## Chapter 2

# **Solving Linear Equations**

## 2.1 Vectors and Linear Equations

#### 2.1.1 Definition of Linear Equations

∀ linear equations

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1, \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2, \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m. \end{cases}$$
(2.1)

where  $m,n\in\mathbb{N}^*$ . The equations are linear, which means that the unknowns are only multiplied by numbers.

### 2.1.2 The Matrix Form of the Equations

The matrix form of linear equations 2.1 is

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}.$$

Let

This linear equations could be expressed as Ax = b. A is called the "coefficient matrix. This linear equations could also be expressed as

$$\mathbf{A}\mathbf{x} = x_1\mathbf{c}_1 + x_2\mathbf{c}_2 + \dots + x_n\mathbf{c}_n = \begin{bmatrix} \mathbf{r}_1 \cdot \mathbf{b} \\ \mathbf{r}_2 \cdot \mathbf{b} \\ \vdots \\ \mathbf{r}_m \cdot \mathbf{b} \end{bmatrix} = \mathbf{b}.$$

### 2.1.3 Identity Matrix

 $\forall n$ -dimensional vector  $\mathbf{v}$  where  $n \in \mathbb{N}^*$ 

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}.$$

Its identity matrix is a  $n \times n$  matrix I

$$\mathbf{I} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}.$$

The identity matrix always yields the multiplication Iv = v.