

Exploding and vanishing gradients

Problem statement

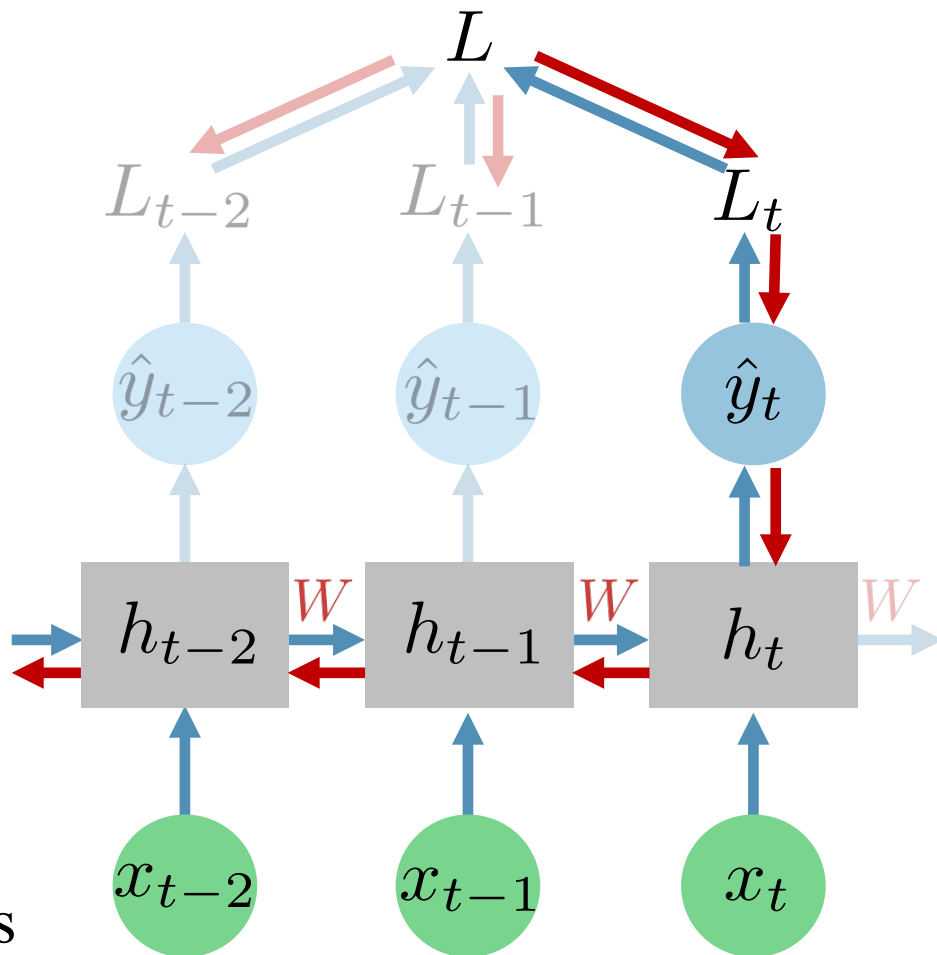
Previously on this week: BPTT

To train an RNN we need to backpropagate through layers and time

$$\frac{\partial L}{\partial W} = \sum_{i=0}^T \frac{\partial L_i}{\partial W}$$

$$\frac{\partial L_t}{\partial W} \propto \sum_{k=0}^t \left(\prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}} \right) \frac{\partial h_k}{\partial W}$$

Contribution of a state at time step k to the gradient of the loss at time step t



Let's look at the gradient

$$\frac{\partial L_t}{\partial W} \propto \sum_{k=0}^t \left(\prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}} \right) \frac{\partial h_k}{\partial W}$$

These are jacobian matrices.

