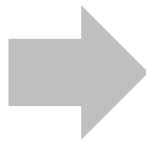
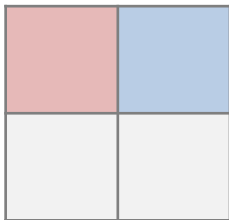
Output: 4x4

We multiply blue input cell value with the same kernel for the blue outline box in 4x4 output.

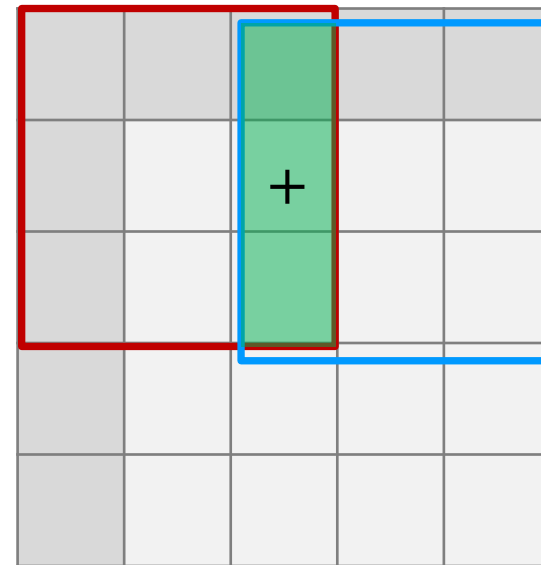
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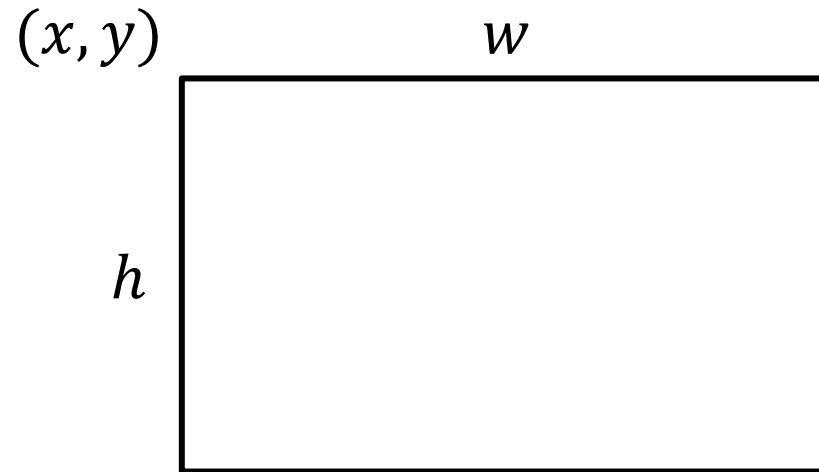
For overlaps, just take sum.

Output: 4x4

This is called TRANSPOSED convolution. It's not the best idea actually, see <https://distill.pub/2016/deconv-checkerboard/>

Object classification + localization

We need to find a bounding box to localize an object.

