

# Action-based Milky Way Disk Modelling with *RoadMapping* and our imperfect Knowledge of the "Real World"

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## 0.1. Effect of measurement errors on recovery of potential?

[TO DO]

Collection tests and plots (tests are still running on the cluster)

- *Plot 1*: number of MC samples needed for the error convolution vs. maximum velocity error inside the observed volume, such that a given accuracy in potential and qDF parameters is reached. Similar to what I had on the poster. However, we still haven't tested, if this plot depends on: hotness of stars and or umber of stars.
- *Plot 2*: 2 columns of panels (one row for each parameter), bias vs. standard error. First column: only proper motion and vlos errors → shows that our error convolution works and should be bias free, plus, when knowing the errors perfectly we can get a perfect deconvolution and tight constraints. Second column: proper motion, vlos and distance modulus errors → shows that for too large proper motion and distance errors our approximation for the error convolution does not work anymore.

**Underestimation of the proper motion error.** We found that in case we perfectly knew the measurement errors (and the distance error is negligible), we can deconvolve the likelihood with the measurement errors and get precise and accurate constraints on the parameters - even if the error itself is quite large. Now we investigate what would happen if the quoted measurement errors, e.g. the proper motion errors, were actually smaller than

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the true errors. Figure 3 shows the case for two different stellar populations and an error underestimation of 10% and 50%.

Overall the parameter recovery gets worse the larger the proper motion error and the stronger the underestimation. The relation between the bias due to error misjudgment and the size of the proper motion error seems to be linear.

For the recovery of the isochrone potential scale length  $b$  the hotness of the population does not matter (see lower left panel in Figure 3). The circular velocity  $v_{\text{circ}}(R_{\odot})$  is, as always, better measured by cooler than by hotter populations (see upper left panel in Figure 3).

We find that the recovery of the qDF parameters on the other hand is more strongly affected by the misjudgment of the velocity error for *cooler* stellar populations. The measured velocity dispersion is the convolution of the intrinsic dispersion with the measurement errors. If the proper motion error is underestimated, the deconvolved velocity dispersion is larger than the intrinsic velocity dispersion and the relative difference is bigger for a cooler population (see upper right panel for  $\sigma_z$  in Figure 3). The intrinsic velocity dispersion is also cooler at larger radii than at smaller radii, therefore the deconvolved dispersion is overestimated more strongly at large  $R$  and the velocity dispersion scale length will be overestimated as well (see lower left panel for  $h_{\sigma_z}$  in Figure 3). We get analogous results for the qDF parameters  $\sigma_R$  and  $h_{\sigma_R}$ . The recovery of the tracer density scale length  $h_R$  is not affected by the misjudgment of velocity errors.

The most important and encouraging result from Figure 3 is, that for an underestimation of 10% the bias is still  $\lesssim 2\sigma$  - even for proper motion errors of 3 mas/yr.

