

MATH1131 Mathematics 1A – Algebra

Lecture 7: Cross Product

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Based on slides by Jonathan Kress

Definition

Suppose that

$$\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$
 and $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$

are vectors in \mathbb{R}^3 .

Then the cross product (or vector product) of \mathbf{a} and \mathbf{b} is:

$$\mathbf{a} \times \mathbf{b} = \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix}$$

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Note that while $\mathbf{a} \cdot \mathbf{b}$ is defined for vectors in all dimensions, $\mathbf{a} \times \mathbf{b}$ is only defined for vectors in \mathbb{R}^3 .

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This formula can be difficult to memorise. One way to remember the terms is to think of the subscripts cycling through in order:

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Definition: 2×2 determinant

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$$\left|\begin{array}{cc} 1 & 2 \\ 3 & 4 \end{array}\right| = 1 \times 4 - 2 \times 3 = -2$$

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$$\mathbf{a} \times \mathbf{b} = \left| egin{array}{cccc} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{array} \right|$$

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$= \mathbf{i} \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} - \mathbf{j} \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} + \mathbf{k} \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

$$= \begin{pmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{pmatrix}$$

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$$= \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix}$$
Note the different signs!

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \times \begin{pmatrix} 2 \\ 3 \\ 5 \end{pmatrix} = =$$

$$\begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} =$$

$$\begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \times \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} =$$

$$\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \times \begin{pmatrix} 2 \\ 3 \\ 5 \end{pmatrix} \qquad = \qquad \begin{pmatrix} 2 \times 5 - 3 \times 3 \\ 3 \times 2 - 1 \times 5 \\ 1 \times 3 - 2 \times 2 \end{pmatrix}$$

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$$\begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \times 1 - (-1) \times 1 \\ (-1) \times 1 - 2 \times 1 \\ 2 \times 1 - 3 \times 1 \end{pmatrix}$$

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$$\begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \times \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} = \begin{pmatrix} 0 \times 5 - 2 \times 4 \\ 2 \times 3 - 1 \times 5 \\ 1 \times 4 - 0 \times 3 \end{pmatrix}$$

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Properties of the cross product

If **a** and **b** are vectors in \mathbb{R}^3 , then $\mathbf{a} \times \mathbf{b}$ is orthogonal to **a** and to **b**.

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For example, we saw

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and can confirm that

$$\begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} -8 \\ 1 \\ 4 \end{pmatrix} = 0 \quad \text{and} \quad \begin{pmatrix} 3 \\ 4 \\ 5 \end{pmatrix} \cdot \begin{pmatrix} -8 \\ 1 \\ 4 \end{pmatrix} = 0.$$

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Exercise

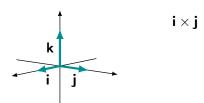
Show that for all $a_i, b_i \in \mathbb{R}$:

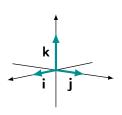
$$\begin{pmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{pmatrix} \cdot \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = 0$$

and

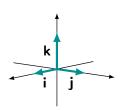
$$\begin{pmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = 0.$$

Examples

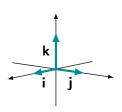




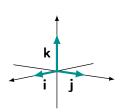
$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$



$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

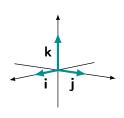


$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \mathbf{k}$$

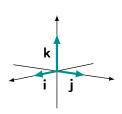


$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \mathbf{k}$$

$$\mathbf{j} \times \mathbf{k} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \mathbf{i}$$



$$\begin{aligned} \mathbf{i} \times \mathbf{j} &= \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \mathbf{k} \\ \mathbf{j} \times \mathbf{k} &= \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \mathbf{i} \\ \mathbf{k} \times \mathbf{i} &= \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \mathbf{j} \end{aligned}$$

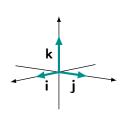


$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \mathbf{k}$$

$$\mathbf{j} \times \mathbf{k} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \mathbf{i}$$

$$\mathbf{k} \times \mathbf{i} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \mathbf{j}$$

Similarly
$$\mathbf{j} \times \mathbf{i} = -\mathbf{k}$$
, $\mathbf{k} \times \mathbf{j} = -\mathbf{i}$, and $\mathbf{i} \times \mathbf{k} = -\mathbf{j}$.



