Formal Methods and Functional Programming

Axiomatic Semantics

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Program Correctness

- Formal semantics can be used to prove the correctness of a program
- Partial correctness expresses that if a program terminates then there
 will be a certain relationship between the initial and the final state
- Total correctness expresses that a program will terminate and there will be a certain relationship between the initial and the final state
 - The relationship is expressed by a formal specification

 $total\ correctness = partial\ correctness + termination$

4. Axiomatic Semantics

- 4.1 Motivation
- 4.2 Hoare Logic
- 4.3 Soundness and Completeness

Program Correctness: Example

Consider the factorial statement

```
y := 1;
while not x = 1 do
    y := y * x;
    x := x - 1
end
```

- Specification:
 The final value of y is the factorial of the initial value of x
- The statement is partially correct
 - It does not terminate for x < 1

Formal Specification

- Specification: The final value of y is the factorial of the initial value of x
- We can express the specification formally based on a formal semantics

```
\forall \sigma, \sigma'.
\vdash \langle y := 1; \text{while not } x = 1 \text{ do } y := y * x; x := x - 1 \text{ end}, \sigma \rangle \rightarrow \sigma'
\Rightarrow \sigma'(y) = \sigma(x)! \land \sigma(x) > 0
```

- This specification expresses partial correctness using big-step semantics
 - We could have used small-step semantics to formulate the property, instead

Correctness Proof

- We prove partial correctness in three steps
- Step 1: The body of the loop satisfies

$$\forall \sigma, \sigma''. \vdash \langle y := y*x; x := x-1, \sigma \rangle \to \sigma'' \land \sigma''(x) > 0 \Rightarrow \sigma(y) \times \sigma(x)! = \sigma''(y) \times \sigma''(x)! \land \sigma(x) > 0$$

Step 2: The loop satisfies

$$\forall \sigma, \sigma''$$
. $\vdash \langle \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end}, \sigma \rangle \rightarrow \sigma'' \Rightarrow \sigma(y) \times \sigma(x)! = \sigma''(y) \wedge \sigma''(x) = 1 \wedge \sigma(x) > 0$

• Step 3: The whole statement is partially correct

$$\forall \sigma, \sigma'$$
. $\vdash \langle y := 1; \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end}, \sigma \rangle \rightarrow \sigma' \Rightarrow \sigma'(y) = \sigma(x)! \land \sigma(x) > 0$

Proof: Step 1—Loop Body

- Let σ and σ'' be arbitrary. To prove the implication, we assume the left-hand-side and prove the right.
- Since we have $\vdash \langle y := y*x; x := x-1, \sigma \rangle \to \sigma''$, we can assume that both $\vdash \langle y := y*x, \sigma \rangle \to \sigma'$ and $\vdash \langle x := x-1, \sigma' \rangle \to \sigma''$ for some σ' (the last rule applied in the original derivation must be Seq_{NS})
- Since these two derivations must end in the Ass_{NS} rule, we must have $\sigma' = \sigma[y \mapsto \mathcal{A}[[y*x]]\sigma]$ and $\sigma'' = \sigma'[x \mapsto \mathcal{A}[[x-1]]\sigma']$, which together imply that $\sigma'' = \sigma[y \mapsto \sigma(y) \times \sigma(x)][x \mapsto \sigma(x)-1]$
- By $\sigma''(x) > 0$, we calculate

$$\sigma''(y) \times \sigma''(x)! = \sigma(y) \times \sigma(x) \times (\sigma(x)-1)! = \sigma(y) \times \sigma(x)!$$

• Finally, by $\sigma''(x) = \sigma(x) - 1$, we get $\sigma(x) > 0$



Proof: Step 2—Loop

Step 2: The loop satisfies

$$\forall \sigma, \sigma''$$
. $\vdash \langle \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end}, \sigma \rangle \rightarrow \sigma'' \Rightarrow \sigma(y) \times \sigma(x)! = \sigma''(y) \wedge \sigma''(x) = 1 \wedge \sigma(x) > 0$

- We prove this property by induction on the shape of the derivation tree:
- Define P(T):

$$P(T) \equiv \forall \sigma, \sigma''.$$

$$root(T) \equiv \langle \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end}, \sigma \rangle \rightarrow \sigma'' \Rightarrow$$

$$\sigma(y) \times \sigma(x)! = \sigma''(y) \wedge \sigma''(x) = 1 \wedge \sigma(x) > 0$$

• We prove P(T) for arbitrary T, with the induction hypothesis $\forall T' \vdash T.P(T')$ (i.e., we can assume the property for all subderivations of the derivation tree T).

