

# School of Mathematics and Statistics Math1131-Algebra

# Lec04: Linear Combinations and Planes

Laure Helme-Guizon (Dr H)
Laure@unsw.edu.au
Jonathan Kress
j.kress@unsw.edu.au

Red-Centre, Rooms 3090 and 3073

2019 Term 1

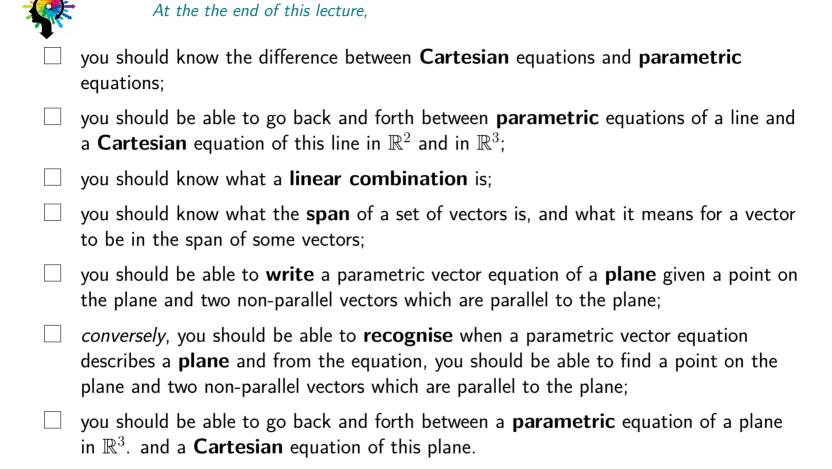
### Warm up

Exercise 1. Let  $\overrightarrow{x} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}$ ,  $\lambda \in \mathbb{R}$  be a line in  $\mathbb{R}^3$ . Write down a vector parametric form of the line  $\ell'$  through (1,2,3) that is parallel to the line  $\ell$  above.

Exercise 2. Find a vector parametric form of the line  $\ell$  in  $\mathbb{R}^4$  which passes through A(2,-3,-1,2) and B(-1,2,2,7).



### **Learning outcomes for this lecture**





You can use this list as a check list to get ready for our next class: After studying the lecture notes, come back to this list, and for each item, check that you have indeed mastered it. Then tick the corresponding box ... or go back to the notes.



# Parametric to Cartesian equations of a line in $\mathbb{R}^3$

Example 3. Find a Cartesian equation for the line  $\ell$  given parametrically as

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ -5 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 3 \\ -1 \end{pmatrix} \ \lambda \in \mathbb{R}$$



# Parametric to Cartesian equation of a line in $\mathbb{R}^3$

Example 4. Find a Cartesian equation for the line  $\ell$  given parametrically as

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ -5 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix} \ \lambda \in \mathbb{R}$$



# Cartesian to parametric vector form of a line

Example 5. Find the a parametric vector equation for each of the following lines.

a) 
$$\ell_1: \frac{x-3}{5} = \frac{y+1}{2} = z-8$$
 in  $\mathbb{R}^3$ .

b) 
$$\ell_2: \frac{x-3}{5} = \frac{y+1}{2}, \ z = 8 \text{ in } \mathbb{R}^3.$$



# Cartesian to parametric vector form of a line

#### Example 5, continued.

Find the a parametric vector equation for each of the following lines.

c)  $\ell_3: y = 3x + 2$  in  $\mathbb{R}^2$ .

d)  $\ell_4: x = 8 \text{ in } \mathbb{R}^2.$ 

e)  $\ell_5: y = 2x + 1, z = 2$  in  $\mathbb{R}^3$ .



### **Linear combinations**

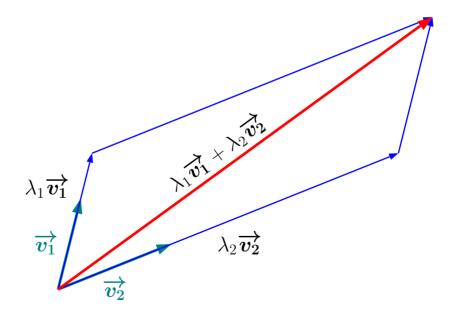


### Linear combinations of two vectors

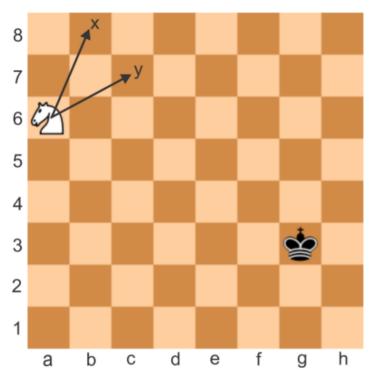
We say that a vector  $\overrightarrow{v}$  is a *linear combination* of two vectors  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$  if  $\overrightarrow{v}$  is a sum of scalar multiples of  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$ , i.e. if  $\overrightarrow{v}$  can be written

