Intro

 In this video we will learn how to compute the gradients for MLP automatically.

Chain rule

We know derivatives for simple functions:

$$\frac{dx^2}{dx} = 2x \qquad \frac{de^x}{dx} = e^x \qquad \frac{d\ln(x)}{dx} = \frac{1}{x}$$

Let's take a composite function:

$$z_1=z_1(x_1,x_2)$$

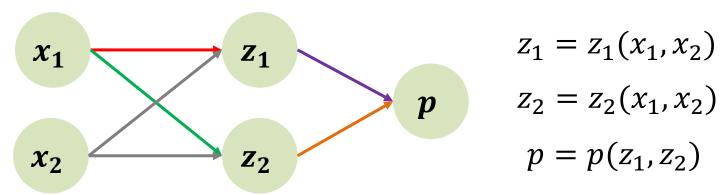
$$z_2=z_2(x_1,x_2)$$
 where z_1,z_2,p are differentiable
$$p=p(z_1,z_2)$$

Chain rule:
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$

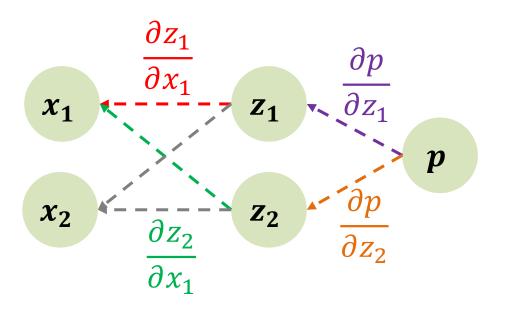
Example for h(x) = f(x)g(x):

$$\frac{\partial h}{\partial x} = \frac{\partial h}{\partial f} \frac{\partial f}{\partial x} + \frac{\partial h}{\partial g} \frac{\partial g}{\partial x} = g \frac{\partial f}{\partial x} + f \frac{\partial g}{\partial x}$$

Let's take our simple computation graph:

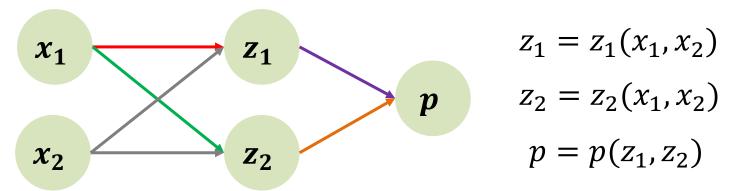


And construct a new graph of derivatives:

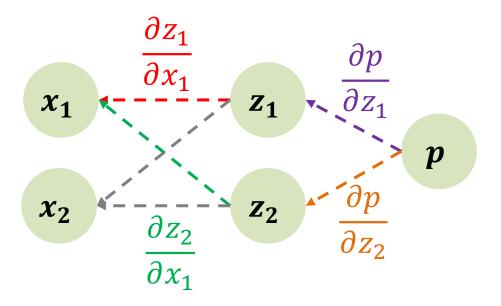


Each edge is assigned to derivative of origin w.r.t. destination

Let's take our simple computation graph:



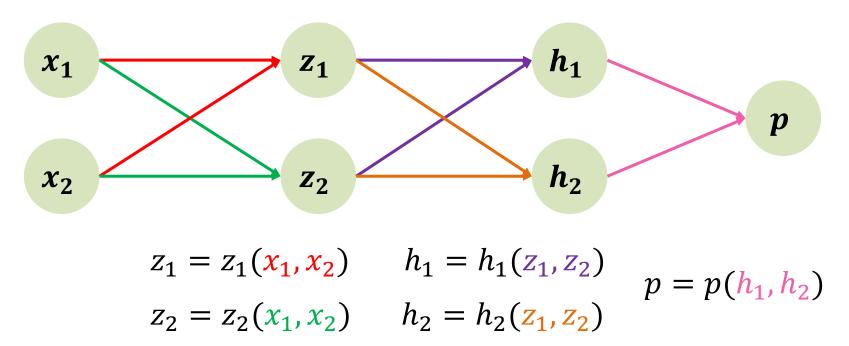
And construct a new graph of derivatives:



$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$

You can see how a **chain rule** works

• A little bit more composite function:



Chain rule:
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial x_1}$$

Chain rule:
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial x_1}$$

$$\frac{\partial h_1}{\partial x_1} = \frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial h_1}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$