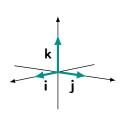
$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \mathbf{k}$$

$$\mathbf{j} \times \mathbf{k} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \mathbf{i}$$

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$$\mathbf{j} \times \mathbf{i} = -\mathbf{k}$$
, $\mathbf{k} \times \mathbf{j} = -\mathbf{i}$, and $\mathbf{i} \times \mathbf{k} = -\mathbf{j}$.

The direction of the cross product vector can be determined from the "right-hand rule": To find the direction of $\mathbf{a} \times \mathbf{b}$, join the vectors tail-to-tail, and point your right thumb in the direction of \mathbf{a} and fingers in the direction of \mathbf{b} . Your palm will point in the direction of $\mathbf{a} \times \mathbf{b}$.



$$\mathbf{i} \times \mathbf{j} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \mathbf{k}$$

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$$\mathbf{j} \times \mathbf{i} = -\mathbf{k}$$
, $\mathbf{k} \times \mathbf{j} = -\mathbf{i}$, and $\mathbf{i} \times \mathbf{k} = -\mathbf{j}$.

The direction of the cross product vector can be determined from the "right-hand rule": To find the direction of $\mathbf{a} \times \mathbf{b}$, join the vectors tail-to-tail, and point your right thumb in the direction of \mathbf{a} and fingers in the direction of \mathbf{b} . Your palm will point in the direction of $\mathbf{a} \times \mathbf{b}$.

Notice also that $\mathbf{i} \times \mathbf{i} = \mathbf{j} \times \mathbf{j} = \mathbf{k} \times \mathbf{k} = \mathbf{0}$.

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For example:

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Notice we have assumed some properties of the cross product, which we should now prove...

Properties of the cross product

For all vectors \mathbf{a} , \mathbf{b} and \mathbf{c} in \mathbb{R}^3 and scalars $\lambda \in \mathbb{R}$,

- $\mathbf{a} \times \mathbf{a} = \mathbf{0}$
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- $\mathbf{b} \times \mathbf{a} = -\mathbf{a} \times \mathbf{b}$

(anti-commutative law)

• $\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c}$

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Proof

$$\mathbf{a} \times \mathbf{a} = \begin{pmatrix} a_2 a_3 - a_3 a_2 \\ a_3 a_1 - a_1 a_3 \\ a_1 a_2 - a_2 a_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \mathbf{0}$$

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Proof

$$\mathbf{0} \times \mathbf{a} = \begin{pmatrix} 0a_3 - 0a_2 \\ 0a_1 - 0a_3 \\ 0a_2 - 0a_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \text{ and } \mathbf{a} \times \mathbf{0} = \begin{pmatrix} a_20 - a_30 \\ a_30 - a_10 \\ a_10 - a_20 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

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Proof

$$\mathbf{b} \times \mathbf{a} = \begin{pmatrix} b_2 a_3 - b_3 a_2 \\ b_3 a_1 - b_1 a_3 \\ b_1 a_2 - b_2 a_1 \end{pmatrix} = - \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix} = -\mathbf{a} \times \mathbf{b}$$

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$$\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = \begin{pmatrix} a_2(b_3 + c_3) - a_3(b_2 + c_2) \\ a_3(b_1 + c_1) - a_1(b_3 + c_3) \\ a_1(b_2 + c_2) - a_2(b_1 + c_1) \end{pmatrix}$$

$$= \begin{pmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{pmatrix} + \begin{pmatrix} a_2c_3 - a_3c_2 \\ a_3c_1 - a_1c_3 \\ a_1c_2 - a_2c_1 \end{pmatrix} = \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c}$$