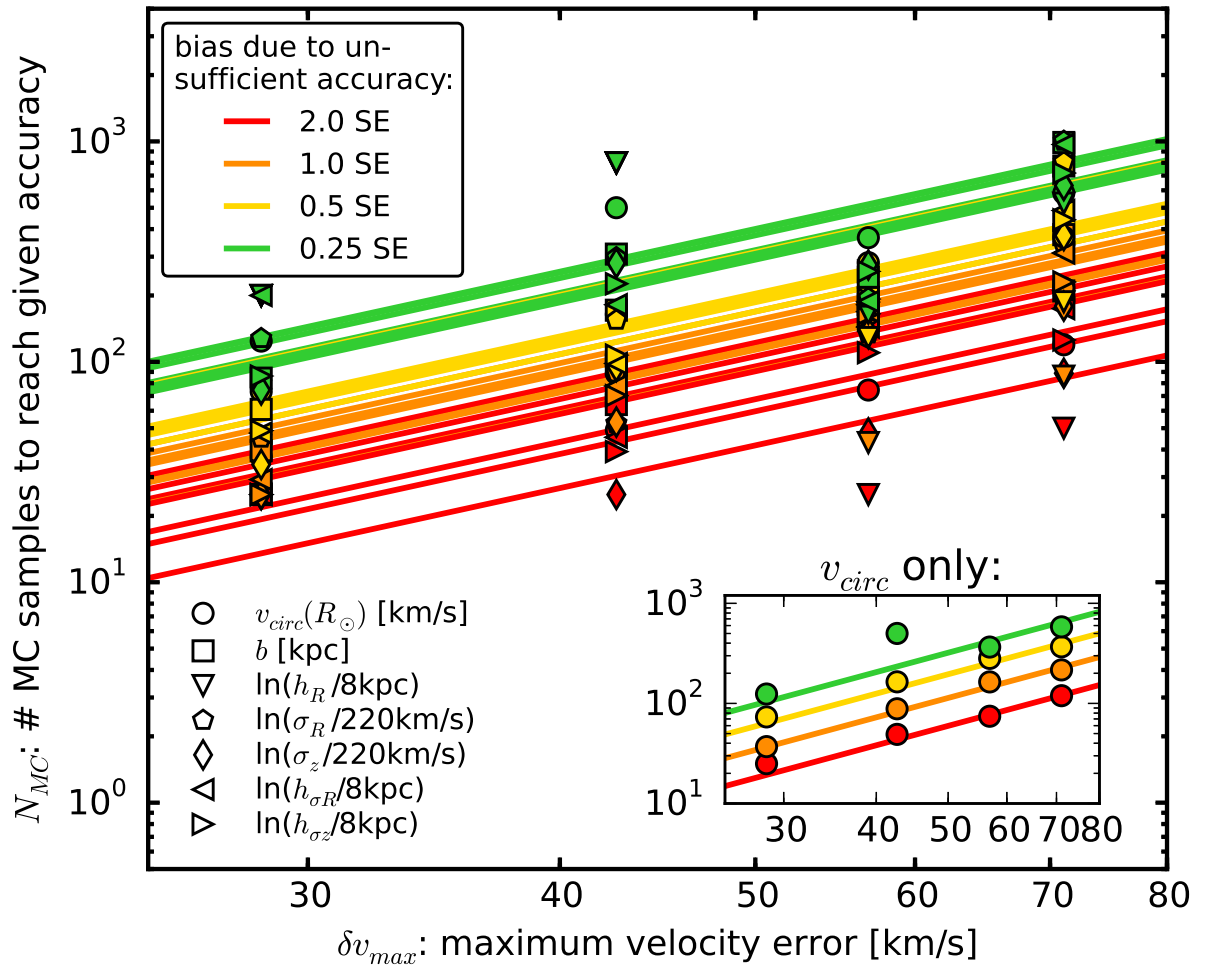


Fig. 1.— [TO DO: Caption]