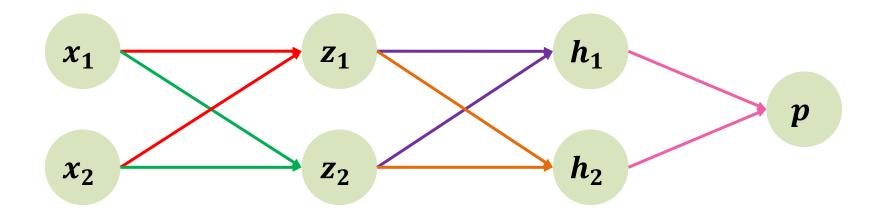
$$\frac{\partial h_2}{\partial x_1} = \frac{\partial h_2}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$

Chain rule:
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial x_1}$$
these are all the possible ways to get from h1 to x1. >>>
$$\frac{\partial p}{\partial x_1} = \frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial h_1}{\partial z_2} \frac{\partial z_2}{\partial x_1} + \frac{\partial h_2}{\partial z_2} \frac{\partial z_1}{\partial x_1} + \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$

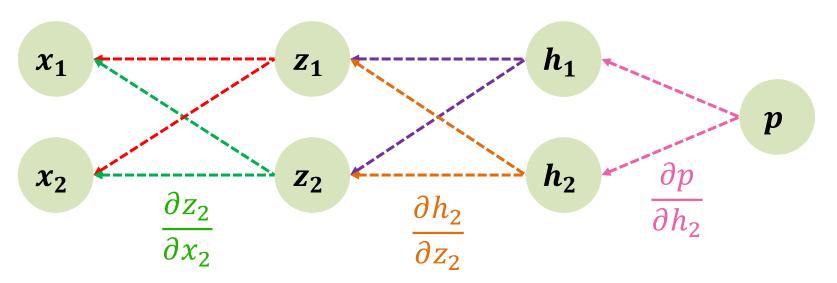
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \left(\frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial h_1}{\partial z_2} \frac{\partial z_2}{\partial x_1} \right) + \frac{\partial p}{\partial h_2} \left(\frac{\partial h_2}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial x_1} \right)$$

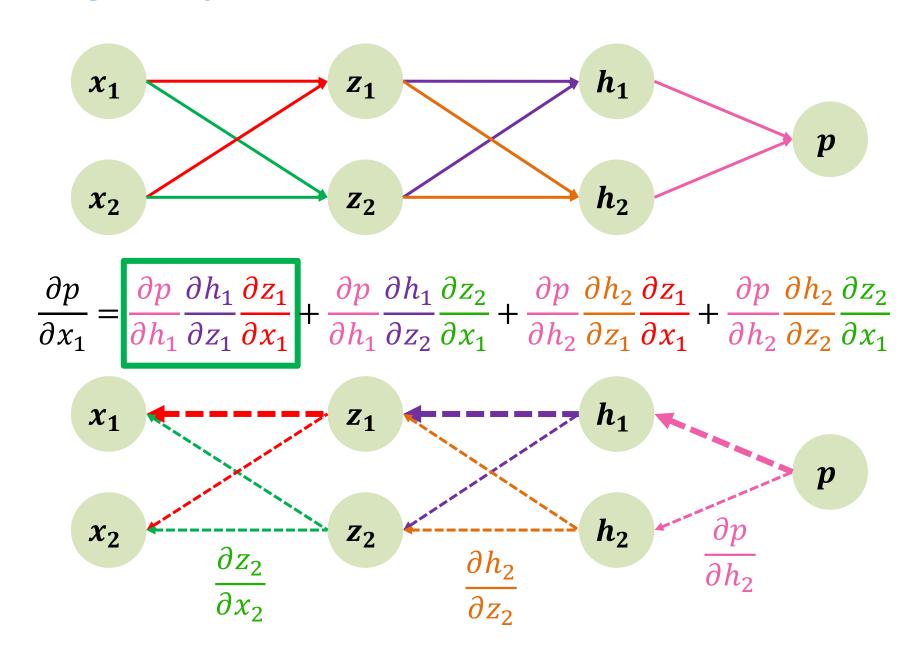
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial z_2} \frac{\partial z_2}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$

