

School of Mathematics and Statistics Math1131-Algebra

Lec08: Triple scalar product/point normal form

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2020 Term 1

Learning outcomes for this lecture



At he the end of this lecture

you should be able to calculate the triple scalar product of three vectors in \mathbb{R}^3 and use it to calculate the volume of a parallelepiped in 3D;
you should know that the coefficients of x,y,z in a Cartesian equation of a plane are the coordinates of a vector which is normal to that plane;
you should be able to write and recognise an equation of a plane written in point normal form ;
you should be able to go any from any equation of a plane (cartesian, parametric, point-normal) to any other;
you should be able to use the cross product to solve problems in Geometry (like finding the distance between a point and a plane);
you should be more convinced than ever that drawing is really helpful!

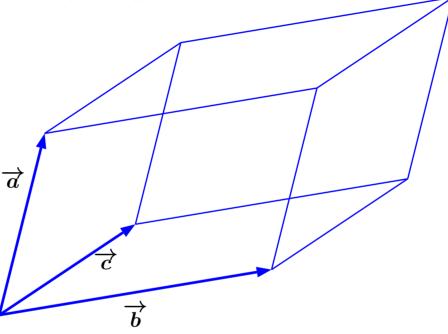


You can use this list as a check list to get ready for our next class: After studying the lecture notes, come back to this list, and for each item, check that you have indeed mastered it. Then tick the corresponding box ... or go back to the notes.



The 3D version of a parallelogram is the parallelepiped. The six faces are parallelograms.

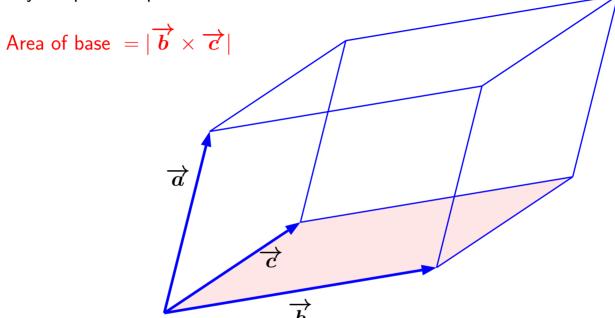
They are pairwise parallel and identical.





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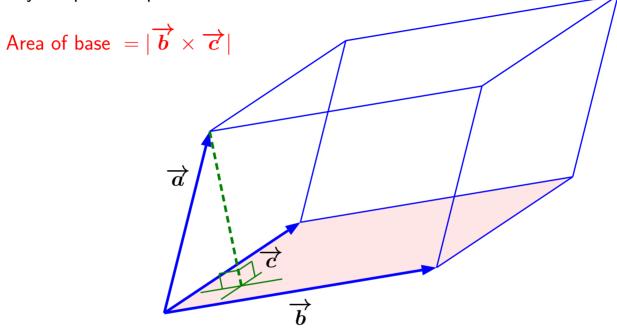
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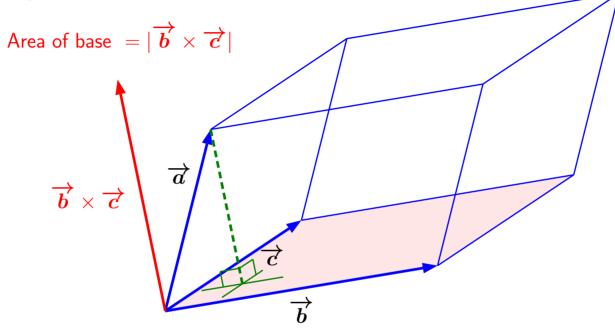


Volume = Area of base \times altitude



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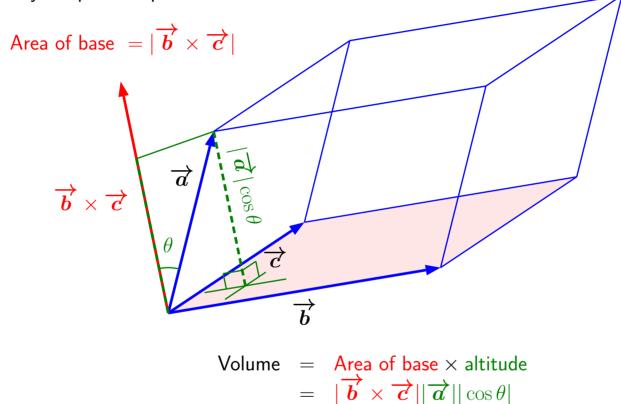