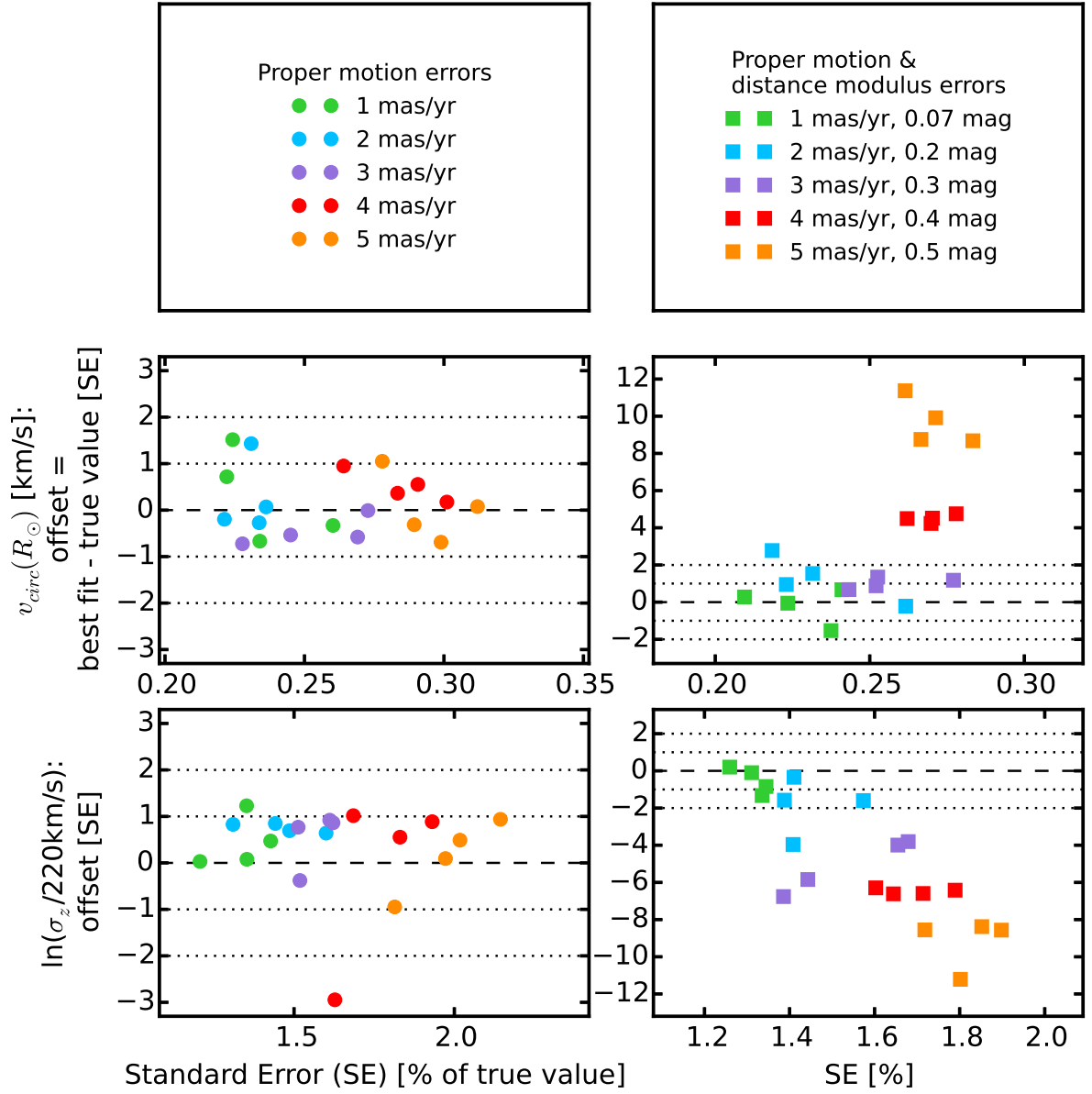


Fig. 2.— [TO DO: Caption]