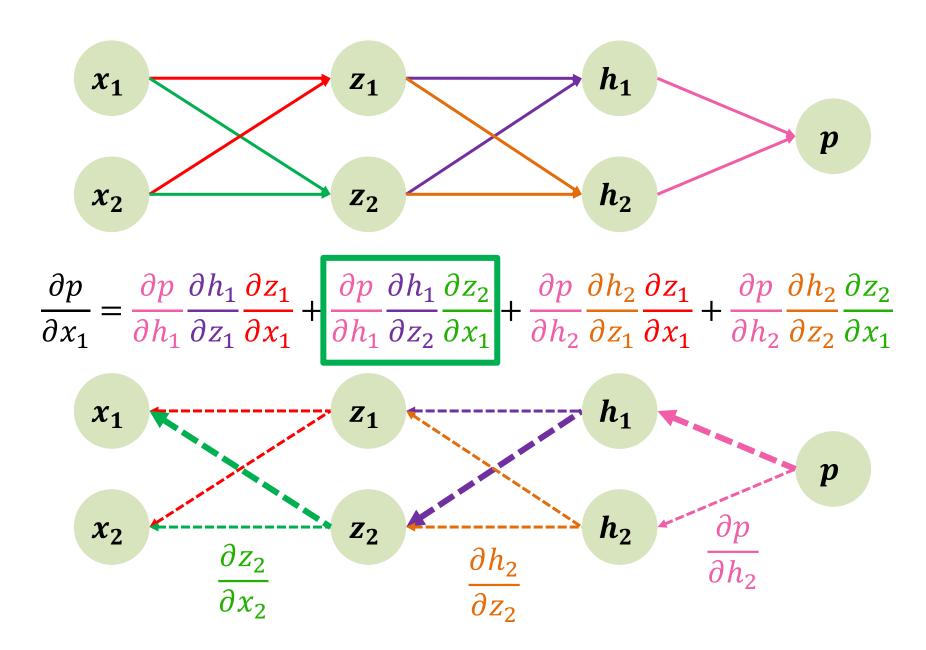
Let's check out the derivatives graph!

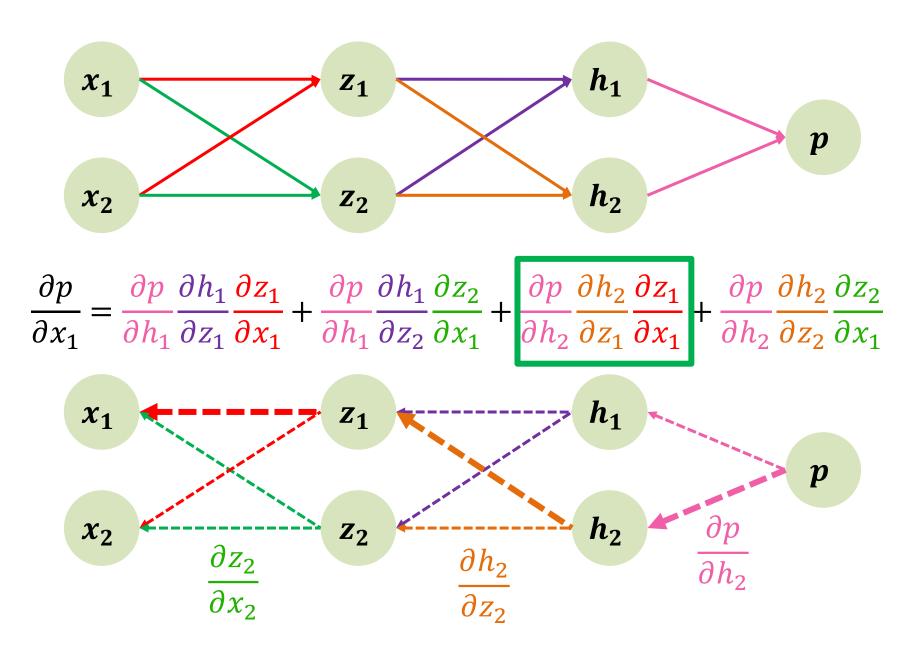


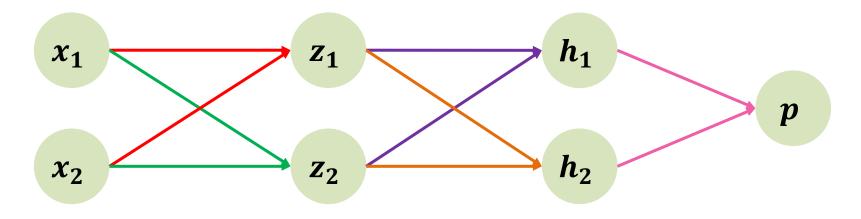
$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial z_2} \frac{\partial z_2}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$



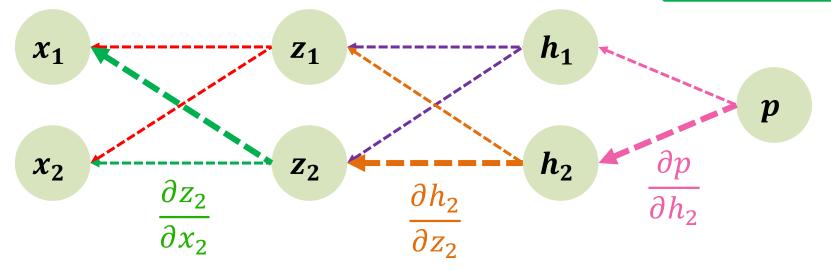








$$\frac{\partial p}{\partial x_1} = \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial h_1} \frac{\partial h_1}{\partial z_2} \frac{\partial z_2}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial z_1} \frac{\partial z_1}{\partial x_1} + \frac{\partial p}{\partial h_2} \frac{\partial h_2}{\partial z_2} \frac{\partial z_2}{\partial x_1}$$