$$\overrightarrow{\boldsymbol{v}} = \lambda_1 \overrightarrow{\boldsymbol{v_1}} + \lambda_2 \overrightarrow{\boldsymbol{v_2}},$$

where  $\lambda_1$  and  $\lambda_2$  are scalars.



### I have seen this before...



Define the vectors  $\mathbf{x}$  and  $\mathbf{y}$  as the directed line segments from a6 to b8, and a6 to c7 respectively on a chessboard. Other traditional knight moves such as a6 to c5, and a6 to b4, are impossible for your white knight due to weak knees. Hence your knight can only move in the  $\mathbf{x}$ ,  $-\mathbf{x}$ ,  $\mathbf{y}$  or  $-\mathbf{y}$  directions.

Nonetheless, your knight can move from a6 to capture the stationary black king at g3!

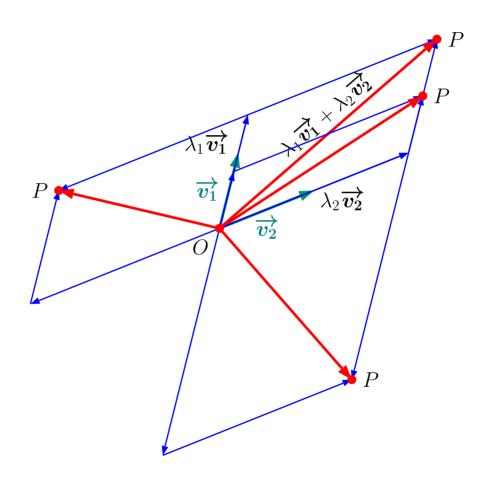
What combination of  $\mathbf{x}$  and  $\mathbf{y}$  moves will accomplish this? Use the syntax  $\mathbf{a} * \mathbf{x} + \mathbf{b} * \mathbf{y}$  where  $\mathbf{a}$  and  $\mathbf{b}$  are integers (for example  $2 * \mathbf{x} + 3 * \mathbf{y}$ ).

a6 to g3:		ব	Σ
-----------	--	---	---



### **Linear combinations**

With  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$  we can make many different linear combinations.





# **Span of two vectors**



### Span of two vectors

The set of all linear combinations of  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$  is called the *span* of  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$ .

$$\mathrm{span}(\overrightarrow{\boldsymbol{v_1}},\overrightarrow{\boldsymbol{v_2}}) = \left\{\overrightarrow{\boldsymbol{v}}: \overrightarrow{\boldsymbol{v}} = \lambda_1\overrightarrow{\boldsymbol{v_1}} + \lambda_2\overrightarrow{\boldsymbol{v_2}}, \ \lambda_1,\lambda_2 \in \mathbb{R}\right\}.$$

#### Example 6.

a) Is 
$$\overrightarrow{u} = \begin{pmatrix} -3 \\ 2 \\ 6 \end{pmatrix}$$
 in the span of  $\overrightarrow{u_1} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}$  and  $\overrightarrow{u_2} = \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix}$ ?



# Span of two vectors



### Span of two vectors

The set of all linear combinations of  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$  is called the  $\overrightarrow{span}$  of  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$ .

$$\mathrm{span}(\overrightarrow{\boldsymbol{v_1}},\overrightarrow{\boldsymbol{v_2}}) = \left\{\overrightarrow{\boldsymbol{v}}: \overrightarrow{\boldsymbol{v}} = \lambda_1\overrightarrow{\boldsymbol{v_1}} + \lambda_2\overrightarrow{\boldsymbol{v_2}}, \ \lambda_1,\lambda_2 \in \mathbb{R}\right\}.$$

#### Example 6, continued.

b) Is 
$$\overrightarrow{\boldsymbol{w}} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$
 in the span of  $\overrightarrow{\boldsymbol{w_1}} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$  and  $\overrightarrow{\boldsymbol{w_2}} = \begin{pmatrix} 5 \\ 2 \\ -4 \end{pmatrix}$ ?