Proof: Step 2—Loop (Case WhFNS)

- We prove P(T) for arbitrary T, with the induction hypothesis $\forall T' \vdash T.P(T')$ (i.e., we can assume the property for all subderivations of the derivation tree T.
- Let σ , σ'' be arbitrary. We assume the property above for root(T), and need to show that $\sigma(y) \times \sigma(x)! = \sigma''(y) \wedge \sigma''(x) = 1 \wedge \sigma(x) > 0$
- We consider the two possible cases for the last rule applied in T: WhF_{NS} and WhT_{NS}

• Case WhF_{NS}:

- From the form of the rule, we must have $\sigma(x) = 1$ and $\sigma = \sigma''$
- Since 1 = 1!, we get $\sigma(y) \times \sigma(x)! = \sigma(y) = \sigma''(y)$
- We also immediately get $\sigma''(x) = 1$ and $\sigma(x) > 0$



Proof: Step 2—Loop (Case WhT $_{NS}$)

• From the form of the rule, we know that two subderivations exist: for some σ''' ,

(1)
$$\vdash \langle y := y*x; x := x-1, \sigma \rangle \rightarrow \sigma'''$$

(2)
$$\vdash$$
 (while not x = 1 do y := y*x;x := x-1 end, σ''') $\rightarrow \sigma''$

- Applying the induction hypothesis to (2) yields $\sigma'''(y) \times \sigma'''(x)! = \sigma''(y) \wedge \sigma''(x) = 1 \wedge \sigma'''(x) > 0$
- By (1), $\sigma'''(x) > 0$, and Proof Step 1, we get $\sigma(y) \times \sigma(x)! = \sigma'''(y) \times \sigma'''(x)! \wedge \sigma(x) > 0$
- Combining these results yields, as required: $\sigma(y) \times \sigma(x)! = \sigma''(y) \wedge \sigma''(x) = 1 \wedge \sigma(x) > 0$

Proof: Step 3—Factorial Statement

• Step 3: The whole statement is partially correct:

$$\forall \sigma, \sigma'$$
. $\vdash \langle y := 1; \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end}, \sigma \rangle \rightarrow \sigma' \Rightarrow \sigma'(y) = \sigma(x)! \land \sigma(x) > 0$

- Let σ , σ' be arbitrary. The last rule applied in the assumed derivation must be Seq_{NS} .
- From the form of the rule, we get, for some σ'' :

(1)
$$\vdash \langle y := 1, \sigma \rangle \rightarrow \sigma''$$

(2)
$$\vdash$$
 (while not x = 1 do y := y*x;x := x-1 end, σ'') $\rightarrow \sigma'$

- By (1), we get $\sigma'' = \sigma[y \mapsto 1]$ and, thus, $\sigma''(x) = \sigma(x)$
- By (2), and Proof Step 2, we get $\sigma''(y) \times \sigma''(x)! = \sigma'(y) \wedge \sigma'(x) = 1 \wedge \sigma''(x) > 0$
- We conclude, as required: $1 \times \sigma(x)! = \sigma'(y) \wedge \sigma(x) > 0$



Verification Example: Observations

- We can prove correctness of a program based on a formal semantics
 - The proof would also be possible with the small-step semantics, but even more complicated
- Proofs are too detailed to be practical
 - We have to consider how whole states are modified
 - We would like to focus on certain properties of states
 - We need to manually decompose the proof into suitable parts
 - For each loop, we need to formulate a separate induction on derivations
- Axiomatic Semantics provides a way of constructing these proofs conveniently
 - Proofs can focus only on essential properties of interest
 - Decomposing the program into smaller parts happens naturally
 - The induction for reasoning about loops is "built" into the semantic rule for loops



4. Axiomatic Semantics

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- 4.2 Hoare Logic
 - 4.2.1 Hoare Triples and Assertions
 - 4.2.2 Derivation System
 - 4.2.3 Total Correctness (Termination)
- 4.3 Soundness and Completeness

Hoare Triples

Properties of programs are specified as Hoare triples

$$\{ \mathbf{P} \} s \{ \mathbf{Q} \}$$

where s is a statement and P and Q are assertions (about the state)

- Terminology
 - The assertion **P** is called the precondition of a triple $\{ P \} s \{ Q \}$
 - The assertion \mathbf{Q} is called the postcondition of a triple $\{\mathbf{P}\} s \{\mathbf{Q}\}$
 - Assertions are boolean expressions, with some additional features (explained shortly). We use **P**, **Q**, **R** as meta-variables over assertions.