The more steps between the time moments k and t , the more elements are in this product



Values of these Jacobian matrices have particularly severe impact on the contributions from faraway steps

Let's look at the gradient

$$\frac{\partial L_t}{\partial W} \propto \sum_{k=0}^t \left(\prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}} \right) \frac{\partial h_k}{\partial W}$$

Let's suppose for a moment that h_i is a scalar and consequently $\frac{\partial h_i}{\partial h_{i-1}}$ is also a scalar

$$\left| \frac{\partial h_i}{\partial h_{i-1}} \right| < 1 \quad \longrightarrow$$

The product goes to 0 exponentially fast

$$\left| \frac{\partial h_i}{\partial h_{i-1}} \right| > 1 \quad \longrightarrow$$

The product goes to infinity exponentially fast

Let's look at the gradient

$$\frac{\partial L_t}{\partial W} \propto \sum_{k=0}^t \left(\prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}} \right) \frac{\partial h_k}{\partial W}$$

Let's suppose for a moment that h_i is a scalar and consequently $\frac{\partial h_i}{\partial h_{i-1}}$ is also a scalar

Vanishing gradients

$$\left| \frac{\partial h_i}{\partial h_{i-1}} \right| < 1 \quad \longrightarrow$$

- contributions from faraway steps vanish and don't affect the training
- difficult to learn long-range dependencies

Let's look at the gradient

$$\frac{\partial L_t}{\partial W} \propto \sum_{k=0}^t \left(\prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}} \right) \frac{\partial h_k}{\partial W}$$

Let's suppose for a moment that h_i is a scalar and
consequently $\frac{\partial h_i}{\partial h_{i-1}}$ is also a scalar

Exploding gradients

$$\left| \frac{\partial h_i}{\partial h_{i-1}} \right| > 1 \quad \longrightarrow$$

- make the learning process unstable
- gradient could even become a NaN

Let's look at the gradient

$$\frac{\partial L_t}{\partial W} \propto \sum_{k=0}^t \left(\prod_{i=k+1}^t \frac{\partial h_i}{\partial h_{i-1}} \right) \frac{\partial h_k}{\partial W}$$

The same is true for matrices but with the spectral matrix norm instead of the absolute value:

The spectral norm is the maximum singular value of a matrix (presumably, in its singular value decomposition). Intuitively, you can think of it as the maximum 'scale', by which the matrix can 'STRETCH' a vector.

See <http://ee263.stanford.edu/lectures/svd-v2.pdf> for more details.

$$\left\| \frac{\partial h_i}{\partial h_{i-1}} \right\|_2 < 1 \quad \longrightarrow$$

The product goes to zero-norm matrix exponentially fast

$$\left\| \frac{\partial h_i}{\partial h_{i-1}} \right\|_2 > 1 \quad \longrightarrow$$

The product goes to a matrix of infinite norm exponentially fast

Is it really a problem in practice?

$$h_t = f_h(Vx_t + Wh_{t-1} + b_h) = f_h(pr_t)$$

$$\frac{\partial h_t}{\partial h_{t-1}} = \frac{\partial h_t}{\partial pr_t} \frac{\partial pr_t}{\partial h_{t-1}} = \text{diag}(f'_h(pr_t)) \cdot ?$$

$\text{diag}(f'_h(pr_t))$ basically means:

We have a diagonal matrix where each diagonal entry
is a partial derivative w.r.t pr_t

Is it really a problem in practice?

$$h_t = f_h(Vx_t + Wh_{t-1} + b_h) = f_h(pr_t)$$

$d pr_t / d h_{t-1} = W$. See equation above:

$$\frac{\partial h_t}{\partial h_{t-1}} = \frac{\partial h_t}{\partial pr_t} \frac{\partial pr_t}{\partial h_{t-1}} = \text{diag}(f'_h(pr_t)) \cdot W$$

