

Operational Semantics of Cool

Lecture 13

Lecture Outline

- COOL operational semantics
- Motivation
- Notation
- The rules

Motivation

- We must specify for every Cool expression what happens when it is evaluated
 - This is the “meaning” of an expression
- The definition of a programming language:
 - The tokens \Rightarrow lexical analysis
 - The grammar \Rightarrow syntactic analysis
 - The typing rules \Rightarrow semantic analysis
 - The evaluation rules
 - \Rightarrow code generation and optimization

Evaluation Rules So Far

- We have specified evaluation rules indirectly
 - The compilation of Cool to a stack machine
 - The evaluation rules of the stack machine
- This is a complete description
 - Why isn't it good enough?

Assembly Language Description of Semantics

- Assembly-language descriptions of language implementation have irrelevant detail
 - Whether to use a stack machine or not
 - Which way the stack grows
 - How integers are represented
 - The particular instruction set of the architecture
- We need a complete description
 - But not an overly restrictive specification

Programming Language Semantics

- A multitude of ways to specify semantics
 - All equally powerful
 - Some more suitable to various tasks than others
- Operational semantics
 - Describes program evaluation via execution rules
 - on an abstract machine
 - Most useful for specifying implementations
 - This is what we use for Cool

Other Kinds of Semantics

- Denotational semantics
 - Program's meaning is a mathematical function
 - Elegant, but introduces complications
 - Need to define a suitable space of functions
- Axiomatic semantics
 - Program behavior described via logical formulae
 - If execution begins in state satisfying X , then it ends in state satisfying Y
 - X, Y formulas
 - Foundation of many program verification systems

Introduction to Operational Semantics

- Once again we introduce a formal notation
- Logical rules of inference, as in type checking

Inference Rules

- Recall the typing judgment

$\text{Context} \vdash e : C$

(in the given *context*, expression *e* has type *C*)

- We try something similar for evaluation

$\text{Context} \vdash e : v$

(in the given *context*, expr. *e* evaluates to value *v*)

Example Operational Semantics Rule

- Example:

$$\frac{\begin{array}{l} \text{Context} \vdash e_1 : 5 \\ \text{Context} \vdash e_2 : 7 \end{array}}{\text{Context} \vdash e_1 + e_2 : 12}$$

- The result of evaluating an expression can depend on the result of evaluating its subexpressions
- The rules specify everything that is needed to evaluate an expression

Contexts are Needed for Variables

- Consider the evaluation of $y \leftarrow x + 1$
 - We need to keep track of values of variables
 - We need to allow variables to change their values during evaluation
- We track variables and their values with:
 - An environment : tells us *where* in memory a variable is stored
 - A store : tells us *what* is in memory

Variable Environments

- A variable environment is a map from variable names to locations
 - Tells in what memory location the value of a variable is stored
 - Keeps track of which variables are in scope
- Example:
$$E = [a : l_1, b : l_2]$$
- $E(a)$ looks up variable a in environment E

Stores

- A store maps memory locations to values
- Example:

$$S = [l_1 \rightarrow 5, l_2 \rightarrow 7]$$

- $S(l_1)$ is the contents of a location l_1 in store S
- $S' = S[12/l_1]$ defines a store S' such that
$$S'(l_1) = 12 \quad \text{and} \quad S'(l) = S(l) \text{ if } l \neq l_1$$

Cool Values

- Cool values are objects
 - All objects are instances of some class
- $X(a_1 = l_1, \dots, a_n = l_n)$ is a Cool object where
 - X is the class of the object
 - a_i are the attributes (including inherited ones)
 - l_i is the location where the value of a_i is stored

Cool Values (Cont.)

- Special cases (classes without attributes)

`Int(5)` the integer 5

`Bool(true)` the boolean true

`String(4, "Cool")` the string "Cool" of length 4

- There is a special value `void` of type `Object`
 - No operations can be performed on it
 - Except for the test `isvoid`
 - Concrete implementations might use NULL here

Operational Rules of Cool

- The evaluation judgment is

$$so, E, S \vdash e : v, S'$$

read:

- Given so the current value of $self$
- And E the current variable environment
- And S the current store
- If the evaluation of e terminates then
- The return value is v
- And the new store is S'

Notes

- “Result” of evaluation is a value and a store
 - New store models the side-effects
- Some things don't change
 - The variable environment
 - The value of *self*
 - The operational semantics allows for non-terminating evaluations

Operational Semantics for Base Values

$so, E, S \vdash \text{true} : \text{Bool}(\text{true}), S$

$so, E, S \vdash \text{false} : \text{Bool}(\text{false}), S$

i is an integer literal

$so, E, S \vdash i : \text{Int}(i), S$

s is a string literal

n is the length of s

$so, E, S \vdash s : \text{String}(n,s), S$

- No side effects in these cases
(the store does not change)

Operational Semantics of Variable References

$$\frac{\begin{array}{l} E(id) = l_{id} \\ S(l_{id}) = v \end{array}}{so, E, S \vdash id : v, S}$$