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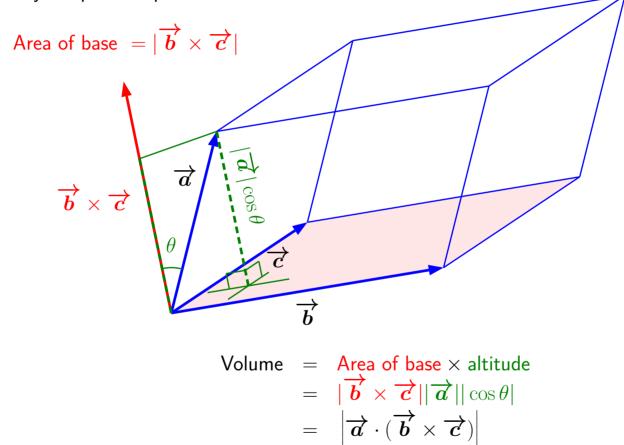
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Scalar triple product

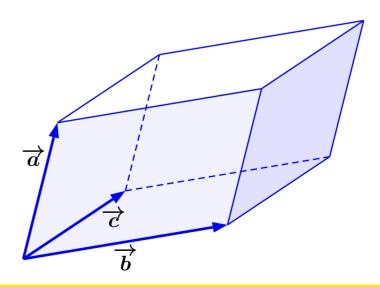
Scalar triple product of three vectors in \mathbb{R}^3

The triple scalar product of \overrightarrow{a} , \overrightarrow{b} , $\overrightarrow{c} \in \mathbb{R}^3$ is the number

$$\overrightarrow{a} \cdot (\overrightarrow{b} \times \overrightarrow{c}).$$

The volume of the parallelepiped with edges given by \overrightarrow{a} , \overrightarrow{b} and \overrightarrow{c} is

$$\left| \overrightarrow{a} \cdot (\overrightarrow{b} \times \overrightarrow{c}) \right|$$
.





Application of the scalar triple product

Exercise 1. Consider the vectors

$$\overrightarrow{\boldsymbol{u}} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}, \quad \overrightarrow{\boldsymbol{v}} = \begin{pmatrix} -3 \\ -2 \\ -7 \end{pmatrix}, \quad \overrightarrow{\boldsymbol{w}} = \begin{pmatrix} -4 \\ 3 \\ 7 \end{pmatrix}.$$



- Calculate
 - $\begin{array}{ccc} \textbf{(i)} & \overrightarrow{\boldsymbol{u}} \cdot (\overrightarrow{\boldsymbol{v}} \times \overrightarrow{\boldsymbol{w}}) \\ \textbf{(ii)} & \overrightarrow{\boldsymbol{v}} \cdot (\overrightarrow{\boldsymbol{u}} \times \overrightarrow{\boldsymbol{w}}) \\ \textbf{(iii)} & \overrightarrow{\boldsymbol{w}} \cdot (\overrightarrow{\boldsymbol{u}} \times \overrightarrow{\boldsymbol{v}}) \end{array}$
- b) Find the volume of the parallelepiped with edges given by the vectors \overrightarrow{u} , \overrightarrow{v} and \overrightarrow{w} .



Checking our answers with Maple

```
> with(LinearAlgebra):
> # use : instead of ; if you do not want the echo
  # SHIFT + ENTER gives a new line in the current execution
  block.
  u := \langle 1, 2, 3 \rangle:
  v := <-3, -2, -7>:
  w := <-4,3,7>;
                                 w := \left| \begin{array}{c} -4 \\ 3 \\ 7 \end{array} \right|
> # First find the cross product of v and w and then the dot
  product with u.
  n := CrossProduct(v,w);
  u.n;
                                  n := \begin{bmatrix} 7 \\ 49 \\ -17 \end{bmatrix}
> # There are two more equivalent ways to calculate this
  v.CrossProduct(w,u);
  w.CrossProduct(u,v);
                                       54
                                       54
```



Properties of the Scalar triple product

$$\bullet \text{ Note that for } \overrightarrow{\boldsymbol{a}} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}, \quad \overrightarrow{\boldsymbol{b}} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}, \quad \overrightarrow{\boldsymbol{c}} = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix},$$

$$\overrightarrow{a} \cdot (\overrightarrow{b} \times \overrightarrow{c}) = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

which we can calculate by developing along the first row or column.