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Proof

$$\mathbf{a} \times (\lambda \mathbf{b}) = \begin{pmatrix} a_2(\lambda b_3) - a_3(\lambda b_2) \\ a_3(\lambda b_1) - a_1(\lambda b_3) \\ a_1(\lambda b_2) - a_2(\lambda b_1) \end{pmatrix} = \lambda \begin{pmatrix} a_2 b_3 - a_3 b_2 \\ a_3 b_1 - a_1 b_3 \\ a_1 b_2 - a_2 b_1 \end{pmatrix} = \lambda (\mathbf{a} \times \mathbf{b})$$

and

$$(\lambda \mathbf{a}) \times \mathbf{b} = \begin{pmatrix} (\lambda a_2)b_3 - (\lambda a_3)b_2 \\ (\lambda a_3)b_1 - (\lambda a_1)b_3 \\ (\lambda a_1)b_2 - (\lambda a_2)b_1 \end{pmatrix} = \lambda \begin{pmatrix} a_2b_3 - a_3b_2 \\ a_3b_1 - a_1b_3 \\ a_1b_2 - a_2b_1 \end{pmatrix} = \lambda (\mathbf{a} \times \mathbf{b})$$

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Theorem

For all vectors \mathbf{a} , \mathbf{b} in \mathbb{R}^3 :

$$|\mathbf{a} \cdot \mathbf{b}|^2 + |\mathbf{a} \times \mathbf{b}|^2 = |\mathbf{a}|^2 |\mathbf{b}|^2$$
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Proof

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Proof

$$|\mathbf{a} \cdot \mathbf{b}|^2 + |\mathbf{a} \times \mathbf{b}|^2$$

=
$$(a_1b_1 + a_2b_2 + a_3b_3)^2 + (a_2b_3 - a_3b_2)^2 + (a_3b_1 - a_1b_3)^2 + (a_1b_2 - a_2b_1)^2$$

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$$= a_1^2b_1^2 + a_1^2b_2^2 + a_1^2b_3^2 + a_2^2b_1^2 + a_2^2b_2^2 + a_2^2b_3^2 + a_3^2b_1^2 + a_3^2b_2^2 + a_3^2b_3^2$$

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$$|\mathbf{a} \cdot \mathbf{b}|^2 + |\mathbf{a} \times \mathbf{b}|^2 = |\mathbf{a}|^2 |\mathbf{b}|^2.$$

Proof

$$|\mathbf{a} \cdot \mathbf{b}|^{2} + |\mathbf{a} \times \mathbf{b}|^{2}$$

$$= (a_{1}b_{1} + a_{2}b_{2} + a_{3}b_{3})^{2} + (a_{2}b_{3} - a_{3}b_{2})^{2} + (a_{3}b_{1} - a_{1}b_{3})^{2} + (a_{1}b_{2} - a_{2}b_{1})^{2}$$

$$= a_{1}^{2}b_{1}^{2} + a_{1}^{2}b_{2}^{2} + a_{1}^{2}b_{3}^{2} + a_{2}^{2}b_{1}^{2} + a_{2}^{2}b_{2}^{2} + a_{2}^{2}b_{3}^{2} + a_{3}^{2}b_{1}^{2} + a_{3}^{2}b_{2}^{2} + a_{3}^{2}b_{3}^{2}$$

$$= (a_{1}^{2} + a_{2}^{2} + a_{3}^{2})(b_{1}^{2} + b_{2}^{2} + b_{3}^{2})$$

Theorem

For all vectors \mathbf{a} , \mathbf{b} in \mathbb{R}^3 :

$$|\mathbf{a} \cdot \mathbf{b}|^2 + |\mathbf{a} \times \mathbf{b}|^2 = |\mathbf{a}|^2 |\mathbf{b}|^2.$$

