view frames Result Recorded at time: 1724627508.959593 map Broadcaster: default authority Average rate:  $1\overline{0.221}$ Buffer length: 4.892 Most recent transform: 1724627509.118278 Oldest transform: 1724627504.226536 odom Broadcaster: default authority Average rate:  $5\overline{0}.17$ Buffer length: 5.003 Most recent transform: 1724627508.946348 Oldest transform: 1724627503.943337 base footprint Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 base link Broadcaster: default authority Broadcaster: default\_authority Broadcaster: default authority Broadcaster: default authority Average rate:  $\overline{10}.2$ Average rate:  $\overline{10.2}$ Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 5.0 Buffer length: 5.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 1724627508.941771 Most recent transform: 1724627508.941771 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 1724627503.941774 Oldest transform: 1724627503.941774 Oldest transform: 0.0 Oldest transform: 0.0  $caster\_wheel\_link$ left\_wheel\_link right wheel link scan Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 lidar frame top lidar Broadcaster: default authority Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 ld06\_base\_cylinder top lidar ld06\_box\_top\_lidar Broadcaster: default authority Average rate:  $10\overline{0}00.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 ld06\_cylinder\_top\_lidar