• and that

$$\overrightarrow{\boldsymbol{a}}\cdot(\overrightarrow{\boldsymbol{b}}\times\overrightarrow{\boldsymbol{c}})=\overrightarrow{\boldsymbol{b}}\cdot(\overrightarrow{\boldsymbol{c}}\times\overrightarrow{\boldsymbol{a}})=\overrightarrow{\boldsymbol{c}}\cdot(\overrightarrow{\boldsymbol{a}}\times\overrightarrow{\boldsymbol{b}}).$$



Note that we can obtain the second and then the third expression from the first one by permuting the vectors: $\overrightarrow{a} \rightarrow \overrightarrow{b} \rightarrow \overrightarrow{c} \rightarrow \overrightarrow{a}$.

As a result,

$$\overrightarrow{a} \cdot (\overrightarrow{b} \times \overrightarrow{c}) = (\overrightarrow{a} \times \overrightarrow{b}) \cdot \overrightarrow{c}.$$



Application of the scalar triple product ... or otherwise

Exercise 2. Show that the points A(3,3,5), B(1,0,1), C(2,2,4) and D(2,1,2) are coplanar.

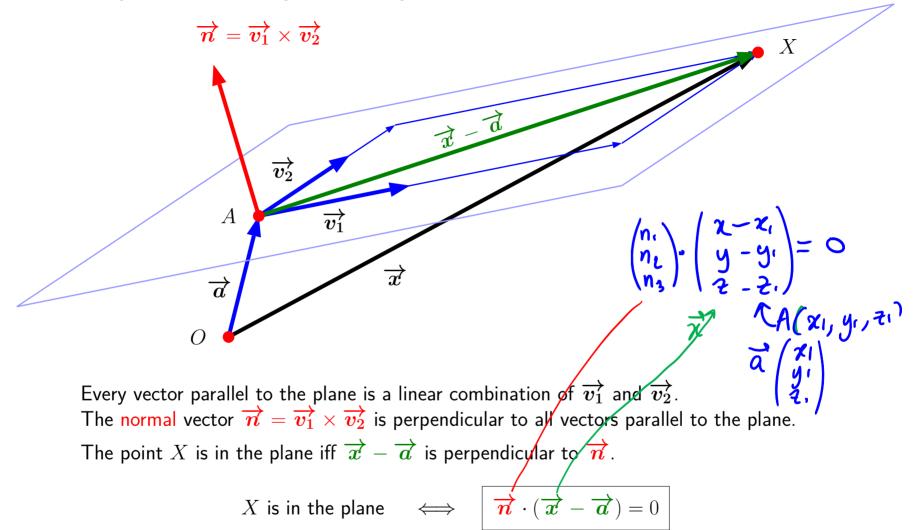


Checking our answers with Maple

```
> with(LinearAlgebra):
\gt # Define position vectors for the points A, B, C and D.
 a := \langle 3, 3, 5 \rangle:
 b := \langle 1, 0, 1 \rangle:
 c := <2,2,4>:
 d := \langle 2, 1, 2 \rangle:
> # Find the cross product of vectors AB and AC.
  AB := b - a;
  AC := c - a;
  n := CrossProduct(AB,AC);
                                   AB := \begin{bmatrix} -2 \\ -3 \\ -4 \end{bmatrix}
                                   AC := \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}
                                    n := \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}
> # D is in the plane ABC iff AD is perpendicular to n.
  AD := d - a;
  n dot AD := n.AD;
                                   AD := \begin{bmatrix} -1 \\ -2 \\ -3 \end{bmatrix}
```



Equation of a plane in point normal form



The boxed equation is a Cartesian equation for the plane written in point normal form.





Suppose
$$\overrightarrow{n} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$
 is a vector normal to a

plane passing through the point $A(x_0, y_0, z_0)$.

• An equation in point normal form of this plane is

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} \cdot \begin{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} \end{pmatrix} = 0.$$



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Expand this out to get

$$ax + by + cz = d,$$

where $d = ax_0 + by_0 + cz_0$.



Note that the **coefficients** of x, y and z in a **Cartesian** equation of the plane are the coordinates of \overrightarrow{n} , which is **normal** to the plane! This is always the case.



