

Lab 4 Report: Implicit Solids

CZ2003 - Computer Graphics & Visualization

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Lab 4 4.1 Implicit Solid

4.2 Bounding Box/Resolution for Efficient Rendering under 5 seconds

4.3 Function-defined Diffuse Color

Reparameterization								
	7	$x = \cos(0.5\theta)(\sin(\varphi))^{3}$ $y = \sin(0.5\theta)(\sin(\varphi))^{3}$ $z = \cos(\varphi)$	0≤θ≤4π	, 0≤φ≤π				
	8	$x = 0.5b\pi \cos(2\theta)$ $y = 0.5\theta - 0.5$ $z = 0.5b\pi \sin(2\theta)$	0≤θ≤π,	0≤b≤1				

To achieve morphing between shape 7 & 8, reparameterization is applied to the parametric equations of both shapes. In this experiment, all the domains (θ , φ for Shape 7 & b, θ for Shape 8) have been **reparametrized to a common base domain** [0,1].

Next, by utilizing a **linear interpolation model with time parameter** *t*, morphing animations can be produced.

Domain Pairing between the 2 Shapes

I have experimented with 2 versions of the morphing.

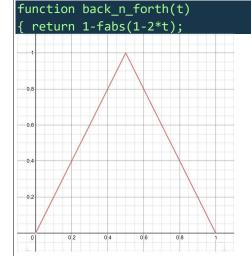
In **morphing7to8_Version1.wrl**, [θ from S7 $\Leftrightarrow b$ from S8] and [φ from S7 $\Leftrightarrow \theta$ from S8].

In morphing7to8_Version2.wrl, [θ from S7 $\Leftrightarrow \theta$ from S8] and [φ from S7 $\Leftrightarrow b$ from S8].

After experimenting with both versions, **morphing7to8_Version1.wrl** may be a better morphing animation as compared to **morphing7to8_Version2.wrl**.

This is so as **morphing7to8_Version1.wrl** animation looks like Shape 7 is unfolding to form Shape 8 which is easy to understand and visualize. In contrast, **morphing7to8_Version2.wrl** animation looks like it is folding into itself which is harder to visualize.





To allow for back and forth animation between the 2 shapes, I have implemented the above function, **back_n_forth(t)**, which takes in parameter *t*. When *t* is cycled through domain [0,1]. It will outure a value from 0 to 1 and since VRML cycles through the domain, we essentially have a periodic triangular function which allows for back and forth animation perpetually.