Meaning of Hoare Triples

ullet The informal meaning of $\{ \ {f P} \ \} \ s \ \{ \ {f Q} \ \}$ is

```
If P evaluates to true in an initial state \sigma, and if the execution of s from \sigma terminates in a state \sigma' then Q will evaluate to true in \sigma'
```

- This meaning describes partial correctness, that is, termination is not an essential property
- It is also possible to assign different meanings to Hoare Triples
 - Total correctness interpretation (see later)

Hoare Triples: Example

Attempted specification of the factorial statement:

```
{ true } 
y := 1; while not x = 1 do y := y*x; x := x-1 end 
{ y = x! \land x > 0 }
```

- In general, this Hoare triple is not correct. For example:
 - Consider an initial state $\sigma_{zero}[x \mapsto 2][y \mapsto 0]$
 - The final state will be $\sigma_{zero}[x \mapsto 1][y \mapsto 2]$
- We need to express that y in the final state is the factorial of x in the initial state
 - We need a way for assertions to describe properties not just of the current state, but also of the initial state

Logical Variables

- We allow assertions to contain logical variables
 - Logical variables may occur only in assertions
 - Logical variables are not program variables and may, thus, not be accessed in programs; in particular, they are never assigned to
- Logical variables can be used to "save" values in the initial state, so that they can be referred to later

```
 \left\{ \begin{array}{l} x = N \\ y := 1; \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end} \\ \left\{ \begin{array}{l} y = N! \land N > 0 \end{array} \right\} \end{array}
```

States map logical variables (and program variables) to their values

Assertion Language

- Pre- and postconditions are assertions, that is, boolean expressions plus logical variables
 - In particular, we will use program boolean expressions b as assertions
 - It is common in practice to use a richer set of expressions for assertions, for instance, to include quantification
 - We will use additional expressions when it is convenient (e.g., x!)
 - We assume that the substitution lemma from the exercises still holds when we use an extended assertion language:

$$\mathcal{B}[[\mathbf{P}[x \mapsto e]]]\sigma = \mathcal{B}[[\mathbf{P}]]\sigma[x \mapsto \mathcal{A}[[e]]\sigma]$$

- We will use the following convenient notations
 - " $P_1 \wedge P_2$ " for " P_1 and P_2 "
 - " $P_1 \vee P_2$ " for " P_1 or P_2 "
 - " $\neg P$ " for "not P"



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Axiomatic Semantics: Derivation System

- We formalize an axiomatic semantics of IMP by describing the valid Hoare triples
- This is done by a derivation system
 - The derivation rules specify which triples can be derived for each statement
 - The premises and conclusions of the derivation rules are Hoare triples

$$\{ \mathbf{P} \} s \{ \mathbf{Q} \}$$

- Derivation trees (using the rules presented next) are defined as before
- Similarly to the other derivation systems we have studied, we write
 ⊢ { P } s { Q } if and only if there exists a (finite) derivation tree ending in { P } s { Q }

$$\bullet \vdash \{ P \} s \{ Q \} \Leftrightarrow \exists T.root(T) \equiv \{ P \} s \{ Q \}$$

Axiomatic Semantics of IMP

skip does not modify the state

$$\frac{1}{\{ \mathbf{P} \} \operatorname{skip} \{ \mathbf{P} \}} (\operatorname{SKIP}_{\mathcal{A}_{\mathcal{X}}})$$

• x := e assigns the value of e to variable x

$$\frac{}{\{ \mathbf{P}[x \mapsto e] \} x := e \{ \mathbf{P} \}} (Ass_{Ax})$$

- Let σ be the initial state
- Precondition: $\mathcal{B}[[\mathbf{P}[x \mapsto e]]]\sigma$, which is equivalent to $\mathcal{B}[[\mathbf{P}]]\sigma[x \mapsto \mathcal{A}[[e]]\sigma]$ (substitution lemma)
- Final state: $\sigma[x \mapsto \mathcal{A}[[e]]\sigma]$
- ullet Consequently, $\mathcal{B}[[\mathbf{P}]]$ holds in the final state
- Reminder: these are rule schemes (they can be instantiated by replacing meta-variables)

Sequential composition s;s'

$$\frac{\left\{\begin{array}{c}\mathbf{P}\right\}s\left\{\left[\mathbf{Q}\right]\right\}\left\{\left[\mathbf{R}\right]\right\}}{\left\{\left[\mathbf{P}\right\}s;s'\left\{\left[\mathbf{R}\right]\right\}\right.}\left(\operatorname{Seq}_{\mathcal{A}_{\mathcal{X}}}\right)$$

