

# Hua-Hsuan Liang

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## EDUCATION

<b>Columbia University</b> <i>Master of Science in Computer Science</i>	<b>Aug. 2024 – Dec. 2025</b> <i>New York, NY</i>
<b>National Cheng Kung University</b> <i>Bachelor of Science in Computer Science and Information Engineering</i>	<b>Sep. 2019 – Jun. 2023</b> <i>Tainan, TW</i>
<ul style="list-style-type: none"><li>• GPA: 4.08/4.3</li><li>• Awarded the Academic Excellence Award (2019)</li><li>• Served as Class President for four years</li></ul>	

## EXPERIENCE

<b>Research Student</b> <i>Columbia University, Robotic Manipulation and Mobility Laboratory (ROAM Lab)</i>	<b>Sep. 2024 – Present</b> <i>New York, NY</i>
<ul style="list-style-type: none"><li>• VibeCheck   <i>Python, ROS2, Machine Learning, Data Analysis</i><ul style="list-style-type: none"><li>◦ Designed and implemented a ROS2-based framework to integrate an acoustic sensor, computer, and UR5 robotic arm for real-time data collection and processing.</li><li>◦ Developed and optimized machine learning models for acoustic data analysis, achieving 90% classification accuracy in object recognition tasks.</li><li>◦ Built a high-fidelity simulation environment to train robotic policies using reinforcement learning and imitation learning, improving system performance before deployment.</li></ul></li></ul>	
<b>Research Assistant</b> <i>National Cheng Kung University</i>	<b>Sep. 2023 – Jun. 2024</b> <i>Tainan, TW</i>
<ul style="list-style-type: none"><li>• Implemented deep reinforcement learning (DRL) models, including DQN, DDPG, and MP-DQN, for computational resource management</li><li>• Built a scalable Python server as a Docker image and managed it with Kubernetes (K8s) and Docker Swarm</li><li>• Stabilized the experimental environment, achieving a 90% success rate in reliability</li></ul>	
<b>Equipment Intelligence Engineering Intern</b> <i>Lam Research</i>	<b>Jul. 2023 – Aug. 2023</b> <i>Hsinchu, TW</i>
<ul style="list-style-type: none"><li>• Leveraged machinery data for dimensionality reduction and visualization, assisting process engineers in troubleshooting</li><li>• Developed automation tools in Python with Pandas and NumPy, saving 5 hours per use in data analysis</li></ul>	

## PUBLICATIONS

<b>VibeCheck: Using Active Acoustic Tactile Sensing for Contact-Rich Manipulation</b>
<ul style="list-style-type: none"><li>• Author list: K. Zhang*, D. Kim*, E. T. Chang*, <b>H. Liang</b>, Z. He, K. Lampo, P. Wu, I. Kymissis, M. Ciocarlie.</li><li>• IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2025). Under review.</li></ul>

## PROJECTS

<b>Newsbie</b>   <i>Python, Flask, React Native, Expo, MongoDB, Docker</i>	<b>Mar. 2024 – Aug. 2024</b>
<ul style="list-style-type: none"><li>• Developed and deployed a full-stack mobile application using Flask (REST API) and React Native, enabling seamless user interaction.</li><li>• Integrated AI-powered news summarization and procast generation using ChatGPT, enhancing content personalization.</li><li>• Designed and implemented a MongoDB database to efficiently store user data and generated procasts, ensuring scalability.</li></ul>	

## EXTRACURRICULAR ACTIVITIES

<b>Graduation Ceremony Deputy Chairperson</b>	<b>Oct. 2022 – Jun. 2023</b>
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## AWARDS

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- **Taipei Metro 2024 Hackathon** - Second Place Award & Best Creative Award

## TECHNICAL SKILLS

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**OS:** Windows, Ubuntu

**Languages:** Java, Python, C/C++, JavaScript, HTML, CSS

**Developer Tools:** PyTorch, Linux, Git, Docker, Kubernetes, Docker Swarm, VS Code, Bash, Vim

**Libraries:** Pandas, NumPy, Flask, Matplotlib, Expo, React Native, ROS2