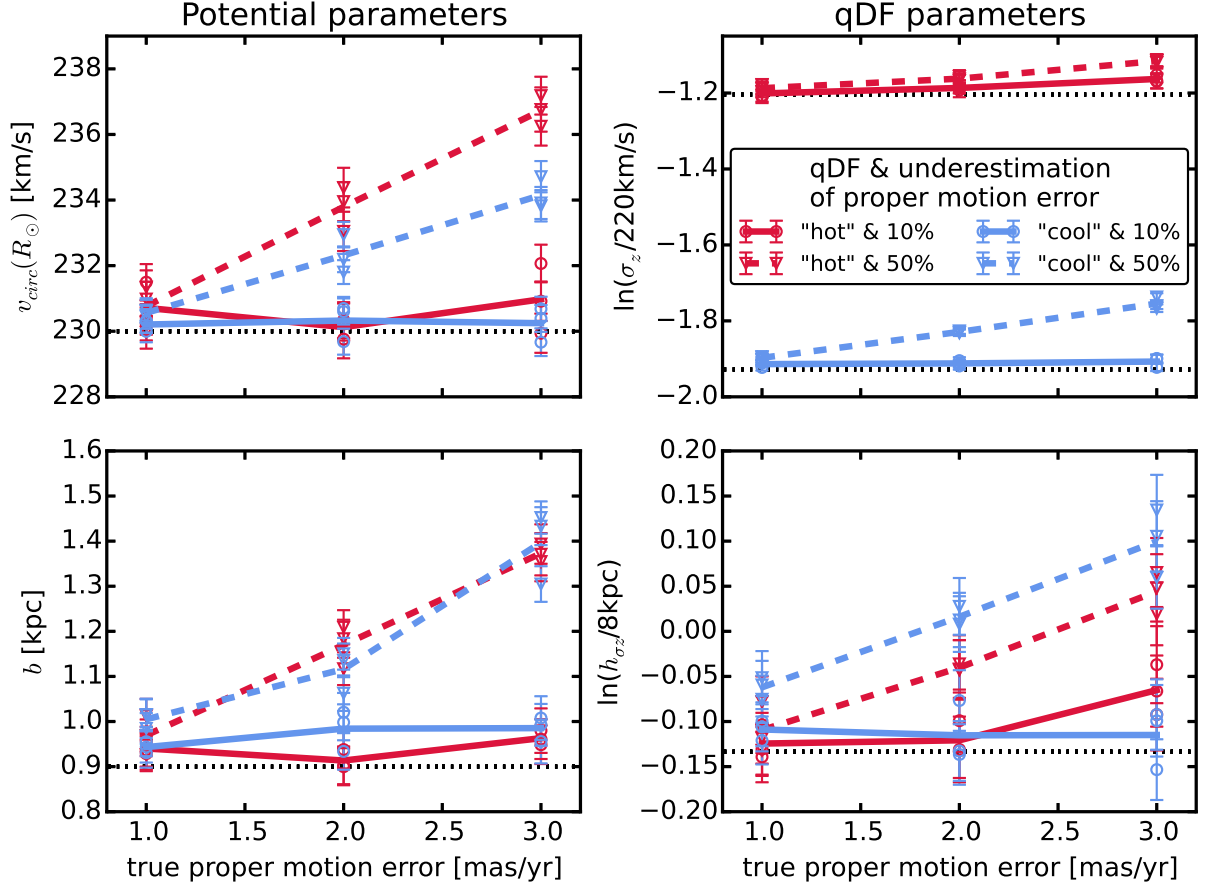


Fig. 3.— Effect of an systematic underestimation of proper motion errors in the recovery of the model parameters. The true model parameters used to create the mock data are summarized as Test ① in Table 3, four of them are given on the  $y$ -axes and the true values are indicated as black dashed lines. The velocities of the mock data were perturbed according to Gaussian errors in the  $\alpha$  and  $\delta$  proper motions as indicated on the  $x$ -axis. The circles and triangles are the best fit parameters of several mock data set assuming the proper motion error, with which the likelihood was convolved, was underestimated in the analysis by 10% or 50%, respectively. The error bars correspond to  $1\sigma$  confidence. The lines connect the mean of each two data realisations and are just guides to the eyes.

Table 1. Gravitational potentials of the reference galaxies used throughout this work and the respective ways to calculate actions in these potentials. All four potentials are axisymmetric. The potential parameters are fixed for the mock data creation at the values given in this table. In the subsequent analyses we aim to recover these potential parameters again. The parameters of "MW13-Pot" and "KKS-Pot" were found as direct fits to the "MW14-Pot".

name	potential type	potential parameters $p_\Phi$		action calculation	reference for potential type
"Iso-Pot"	isochrone potential	circular velocity at the sun isochrone scale length	$v_{\text{circ}} = 230 \text{ km s}^{-1}$ $b = 0.9 \text{ kpc}$	<i>analytical and exact</i> $J_r, J_\vartheta, L_z$ ; ? use $J_r \rightarrow J_R, J_\vartheta \rightarrow J_z$ in Eq. (??)	
"KKS-Pot"	2-component Kuzmin-Kutuzov- Stäckel potential (disk + halo)  (analytic potential)	circular velocity at the sun focal distance of coordinate system <sup>a</sup> axis ratio of the coordinate surfaces <sup>a</sup> ... ...of the disk component ...of the halo component relative contribution of the disk mass to the total mass	$v_{\text{circ}} = 230 \text{ km s}^{-1}$ $\Delta = 0.3$  $\left(\frac{a}{c}\right)_{\text{Disk}} = 20$ $\left(\frac{a}{c}\right)_{\text{Halo}} = 1.07$  $k = 0.28$	<i>exact</i> $J_R, J_z, L_z$ using "Stäckel Fudge" (?) and interpolation on action grid <sup>b</sup> (?)	?
"MW13-Pot"	MW-like potential with Hernquist bulge, 2 exponential disks (stars + gas), spherical power-law halo (interpolated potential)	circular velocity at the sun stellar disk scale length stellar disk scale height relative halo contribution to $v_{\text{circ}}^2(R_\odot)$ "flatness" of rotation curve	$v_{\text{circ}} = 230 \text{ km s}^{-1}$ $R_d = 3 \text{ kpc}$ $z_h = 0.4 \text{ kpc}$ $f_h = 0.5$ $\frac{d \ln(v_{\text{circ}}(R_\odot))}{d \ln(R)} = 0$	<i>approximate</i> $J_R, J_z, L_z$ using "Stäckel Fudge" (?) and interpolation on action grid <sup>a</sup> (?)	?
"MW14-Pot"	MW-like potential with cut-off power-law bulge, Miyamoto-Nagai stellar disk, NFW halo	-	-	<i>approximate</i> $J_R, J_z, L_z$ (see "MW13-Pot")	?