- Note the double lookup of variables
 - First from name to location
 - Then from location to value
- The store does not change

Operational Semantics for Self

- A special case:

$$\text{so, } E, S \vdash \text{self} : \text{so, } S$$

Operational Semantics of Assignment

$$\frac{\begin{array}{l} \text{so, } E, S \vdash e : v, S_1 \\ E(\text{id}) = l_{\text{id}} \\ S_2 = S_1[v/l_{\text{id}}] \end{array}}{\text{so, } E, S \vdash \text{id} \leftarrow e : v, S_2}$$

- Three step process
 - Evaluate the right hand side
 \Rightarrow a value v and new store S_1
 - Fetch the location of the assigned variable
 - The result is the value v and an updated store

Operational Semantics of Conditionals

$$\frac{\begin{array}{c} \text{so, } E, S \vdash e_1 : \text{Bool}(\text{true}), S_1 \\ \text{so, } E, S_1 \vdash e_2 : v, S_2 \end{array}}{\text{so, } E, S \vdash \text{if } e_1 \text{ then } e_2 \text{ else } e_3 : v, S_2}$$

- The “threading” of the store enforces an evaluation sequence
 - e_1 must be evaluated first to produce S_1
 - Then e_2 can be evaluated
- The result of evaluating e_1 is a **Bool**. Why?

Operational Semantics of Sequences

$$\frac{\begin{array}{c} \text{so, E, S} \vdash e_1 : v_1, S_1 \\ \text{so, E, S}_1 \vdash e_2 : v_2, S_2 \\ \dots \\ \text{so, E, S}_{n-1} \vdash e_n : v_n, S_n \end{array}}{\text{so, E, S} \vdash \{ e_1; \dots; e_n; \} : v_n, S_n}$$

- Again the threading of the store expresses the required evaluation sequence
- Only the last value is used
- But all the side-effects are collected

Operational Semantics of **while** (I)

$$\frac{so, E, S \vdash e_1 : \text{Bool}(\text{false}), S_1}{so, E, S \vdash \text{while } e_1 \text{ loop } e_2 \text{ pool} : \text{void}, S_1}$$

- If e_1 evaluates to **false** the loop terminates
 - With the side-effects from the evaluation of e_1
 - And with result value **void**
- Type checking ensures e_1 evaluates to a **Bool**

Operational Semantics of **while** (II)

$$\frac{\begin{array}{c} \text{so, } E, S \vdash e_1 : \text{Bool}(\text{true}), S_1 \\ \text{so, } E, S_1 \vdash e_2 : v, S_2 \\ \text{so, } E, S_2 \vdash \text{while } e_1 \text{ loop } e_2 \text{ pool} : \text{void}, S_3 \end{array}}{\text{so, } E, S \vdash \text{while } e_1 \text{ loop } e_2 \text{ pool} : \text{void}, S_3}$$

- Note the sequencing ($S \rightarrow S_1 \rightarrow S_2 \rightarrow S_3$)
- Note how looping is expressed
 - Evaluation of “**while ...**” is expressed in terms of the evaluation of itself in another state
- The result of evaluating e_2 is discarded
 - Only the side-effect is preserved

Operational Semantics of **let** Expressions (I)

$$\frac{\begin{array}{l} \text{so, } E, S \vdash e_1 : v_1, S_1 \\ \text{so, } ?, ? \vdash e_2 : v_2, S_2 \end{array}}{\text{so, } E, S \vdash \text{let id : } T \leftarrow e_1 \text{ in } e_2 : v_2, S_2}$$

- In what context should e_2 be evaluated?
 - Environment like E but with a new binding of id to a fresh location l_{new}
 - Store like S_1 but with l_{new} mapped to v_1

Operational Semantics of **let** Expressions (II)

- We write $l_{\text{new}} = \text{newloc}(S)$ to say that l_{new} is a location not already used in S
 - newloc is like the memory allocation function
- The operational rule for **let**:

$$\frac{\begin{array}{l} \text{so, } E, S \vdash e_1 : v_1, S_1 \\ l_{\text{new}} = \text{newloc}(S_1) \\ \text{so, } E[l_{\text{new}}/\text{id}], S_1[v_1/l_{\text{new}}] \vdash e_2 : v_2, S_2 \end{array}}{\text{so, } E, S \vdash \text{let id : T} \leftarrow e_1 \text{ in } e_2 : v_2, S_2}$$

Operational Semantics of `new`

- Informal semantics of `new T`
 - Allocate locations to hold all attributes of an object of class `T`
 - Essentially, allocate a new object
 - Initialize attributes with their default values
 - Evaluate the initializers and set the resulting attribute values
 - Return the newly allocated object

Default Values

- For each class A there is a default value denoted by D_A
 - $D_{\text{int}} = \text{Int}(0)$
 - $D_{\text{bool}} = \text{Bool}(\text{false})$
 - $D_{\text{string}} = \text{String}(0, "")$
 - $D_A = \text{void}$ (for any other class A)