How this graph of derivatives helps

$$x_{1} = \frac{\partial z_{1}}{\partial x_{1}}$$

$$x_{2} = \frac{\partial z_{1}}{\partial z_{1}}$$

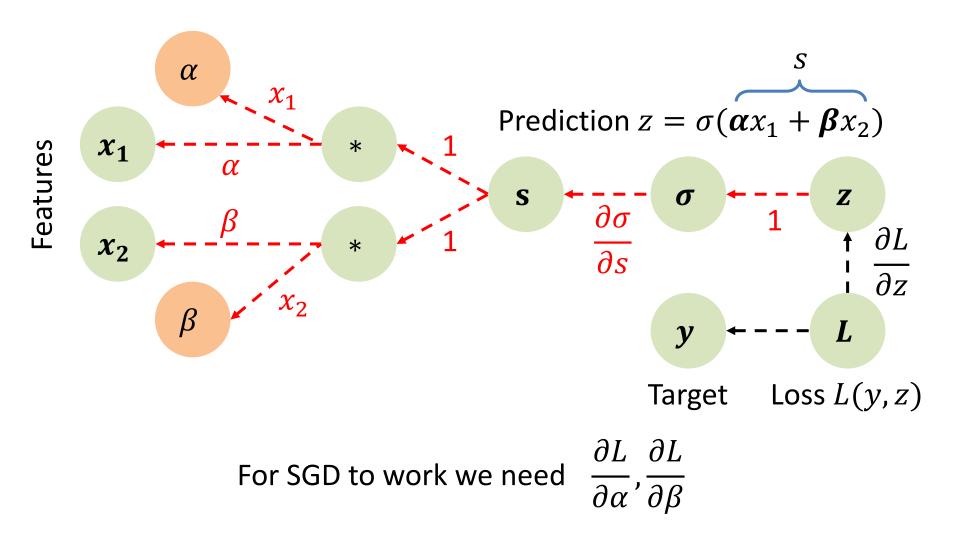
$$x_{2} = \frac{\partial z_{1}}{\partial z_{1}}$$

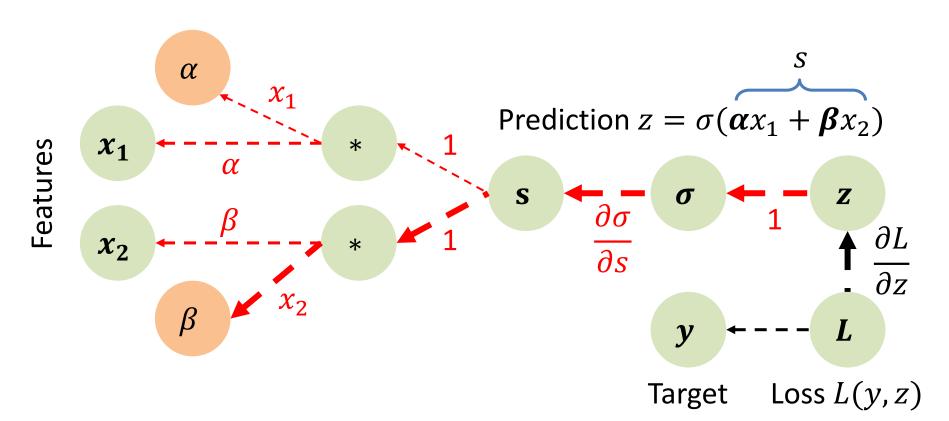
$$\frac{\partial z_{1}}{\partial z_{2}}$$

$$\frac{\partial z_{2}}{\partial z_{1}}$$

How to calculate a derivative of node a w.r.t. node b:

- Find an unvisited path from a to b
- Multiply all edge values along this path
- Add to the resulting derivative





$$\frac{\partial L}{\partial \alpha} = \frac{\partial L}{\partial z} \frac{\partial \sigma}{\partial s} x_1 \qquad \qquad \frac{\partial L}{\partial \beta} = \frac{\partial L}{\partial z} \frac{\partial \sigma}{\partial s} x_2 \qquad \qquad x_1 = \frac{1 = \frac{1}{2} - \frac{1}{2} -$$

 ∂L ∂L NOTE: z is basically sigma. See

the '1' above. so dsigma / ds = dz / ds

Summary

We can use chain rule to compute derivatives of composite functions

 We can use a computation graph of derivatives to compute them automatically

In the next video we will find out how to do this fast!