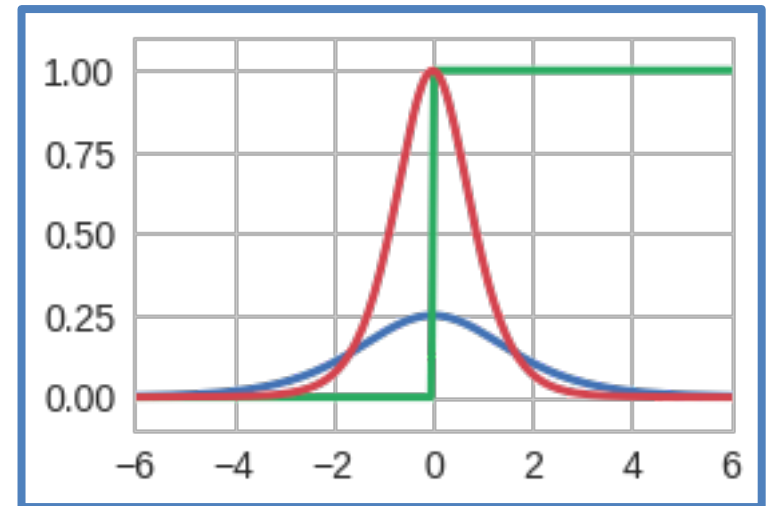
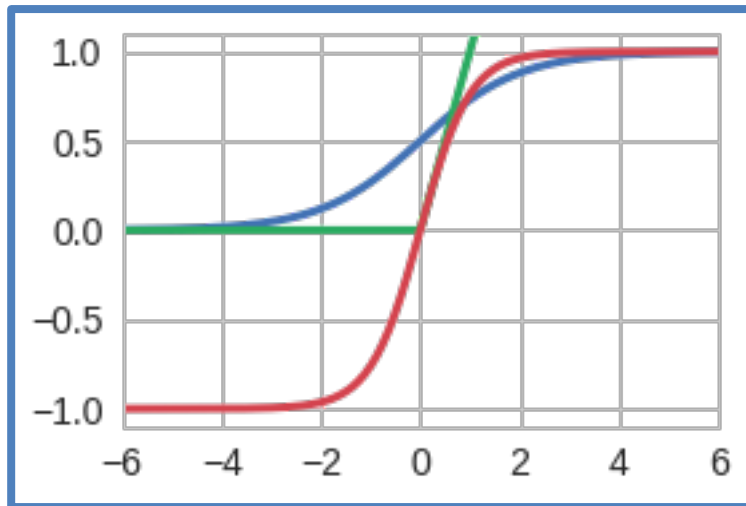
Is it really a problem in practice?

$$h_t = f_h(Vx_t + Wh_{t-1} + b_h) = f_h(pr_t)$$

$$\frac{\partial h_t}{\partial h_{t-1}} = \frac{\partial h_t}{\partial pr_t} \frac{\partial pr_t}{\partial h_{t-1}} = \boxed{\text{diag}(f'_h(pr_t))} \cdot W$$

sigmoid, tanh, ReLU ReLU may still vanish if
always negative.

Derivatives



Vanishing gradients are very likely especially with
sigmoid and tanh

Yes. This is because their gradients have limit to 0 on both $-\infty$ and ∞ .

Is it really a problem in practice?

$$h_t = f_h(Vx_t + Wh_{t-1} + b_h) = f_h(pr_t)$$

$$\frac{\partial h_t}{\partial h_{t-1}} = \frac{\partial h_t}{\partial pr_t} \frac{\partial pr_t}{\partial h_{t-1}} = \text{diag}(f'_h(pr_t)) \cdot \boxed{W}$$

$\|W\|$ may be either **small** or **large**



Small $\|W\|$ could aggravate
the vanishing gradient
problem

Question: What is the use of the
spectral norm?



Large $\|W\|$ could cause
exploding gradients
(especially with ReLU)

Summary

- In practice vanishing and exploding gradients are common for RNNs. These problems also occur in deep Feedforward NNs.
- Vanishing gradients make the learning of long-range dependencies very difficult.
- Exploding gradients make the learning process very unstable and may even crash it.

In the next video:

How to deal with these issues?