<sup>a</sup>The coordinate system of each of the two Stäckel-potential components is  $\frac{R^2}{\tau_{i,p} + \alpha_p} + \frac{z^2}{\tau_{i,p} + \gamma_p} = 1$  with  $p \in \{\text{Disk}, / \text{Halo}\}$  and  $\tau_{i,p} \in \{\lambda_p, \nu_p\}$ . Both components have the same focal distance  $\Delta = \sqrt{\gamma_p - \alpha_p}$ , to make sure that the superposition of the two components itself is still a Stäckel potential. The axis ratio of the coordinate surfaces  $\left(\frac{a}{c}\right)_p := \sqrt{\frac{\alpha_p}{\gamma_p}}$  describes the flatness of the corresponding Stäckel component.

<sup>b</sup>We use a finely spaced action interpolation grid with  $R_{\text{max}} = 10$  [TO DO: What's that??? units???] and 50 grid points in  $E$  and  $\psi$  [TO DO: Find out what's that???], and 60 grid points in  $L_z$ . [TO DO: more details?]

Table 2. Reference distribution function parameters for the qDF in eq. (??)-(??). These qDFs describe the phase-space distribution of stellar *MAPs* for which mock data is created and analysed throughout this work for testing purposes. The parameters of the "cooler" & "colder" ("hotter" & "warmer") *MAPs* were chosen such, that the they have the same  $\sigma_R/\sigma_z$  ratio as the "hot" ("cool") *MAP* . The "colder" and "warmer" *MAPs* have a free parameter  $X$  that governs how much colder/warmer they are then the reference "hot" and "cool" qDFs. Hotter populations have shorter tracer scale lengths (?) and the velocity dispersion scale lengths were fixed according to ?.

name of <i>MAP</i>	qDF parameters $p_{\text{DF}}$				
	$h_R$ [kpc]	$\sigma_R$ [km s <sup>-1</sup> ]	$\sigma_z$ [km s <sup>-1</sup> ]	$h_{\sigma_R}$ [kpc]	$h_{\sigma_z}$ [kpc]
"hot"	2	55	66	8	7
"cool"	3.5	42	32	8	7
"cooler"	2 +50%	55-50%	66-50%	8	7
"hotter"	3.5-50%	42+50%	32+50%	8	7
"colder"	2 +X%	55-X%	66-X%	8	7
"warmer"	3.5-X%	42+X%	32+X%	8	7

Table 3. Summary of test suites in this work: The first column indicates the test suite, the second column the potential, DF and selection function model etc. used for the mock data creation, the third model the corresponding model assumed in the analysis, and the last column lists the figures belonging to the test suite. Parameters that are not left free in the analysis, are always fixed to their true value. Unless otherwise stated we calculate the likelihood by the nested-grid and MCMC approach outlined in §?? and use  $N_{\text{spatial}} = 16$ ,  $N_{\text{velocity}} = 24$ ,  $N_{\text{sigma}} = 5$  as numerical accuracy for the likelihood normalisation in Eq. (??) and (??). [TO DO: Change encircled numbers to proper order.

Make sure the plot references are the right ones.]