Proof

For $\mathbf{a}, \mathbf{b} \in \mathbb{R}^3$:

$$|\mathbf{a}\cdot\mathbf{b}|^2+|\mathbf{a}\times\mathbf{b}|^2$$

$$= (a_1b_1 + a_2b_2 + a_3b_3)^2 + (a_2b_3 - a_3b_2)^2 + (a_3b_1 - a_1b_3)^2 + (a_1b_2 - a_2b_1)^2$$

$$= a_1^2b_1^2 + a_1^2b_2^2 + a_1^2b_3^2 + a_2^2b_1^2 + a_2^2b_2^2 + a_2^2b_3^2 + a_3^2b_1^2 + a_3^2b_2^2 + a_3^2b_3^2$$

$$= (a_1^2 + a_2^2 + a_3^2)(b_1^2 + b_2^2 + b_3^2)$$

$$= |\mathbf{a}|^2 |\mathbf{b}|^2$$

Theorem

For all vectors \mathbf{a} , \mathbf{b} in \mathbb{R}^3 :

$$|\mathbf{a} \cdot \mathbf{b}|^2 + |\mathbf{a} \times \mathbf{b}|^2 = |\mathbf{a}|^2 |\mathbf{b}|^2.$$

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So if $\mathbf{a}, \mathbf{b} \in \mathbb{R}^3$ and θ is the angle between \mathbf{a} and \mathbf{b} , then

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Hence (since $sin(\theta)$ is positive for all $0 < \theta < \pi$):

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Hence (since $sin(\theta)$ is positive for all $0 < \theta < \pi$):

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(Note that if $\mathbf{a} = \mathbf{0}$ or $\mathbf{b} = \mathbf{0}$, then both sides are 0 although $\sin \theta$ is not defined.)

Geometric interpretation of the cross product

We can now describe the cross product of two vectors geometrically:

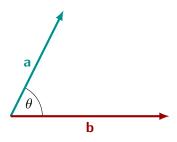
Summary

For non-zero vectors ${\boldsymbol a}$ and ${\boldsymbol b}$ in $\mathbb{R}^3,$ the cross product ${\boldsymbol a}\times{\boldsymbol b}$ is a vector of length

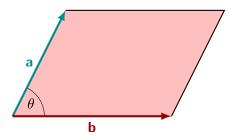
$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}|\sin\theta$$

in the direction perpendicular to both ${\bf a}$ and ${\bf b}$ as determined by the right-hand rule.

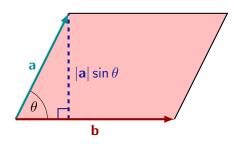
Area of a parallelogram



Area of a parallelogram

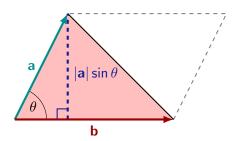


Area of a parallelogram



Area =
$$base \times altitude = |\mathbf{b}||\mathbf{a}| \sin \theta = |\mathbf{a} \times \mathbf{b}|$$

Area of a triangle



Area =
$$\frac{1}{2}$$
base × altitude = $\frac{1}{2}$ |**b**||**a**| sin θ = $\frac{1}{2}$ |**a** × **b**|

Find the area of a parallelogram with vertices at points A(1,0,1), B(-2,1,3), C(3,1,4) and D.

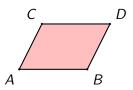
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What are the possibilities for D?

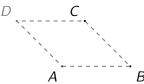
С.

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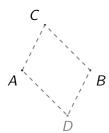
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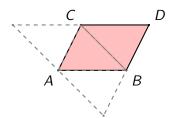
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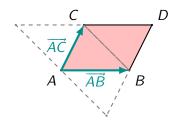
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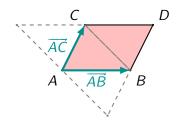


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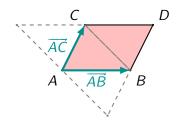
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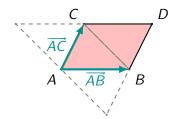
Area =
$$|\overrightarrow{AB} \times \overrightarrow{AC}|$$
 = $\begin{vmatrix} -2 - 1 \\ 1 - 0 \\ 3 - 1 \end{vmatrix} \times \begin{vmatrix} 3 - 1 \\ 1 - 0 \\ 4 - 1 \end{vmatrix}$

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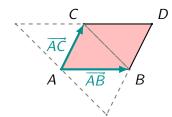
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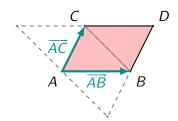
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Exercise

Show that the same area value arises for the other choices of D.