Expanded Cartesian and point normal forms

Exercise 3. Find an expanded Cartesian equation of the plane with normal $\overrightarrow{n} = \begin{bmatrix} -2 \\ 2 \end{bmatrix}$

that passes through the point A(1, 2, 1).

$$p(x/y/2)$$
 is on the plane $\Rightarrow AP \cdot n = 0$

$$\Rightarrow AP. N = 0$$

$$\Rightarrow (4)(x-1) = 0$$

$$\iff \begin{pmatrix} 4 \\ -2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} x - 1 \\ y - 2 \\ z - 1 \end{pmatrix} = 0$$

$$4x - 2y + 3z - 3 = 0$$

$$4x-2y+3z-3=0$$

$$\frac{\text{Method 2}:}{4x-2y+3z+d}=0$$
A is on the plane so $4xI-2x2+3xI+d=0$
 $3+d=0$



Exercise 4. Write equations of the plane Π defined by

$$\overrightarrow{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \lambda_1 \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} + \lambda_2 \begin{pmatrix} 5 \\ -4 \\ 1 \end{pmatrix}, \quad \lambda_1, \lambda_2 \in \mathbb{R},$$
and form and in expanded Cartesian form

in point normal form and in expanded Cartesian form.

$$= \begin{pmatrix} -1 + 12 \\ -(2 - 15) \\ -8 + 5 \end{pmatrix} = \begin{pmatrix} 11 \\ 13 \\ -3 \end{pmatrix}$$

chede
$$\vec{n} \cdot \vec{V}_1 = 2x11 - 13 - 9$$

= 22 - 13 - 9 = 0

quation of
$$T$$
:
$$\frac{1}{1} \cdot (x - a) = 0$$

$$\frac{1}{12} \cdot (y - 2) = 0$$

$$\frac{1}{12} \cdot (y - 2) = 0$$

$$\frac{1}{12} \cdot (y - 2) = 0$$

1 n = V1 + V2

$$= \begin{pmatrix} -1+12 \\ -(2-15) \\ -8+5 \end{pmatrix} = \begin{pmatrix} 11 \\ 13 \\ -3 \end{pmatrix}$$

$$= \begin{pmatrix} 11 \\ 26 + 9 = 0 \\ 11 \\ 27 + 13y - 3z = 28 \end{pmatrix}$$



Exercise 4, continued. Write equations of the plane Π defined by

$$\overrightarrow{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \lambda_1 \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} + \lambda_2 \begin{pmatrix} 5 \\ -4 \\ 1 \end{pmatrix}, \quad \lambda_1, \lambda_2 \in \mathbb{R},$$



in point normal form and in expanded Cartesian form.



Checking our answers with Maple

```
> with(LinearAlgebra):
> # Use : instead of ; if you do not want the echo.
v1 := <2,-1,3>:
v2 := <5,-4,1>:
> n := CrossProduct(v1,v2);
                                                 n := \begin{bmatrix} 11 \\ 13 \\ -3 \end{bmatrix}
> # Find a Cartesian equation in point normal form
  a := \langle 1, 2, 3 \rangle:
                                          11 x - 28 + 13 y - 3 z = 0
                                             11 x + 13 y - 3 z = 28
```



Distance from point to a plane

Exercise 5. Find the shortest distance between the point P(4, -2, 3) and the plane passing through the points A(1, 2, 3), B(-3, 2, 1) and C(4, 5, 6).

Shortest dist between P and plane is
$$|\overrightarrow{HP}| = \left| -\frac{1}{6} \left(\frac{1}{2} \right) \right| = \frac{1}{6} \sqrt{1+1+4} = \frac{\sqrt{6}}{6}$$



AN = AB X AC

Distance from point to a plane

Exercise 5, continued. Find the shortest distance between the point P(4,-2,3) and the plane passing through the points A(1,2,3), B(-3,2,1) and C(4,5,6).



Checking our answers with Maple

```
> with (LinearAlgebra):
> # Define position vectors for the
   # points A, B, C and P.
  a := \langle 1, 2, 3 \rangle:
  b := <-3,2,1>:
 c := \langle 4, 5, 6 \rangle:
 p := \langle 4, -2, 3 \rangle:
> # Find the cross product of vectors AB and AC
  AB := b - a:
  AC := c - a:
   n := CrossProduct(AB,AC);
                          n := \left[ \begin{array}{c} 6 \\ 6 \\ -12 \end{array} \right]
> # Let's use a scalar multiple of n
  n1 := 1/6*n;
                         nl := \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}
```

```
> # Project vector AP onto n.

AP := p - a:
d := (AP.n1)/(n1.n1)*n1;
d := \begin{bmatrix} -\frac{1}{6} \\ -\frac{1}{6} \\ \frac{1}{3} \end{bmatrix}
> # The distance from P to the plane is # the length of vector d.

dist := sqrt(d.d);
dist := \frac{\sqrt{6}}{6}
```