• Conditional statement if b then s_1 else s_2 end

$$\frac{\left\{\begin{array}{ll}b\wedge\mathbf{P}\right\}s\left\{\left.\mathbf{Q}\right.\right\}}{\left\{\left.\mathbf{P}\right.\right\}\text{ if }b\text{ then }s\text{ else }s'\text{ end }\left\{\left.\mathbf{Q}\right.\right\}}\left(\mathrm{If}_{\mathcal{A}_{\mathcal{X}}}\right)$$

Loop statement while b do s end

$$\frac{\left\{ \right.b\wedge\mathsf{P}\left.\right\} s\left\{\right.\mathsf{P}\left.\right\} }{\left\{\right.\mathsf{P}\left.\right\} \text{ while }b\text{ do }s\text{ end }\left\{\right.\neg b\wedge\mathsf{P}\left.\right\} }\left(\mathrm{WH}_{\mathcal{A}_{\mathcal{X}}}\right)$$

• The assertion **P** is the loop invariant

- The rules so far manipulate assertions syntactically
 - For example, so far, we cannot derive the triple $\{x = 4 \land y = 5\}$ skip $\{y = 5 \land x = 4\}$ (assertions are not identical, so this is not an instance of the $SKIP_{Ax}$ rule)
 - During proofs, we often need to perform semantic reasoning (e.g., applying mathematical properties of factorial, arithmetic rules, etc.)

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- Semantic entailment expresses these reasoning steps: we write $\mathbf{P} \models \mathbf{Q}$ iff "for all states σ , $\mathcal{B}[[P]]\sigma = tt$ implies $\mathcal{B}[[Q]]\sigma = tt$ "

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- The rule of consequence allows semantic entailments in derivations

$$\frac{\{ \mathbf{P}' \} s \{ \mathbf{Q}' \}}{\{ \mathbf{P} \} s \{ \mathbf{Q} \}} (Cons_{Ax}) \qquad if \mathbf{P} \models \mathbf{P}' \text{ and } \mathbf{Q}' \models \mathbf{Q}$$

- We can strengthen preconditions (P cannot be weaker than P')
- We can weaken postconditions (\mathbf{Q} cannot be stronger than \mathbf{Q}')



Derivation Trees: Example 1

 \bullet Prove that the following statement swaps the values in the variables x and y

$$(z:=x; x:=y); y:=z$$

We can build the following derivation tree

$$\frac{\left\{\begin{array}{l} \mathbf{P}\right\}z:=x\;\left\{\;z=X_{0}\;\wedge\;y=Y_{0}\;\right\}}{\left\{\begin{array}{l} \mathbf{P}\right\}z:=x\;\left\{\;y=Y_{0}\;\wedge\;z=X_{0}\;\right\}} & \left(\operatorname{Cons}_{A_{X}}\right)^{*} \\ \hline \left\{\begin{array}{l} \mathbf{P}\right\}z:=x\;\left\{\;y=Y_{0}\;\wedge\;z=X_{0}\;\right\}\;x:=y\;\left\{\begin{array}{l} \mathbf{Q}'\end{array}\right\} & \left(\operatorname{Ass}_{A_{X}}\right) \\ \hline \left\{\begin{array}{l} \mathbf{P}\right\}z:=x\;;\;\;x:=y\;\left\{\begin{array}{l} \mathbf{Q}'\end{array}\right\} & \left(\operatorname{Ass}_{A_{X}}\right) \\ \hline \left\{\begin{array}{l} \mathbf{P}\right\}\left(z:=x\;;\;\;x:=y\right)\;;\;\;y:=z\;\left\{\begin{array}{l} \mathbf{Q}\end{array}\right\} & \left(\operatorname{Ass}_{A_{X}}\right) \\ \hline \left\{\begin{array}{l} \mathbf{P}\right\}\left(z:=x\;;\;\;x:=y\right)\;;\;\;y:=z\;\left\{\begin{array}{l} \mathbf{Q}\end{array}\right\} & \left(\operatorname{Ass}_{A_{X}}\right) \\ \end{array} \\ \end{array}$$

where we write:

• **P** for
$$x = X_0 \land y = Y_0$$

• **Q** for
$$x = Y_0 \wedge y = X_0$$

•
$$\mathbf{Q}'$$
 for $\mathbf{x} = Y_0 \wedge \mathbf{z} = X_0$



Derivation Trees: Example 2

Consider the non-terminating loop

while true do skip end

We can build the following derivation tree

```
\frac{-\frac{1}{\{\text{ true }\}\text{ skip }\{\text{ true }\}}(\text{SKIP}_{Ax})}{\{\text{ true }\land\text{ true }\}\text{ skip }\{\text{ true }\}}(\text{CONS}_{Ax})^{1}}
\frac{\{\text{ true }\}\text{ while true do skip end }\{\neg\text{true }\land\text{ true }\}}{\{\text{ true }\}\text{ while true do skip end }\{\neg\text{true }\}}(\text{CONS}_{Ax})^{2}}
\frac{1}{\{\text{ true }\land\text{ true }\vDash\text{ true }\}}
```