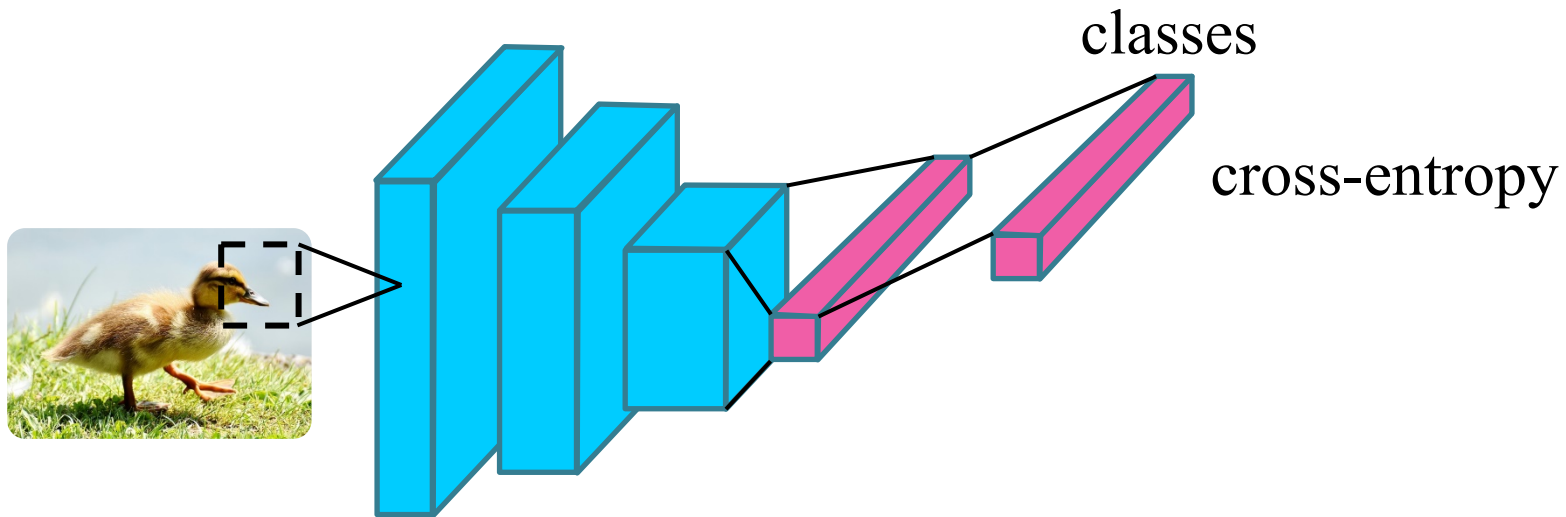


We will use regression for (x, y, w, h) !

(x, y) is the coordinate of the upper left corner of box.
 w, h is width and height.

Object classification + localization

Classification network:

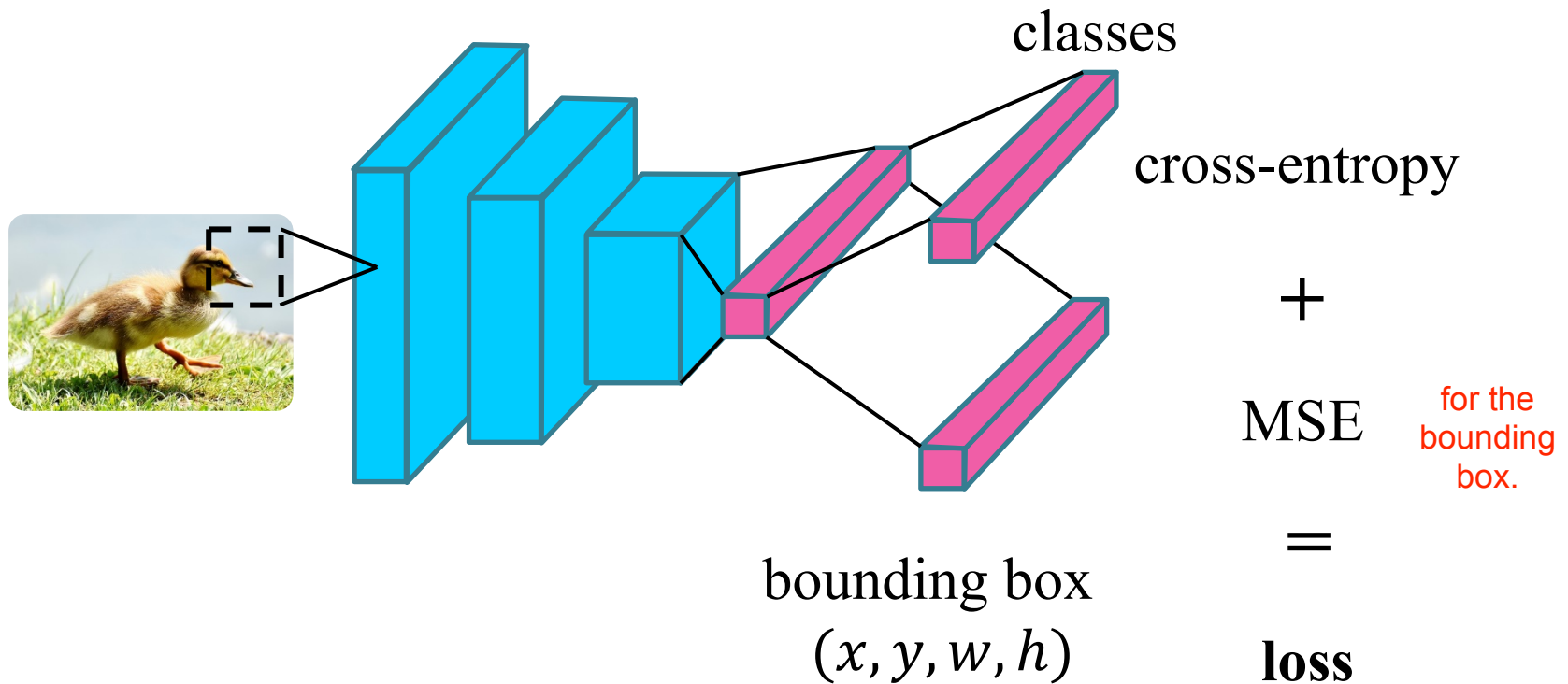


Do we need a second network?

No! Just use the same feature extractors, and train a smaller network on top of it.

Object classification + localization

Classification + localization network:



Summary

- In this video we took a sneak peek into other computer vision problems that successfully utilize convolutional neural networks.
- This video concludes our introduction to neural networks for images!