Test	Model for Mock Data		Model in Analysis	Figures
① Influence of survey volume on mock data distribution, also in action space	<i>Potential:</i> <i>MAP :</i> <i>Survey volume:</i> <i># stars per data set:</i> <i># data sets:</i>	"KKS-Pot" 2 MAPs "hot" or "cold" qDF a) $R \in [4, 12]$ kpc, $z \in [-4, 4]$ kpc, $\phi \in [-20^\circ, 20^\circ]$ . b) $R \in [6, 10]$ kpc, $z \in [1, 5]$ kpc, $\phi \in [-20^\circ, 20^\circ]$ . 20,000 4 (= $2 \times 2$ models)	-	Mock data: Fig. ??
⑨ Numerical accuracy in calculation of the likelihood normalisation	<i>Potential:</i> <i>MAP :</i> <i>Survey volume:</i> <i>Numerical accuracy:</i>	"Iso-Pot", "MW13-Pot" & "KKS-Pot" "hot" qDF sphere around sun, $r_{\text{max}} = 0.2, 1, 2, 3$ or 4 kpc $N_{\text{spatial}} \in [5, 20]$ , $N_{\text{velocity}} \in [6, 40]$ , $N_{\text{sigma}} \in [3.5, 7]$	-	Convergence of normalisation:   Fig. ?? $\infty$ 
⑩ <i>pdf</i> is a multivariate Gaussian for large data sets.	<i>Potential:</i> <i>MAP :</i> <i>Survey Volume:</i> <i># stars per data set:</i> <i># data sets:</i> <i>Numerical accuracy:</i>	"Iso-Pot" "hot" qDF sphere around sun, $r_{\text{max}} = 2$ kpc 20,000 5 (only one is shown)	"Iso-Pot", all parameters free qDF, all parameters free (fixed & known)  $N_{\text{velocity}} = 20$ and $N_{\text{sigma}} = 4$	Fig. ??
② Width of the likelihood scales with number of stars by $\propto 1/\sqrt{N}$ .	<i>Potential:</i> <i>MAP :</i>  <i>Survey volume:</i> <i># stars per data set:</i> <i># data sets:</i> <i>Analysis method:</i> <i>Numerical accuracy:</i>	"Iso-Pot" "hot" qDF  sphere around sun, $r_{\text{max}} = 3$ kpc between 100 and 40,000 132  likelihood on grid $N_{\text{velocity}} = 20$ and $N_{\text{sigma}} = 4$ (for speed)	"Iso-Pot", free parameter: $b$ "hot" qDF, free parameters: $\ln\left(\frac{h_R}{8\text{kpc}}\right), \ln\left(\frac{\sigma_R}{230\text{km s}^{-1}}\right), \ln\left(\frac{h_{\sigma,R}}{8\text{kpc}}\right)$ (fixed & known)	Fig. ??
③ Parameter estimates are unbiased.	<i>Potential:</i>  <i>MAP :</i>  <i>Survey volume:</i> <i># stars per data set:</i> <i># data sets:</i> <i>Analysis method:</i> <i>Numerical accuracy:</i>	2 "Iso-Pot" with $b = 0.8$ kpc or $b = 1.5$ kpc 2 MAPs, "hot" or "cool" qDF  5 spheres around sun, $r_{\text{max}} = 0.2, 1, 2, 3$ or 4 kpc 20,000 640 (= $2 \times 2 \times 5$ models $\times$ 32 realisations)  likelihood on grid $N_{\text{velocity}} = 20$ and $N_{\text{sigma}} = 4$ (for speed)	"Iso-Pot", free parameter: $b$  "hot"/"cool" qDF, free parameters: $\ln\left(\frac{h_R}{8\text{kpc}}\right), \ln\left(\frac{\sigma_R}{230\text{km s}^{-1}}\right), \ln\left(\frac{h_{\sigma,R}}{8\text{kpc}}\right)$ (fixed & known)	Fig. ??
④	<i>Potential:</i>	i) "Iso-Pot", ii) "MW13-Pot" or iii) "KKS-Pot"	i) "Iso-Pot", all parameters free	Fig. ??