More Notation

- For a class A we write

$\text{class}(A) = (a_1 : T_1 \leftarrow e_1, \dots, a_n : T_n \leftarrow e_n)$ where

- a_i are the attributes (including the inherited ones)
- T_i are their declared types
- e_i are the initializers

Operational Semantics of new

- `new SELF_TYPE` allocates an object with the same dynamic type as `self`

$$\begin{aligned} T_0 &= \text{if } (T == \text{SELF_TYPE} \text{ and } \text{so} = X(\dots)) \text{ then } X \text{ else } T \\ \text{class}(T_0) &= (a_1 : T_1 \leftarrow e_1, \dots, a_n : T_n \leftarrow e_n) \\ l_i &= \text{newloc}(S) \text{ for } i = 1, \dots, n \\ v &= T_0(a_1 = l_1, \dots, a_n = l_n) \\ S_1 &= S[D_{T_1}/l_1, \dots, D_{T_n}/l_n] \\ E' &= [a_1 : l_1, \dots, a_n : l_n] \\ v, E', S_1 &\vdash \{ a_1 \leftarrow e_1; \dots; a_n \leftarrow e_n; \} : v_n, S_2 \\ \hline \text{so}, E, S &\vdash \text{new } T : v, S_2 \end{aligned}$$

Notes on Operational Semantics of **new**.

- The first three steps allocate the object
- The remaining steps initialize it
 - By evaluating a sequence of assignments
- State in which the initializers are evaluated
 - Self is the current object
 - Only the attributes are in scope (same as in typing)
 - Initial values of attributes are the defaults

Operational Semantics of Method Dispatch

- Informal semantics of $e_0.f(e_1, \dots, e_n)$
 - Evaluate the arguments in order e_1, \dots, e_n
 - Evaluate e_0 to the target object
 - Let X be the dynamic type of the target object
 - Fetch from X the definition of f (with n args.)
 - Create n new locations and an environment that maps f 's formal arguments to those locations
 - Initialize the locations with the actual arguments
 - Set $self$ to the target object and evaluate f 's body

More Notation

- For a class A and a method f of A (possibly inherited) we write:

$\text{impl}(A, f) = (x_1, \dots, x_n, e_{\text{body}})$ where

- x_i are the names of the formal arguments
- e_{body} is the body of the method

Operational Semantics of Dispatch

$$\begin{array}{l}
 so, E, S \vdash e_1 : v_1, S_1 \\
 so, E, S_1 \vdash e_2 : v_2, S_2 \\
 \dots \\
 so, E, S_{n-1} \vdash e_n : v_n, S_n \\
 so, E, S_n \vdash e_0 : v_0, S_{n+1} \\
 v_0 = X(a_1 = l_1, \dots, a_m = l_m) \\
 \text{impl}(X, f) = (x_1, \dots, x_n, e_{\text{body}}) \\
 l_{x_i} = \text{newloc}(S_{n+1}) \text{ for } i = 1, \dots, n \\
 E' = [a_1 : l_1, \dots, a_m : l_m][x_1/l_{x_1}, \dots, x_n/l_{x_n}] \\
 S_{n+2} = S_{n+1}[v_1/l_{x_1}, \dots, v_n/l_{x_n}] \\
 v_0, E', S_{n+2} \vdash e_{\text{body}} : v, S_{n+3} \\
 \hline
 so, E, S \vdash e_0.f(e_1, \dots, e_n) : v, S_{n+3}
 \end{array}$$

Notes on Operational Semantics of Dispatch

- The body of the method is invoked with
 - **E** mapping formal arguments and self's attributes
 - **S** like the caller's except with actual arguments bound to the locations allocated for formals
- The notion of the frame is implicit
 - New locations are allocated for actual arguments
- The semantics of static dispatch is similar

Runtime Errors

Operational rules do not cover all cases

Consider the dispatch example:

$$\frac{\begin{array}{l} \dots \\ so, E, S_n \vdash e_0 : v_0, S_{n+1} \\ v_0 = X(a_1 = l_1, \dots, a_m = l_m) \\ impl(X, f) = (x_1, \dots, x_n, e_{body}) \\ \dots \end{array}}{so, E, S \vdash e_0.f(e_1, \dots, e_n) : v, S_{n+3}}$$

What happens if $impl(X, f)$ is not defined?

Cannot happen in a well-typed program

Runtime Errors (Cont.)

- There are some runtime errors that the type checker does not prevent
 - A dispatch on void
 - Division by zero
 - Substring out of range
 - Heap overflow
- In such cases execution must abort gracefully
 - With an error message, not with segfault

Conclusions

- Operational rules are very precise & detailed
 - Nothing is left unspecified
 - Read them carefully
- Most languages do not have a well specified operational semantics
- When portability is important an operational semantics becomes essential