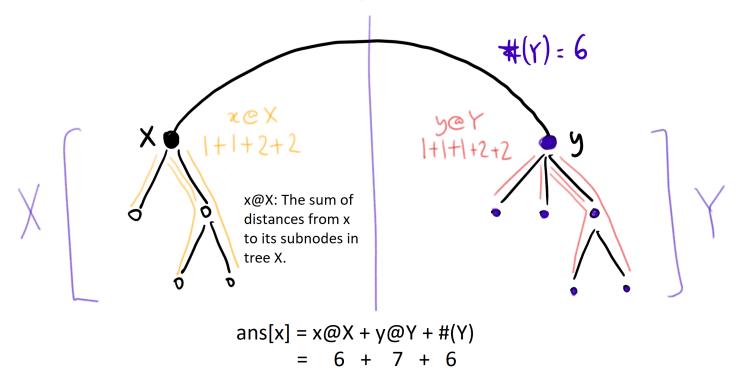
## Approach #1: Subtree Sum and Count [Accepted]

## Intuition

Let ans be the returned answer, so that in particular ans[x] be the answer for node x.

Naively, finding each ans[x] would take O(N) time (where N is the number of nodes in the graph), which is too slow. This is the motivation to find out how ans[x] and ans[y] are related, so that we cut down on repeated work.

Let's investigate the answers of neighboring nodes x and y. In particular, say xy is an edge of the graph, that if cut would form two trees X (containing x) and Y (containing y).



Then, as illustrated in the diagram, the answer for x in the entire tree, is the answer of x on X "x@X", plus the answer of y on Y "y@Y", plus the number of nodes in Y "#(Y)". The last part "#(Y)" is specifically because for any node z in Y, dist(x, z) = dist(y, z) + 1.

By similar reasoning, the answer for y in the entire tree is ans[y] = x@X + y@Y + #(X). Hence, for neighboring nodes x and y, ans[x] - ans[y] = #(Y) - #(X).

## **Algorithm**

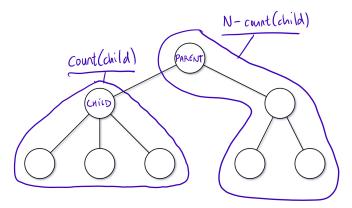
Root the tree. For each node, consider the subtree  $S_{\rm node}$  of that node plus all descendants. Let count[node] be the number of nodes in  $S_{\rm node}$ , and stsum[node] ("subtree sum") be the sum of the distances from node to the nodes in  $S_{\rm node}$ .

We can calculate count and stsum using a post-order traversal, where on exiting some node, the count and stsum of all descendants of this node is correct, and we now calculate count[node] += count[child] and stsum[node] += stsum[child] + count[child].

This will give us the right answer for the root: ans[root] = stsum[root].

Now, to use the insight explained previously: if we have a node parent and it's child child, then these are neighboring nodes, and so ans[child] = ans[parent] - count[child] + (N - count[child]). This is because

there are count[child] nodes that are 1 easier to get to from child than parent, and N-count[child] nodes that are 1 harder to get to from child than parent.



Using a second, pre-order traversal, we can update our answer in linear time for all of our nodes.

## **Complexity Analysis**

- Time Complexity: O(N), where N is the number of nodes in the graph.
- Space Complexity: O(N).