Table 3—Continued

Test	Model for Mock Data		Model in Analysis	Figures
Influence of position & shape of survey volume on parameter recovery	<p><i>MAP :</i></p> <p><i>Survey volume:</i></p> <p><i># of stars per data set:</i></p> <p><i># data sets:</i></p> <p><i>Analysis method:</i></p> <p><i>Action calculation:</i></p>	<p>"hot" qDF</p> <p>4 different wedges, see Fig. ??, upper right panel</p> <p>20,000</p> <p>48 (= 4 × 3 models × 4 realisations)</p> <p>ii) &amp; iii) low accuracy</p> <p>"Stäckel Fudge" grid (?) for speed</p> <p>(# grid points: 25 in each <math>E</math> and <math>\psi</math>, 30 in <math>L_z</math>, <math>R_{\max} = 5</math></p> <p>[TO DO: What is psi and Rmax (units)?])</p>	<p>ii) "MW13-Pot", <math>R_d</math> and <math>f_h</math> free</p> <p>iii) "KKS-Pot", all free except <math>v_{\text{circ}}(R_{\odot})</math></p> <p>i) &amp; iii) qDF, all parameters free</p> <p>ii) qDF, only <math>h_R</math>, <math>\sigma_{z,0}</math> and <math>h_{\sigma_R}</math> free (fixed &amp; known)</p> <p>i) &amp; ii) MCMC, iii) likelihood on grid (same as mock data creation)</p>	
⑤ Influence of wrong assumptions about the data set (in-)completeness on parameter recovery	<p><i>Potential:</i></p> <p><i>MAP :</i></p> <p><i>Survey volume:</i></p> <p><i>Completeness:</i></p> <p><i># stars per data set:</i></p> <p><i># data sets:</i></p> <p>[TO DO]</p>	<p>"Iso-Pot"</p> <p>2 MAPs , a) "hot" or b) "cool" qDF</p> <p>sphere around sun, <math>r_{\max} = 3</math> kpc</p> <p><i>Example 1:</i> radial incompleteness, <math>\text{completeness}(r) = 1 - \epsilon_r \frac{r}{r_{\max}}</math>, twenty <math>\epsilon_r \in [0, 0.7]</math></p> <p><math>r \equiv</math> distance from sun,</p> <p><i>Example 2:</i> planar incompleteness, <math>\text{completeness}(z) = 1 - \epsilon_z \frac{ z }{r_{\max}}</math>, <math>\epsilon_r \in [0, 0.7]</math>,</p> <p><math>z \equiv</math> distance from Gal. plane.</p> <p>20,000</p> <p>40 (= 2 × 2 × 20)</p>	<p>"Iso-Pot", all parameters free</p> <p>qDF, all parameters free (fixed &amp; known)</p> <p>data set complete, <math>\text{completeness}(r) = 1</math>, <math>\epsilon_r = 0</math></p> <p>data set complete, <math>\text{completeness}(r) = 1</math>, twenty <math>\epsilon_z = 0</math></p>	<p>Illustration &amp; mock data: Fig. ?? &amp; ??</p> <p>Analysis results: <sup>1</sup> 6 Fig. ?? &amp; ??</p> <p>Analysis results: <sup>1</sup> when not using <math>v_T</math> data: Fig. ??</p>
⑥ Measurement errors				
⑦ Underestimation of proper motion errors	<p><i>Potential:</i></p> <p><i>MAP :</i></p> <p><i>Survey volume:</i></p> <p><i>Errors:</i></p> <p><i># stars per data set:</i></p> <p><i># data sets:</i></p>	<p>"Iso-Pot"</p> <p>"hot" or "cool" qDF</p> <p>sphere around sun, <math>r_{\max} = 3</math> kpc [TO DO: CHECK]</p> <p>only proper motion errors</p> <p>1, 2 or 3 mas/yr</p> <p>10,000</p> <p>24 (= 2 × 2 × 3 × 2 realisations )</p>	<p>"Iso-Pot", all parameters free</p> <p>qDF, all parameters free (fixed &amp; known)</p> <p>convolution with proper motion errors</p> <p>10% or 50% underestimated</p>	Fig. 3
⑧ Deviations in the	<p><i>Potential:</i></p> <p><i>MAP :</i></p>	<p>"Iso-Pot"</p> <p>mixture of two qDFs</p>	<p>"Iso-Pot", all parameters free</p> <p>single qDF, all parameters free</p>	<p>mock data: Fig. ??</p>

Table 3—Continued

Test		Model for Mock Data	Model in Analysis	Figures
assumed DF from the star’s true DF		<i>Example 1:</i> with fixed qDF parameters, but 20 different mixing rates: a) "hot" & "cooler" qDF or b) "cool" & "hotter" qDF <i>Example 2:</i> 20 fixed 50/50 mixtures, with varying qDF parameters (by $X\%$ ): a) "hot" & "colder" qDF or b) "cool" & "warmer" qDF		Analysis results: ?? & Fig. ??
	<i>Survey volume:</i>	sphere around sun, $r_{\max} = 2$ kpc	(fixed & known)	
	<i># stars per data set:</i>	20,000		
	<i># data sets:</i>	40 ( $= 2 \times 2 \times 20$ )		
⑧ Deviations of the assumed potential model from the star’s true potential	<i>Potential:</i>  <i>MAP :</i> <i>Survey volume:</i> <i># stars per data set:</i> <i># data sets:</i>	"MW14-Pot"  "hot" or "cool" qDF sphere around sun, $r_{\max} = 4$ kpc 20,000 2	"KKS-Pot", all parameters free, only $v_{\text{circ}}(R_{\odot}) = 230 \text{ km s}^{-1}$ fixed qDF, all parameters free (fixed & known)	potential contours: Fig. ?? qDF recovery: Fig. ??