# **Span**

#### Example 6, continued.



c) Is 
$$\overrightarrow{\boldsymbol{v}} = \begin{pmatrix} -3 \\ 2 \\ 6 \end{pmatrix}$$
 in the span of  $\overrightarrow{\boldsymbol{v_1}} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$  and  $\overrightarrow{\boldsymbol{v_2}} = \begin{pmatrix} 5 \\ 2 \\ -4 \end{pmatrix}$ ?

### Planes and lines through the origin



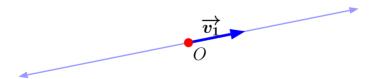
The span of two non-zero non-parallel vectors is a plane through the origin.

We say that  $\operatorname{span}(\overrightarrow{v_1}, \overrightarrow{v_2})$  is the plane spanned by  $\overrightarrow{v_1}$  and  $\overrightarrow{v_2}$ .

In MATH1231, we will define the span of any number of vectors.

Example 7 (Important!) Geometrically, what is the span of one non-zero vector

$$\operatorname{span}(\overrightarrow{\boldsymbol{v_1}}) = \left\{\overrightarrow{\boldsymbol{x}}: \overrightarrow{\boldsymbol{x}} = \lambda_1 \overrightarrow{\boldsymbol{v_1}}, \ \lambda_1 \in \mathbb{R}\right\}?$$





### **Planes**

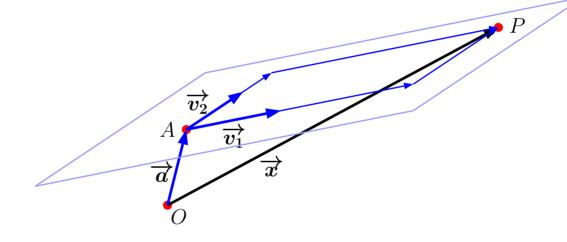
#### Planes in $\mathbb{R}^n$

A plane in  $\mathbb{R}^n$  is the set of points or vectors  $\overrightarrow{x}$  given by



$$\overrightarrow{x} = \overrightarrow{a} + \lambda_1 \overrightarrow{v_1} + \lambda_2 \overrightarrow{v_2}, \quad \lambda_1, \lambda_2 \in \mathbb{R},$$

where  $\overrightarrow{a} \in \mathbb{R}^n$  gives a point on the plane and  $\overrightarrow{v_1}$ ,  $\overrightarrow{v_2} \in \mathbb{R}^n$  are a pair of non-zero, non-parallel vectors that are directions in the plane.



Example 8. To be done on the next slide.

Find the a parametric vector form of the plane  $\Pi$  passing through the three points A(1,-2,1), B(2,1,1) and C(0,3,1).



## Parametric equation of a plane from three points

#### Example 8.

Find the a parametric vector form of the plane  $\Pi$  passing through the three points A(1,-2,1), B(2,1,1) and C(0,3,1).



# Parametric equation of a plane from 1 point and 2 lines

Example 9. Find the a parametric vector form of the plane  $\Pi$  passing through the point (2,-1,2) and parallel to the lines

$$\ell_1: \qquad \frac{x-2}{3} = \frac{y-1}{-3} = \frac{2z-3}{8}$$

and

$$\ell_2: \qquad \overrightarrow{x} = \begin{pmatrix} -2\\3\\1 \end{pmatrix} + \lambda \begin{pmatrix} 2\\1\\1 \end{pmatrix}, \ \lambda \in \mathbb{R}.$$



### Cartesian equation of a plane

Example 10. For the plane  $\Pi$  given by

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \lambda_1 \begin{pmatrix} 0 \\ -1 \\ 4 \end{pmatrix} + \lambda_2 \begin{pmatrix} 4 \\ -2 \\ 0 \end{pmatrix}, \quad \lambda_1, \lambda_2 \in \mathbb{R},$$

eliminate the parameters  $\lambda_1$  and  $\lambda_2$  to find an equation relating  $x_1$ ,  $x_2$  and  $x_3$ .



# Cartesian equation of a plane in $\mathbb{R}^3$





A Cartesian equation of a plane in  $\mathbb{R}^3$  is an equation of the form

$$ax_1 + bx_2 + cx_3 = d$$

for some  $a, b, c, d \in \mathbb{R}$  with at least one of a, b and c non-zero.

Example 11. Find the a vector equation for the plane  $\Pi$  in  $\mathbb{R}^3$ ,  $x_1 + 2x_2 - x_3 = 3$ .



Don't forget to read Chapter 1 of the Algebra Notes! (It is the big yellow book that was in the course pack, the one that contains the Algebra tutorial questions)

