Wilson Lam

225 South Curtis Ave. Apt. D Alhambra CA 91801 • (626) 264-3213 • wilsonlam@ucla.edu

Website: www.wilsonlam.co.nf (visit site for more projects)

EDUCATION

University of California, Los Angeles

Master Degree in Mechanical Engineer, GPA: 3.23

[Expected June 2014] Bachelor of Science in Mechanical Engineer, GPA: 3.25

[2009 - 2013]

Combustion Engine Design

Connecting Rod Design (+FEA)

Heat Transfer and Thermodynamics

Finite Element Analysis (Theory & Coding)

Mechanical Design/Material Strength

Formula SAE vehicle design

Smart Grid Research

Electric Vehicle Design and Implementation

Rapid-Prototyping and Manufacturing

Management & Assembly of Molding & Casting

Dynamic System Control (feedback & control)

Composite Structure Design

SKILLS

Languages

Proficient in: Matlab, Javascript, HTML, CSS, LabVIEW

Familiar with: Visual C++, Java, Python, Mathematica

Software

Platforms: -Windows: XP, 7, Vista, 8; -Linux: Ubuntu, Puppy; -Mac; -Android

CAD Software: Proficient in static, frequency, optimization, thermal, and motion FEA: (Link1)(Link2)

o Abagus

o AutoCAD

 Solidworks Inventor

Comsol

Microsoft Office & Visio Products, Web Design, jQuery, Creative Suite (Dreamweaver, Photoshop, etc.)

Technical Skills

Manufacturing: Mills, lathe, water-jet abrasive cutter, EDM, and Solid Freeform Fabrication (3DP, FDM)

Electronics: Sensors testing and installation, PID control of sensors and actuators, wire soldering, softwarehardware integration, integrated circuit designs, and feedback control.

American Society of Engineers and Architects (secretary managing group activities and meetings)

ENGINEERING PROJECTS

pocketRULER (Rapid-Prototyping with FDM)

[2014]

- Gather data then design and manufacture working prototype.
- Present product, redesign, and remanufacture until product is optimized though rigorous iterations.
- Primary responsibilities include design, develop, present product, and organize group presentations.

Project Panthra (Autonomous Delivery Vehicle)

- Group design, purchase, manufacture, test, and assemble the autonomous vehicle to transverse a designed track carrying 18 lbs. to unloading area. Model in Solidworks then machine or build parts.
- Solder and wire electronic components to H-bridges, sensors, and control board.
- Test multiple sensors with PID for dynamic feedback control of wall distance in real time.

Project Magneton (Solid Freeform Fabrication (SFF) and Manufacturing)

[2011]

Design Solidworks model of Magneton then use SFF, waterjet cutter, EDM, and mill to create the rapidprototype model. CNC is use in the production of some parts.

INTERESTS/ACTIVITIES

Robotics MESA (Link)

ASEA UCLA FSAE (<u>Link 1</u>)(<u>Link 2</u>)

Science Olympiad

Skill USA (Link)