This proof illustrates that we have partial correctness

Proof Outlines

- Derivation trees tend to get very large and are, thus, inconvenient to write
 - Most statements are written many times
 - Many assertions are written many times

An alternative is to group the assertions around the program text

 We write assertions before and after each statement to indicate which properties hold in the states before and after the execution of this statement

Proof Outlines: Notation

• We write instances of the $SKIP_{Ax}$ and Ass_{Ax} rules as:

$$\left\{ \begin{array}{l} \mathbf{P}[x \mapsto e] \right\} \\ x := e \\ \left\{ \begin{array}{l} \mathbf{P} \end{array} \right\}$$

• We write an instance of the rule for sequential composition as:

- This expresses $\vdash \{ \mathbf{P} \} s_1 \{ \mathbf{Q} \}, \vdash \{ \mathbf{Q} \} s_2 \{ \mathbf{R} \}, \text{ and } \vdash \{ \mathbf{P} \} s_1; s_2 \{ \mathbf{R} \}$
- Note: we write each statement and the intermediate assertion **Q** once

Proof Outlines: Notation (cont'd)

 We write an instance of the rule for conditional statements as:

```
{ P }
   if b then
        \{b \land P\}
           S<sub>1</sub>
       { Q }
   else
       \{ \neg b \land \mathbf{P} \}
           S<sub>2</sub>
        { Q }
   end
{ Q }
```

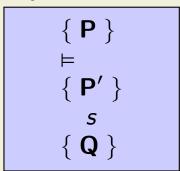
 We write an instance of the rule for loops as:

```
while b do
        \{b \land \mathbf{P}\}
        { P }
    end
\{ \neg b \land \mathbf{P} \}
```

Proof Outlines: Notation (cont'd)

• We write an instance of the rule of consequence as:

• We omit the entailment step when P and P' or Q and Q' are syntactically identical. For example, we may also write:



Proof Outlines: Example

Back to our swap-example:

$$(z:=x; x:=y); y:=z$$

Proof outline:

{
$$x = X_0 \land y = Y_0$$
 }
 $=$ { $y = Y_0 \land x = X_0$ }
 $z := x;$
{ $y = Y_0 \land z = X_0$ }
 $x := y;$
{ $x = Y_0 \land z = X_0$ }
 $y := z$
{ $x = Y_0 \land y = X_0$ }

Proof outlines are often best developed bottom-up

Verification of Factorial Statement

```
\{ x = N \}
y := 1; while not x = 1 do y := y*x; x := x-1 end
\{ y = N! \land N > 0 \}
```

Verification of Factorial Statement

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\{ x = N \}
y := 1; while not x = 1 do y := y*x; x := x-1 end
\{ y = N! \land N > 0 \}
```

Determining the loop invariant

I teration	0	1	2	i	N-1
х	N	N-1	N-2	N-i	1
У	1	N	N*(N-1)	N*(N-1)**(N-i+1)	N!

Verification of Factorial Statement

```
\{ x = N \}
y := 1; while not x = 1 do y := y*x; x := x-1 end
\{ y = N! \land N > 0 \}
```

Determining the loop invariant

Iteration	0	1	2	i	N-1
x	N	N-1	N-2	N-i	1
У	1	N	N*(N-1)	N*(N-1)**(N-i+1)	N!

• Invariant: $x > 0 \Rightarrow y*x! = N! \land N \ge x$

Proof Outline for Factorial Statement

```
\{ \mathbf{x} = \mathbf{N} \}
\{ x > 0 \Rightarrow 1*x! = N! \land N \ge x \}
   |y := 1;|
\{ x > 0 \Rightarrow y * x! = N! \land N \ge x \}
   while not x = 1 do
   \{ x \neq 1 \land (x > 0 \Rightarrow y*x! = N! \land N \geq x) \}
   \{ x-1 > 0 \Rightarrow y*x*(x-1)! = N! \land N \ge x-1 \}
       y := y*x;
   \{x-1>0 \Rightarrow y*(x-1)! = N! \land N \ge x-1\}
       |x := x-1|
   \{ x > 0 \Rightarrow y*x! = N! \land N \ge x \}
   end
\{ x = 1 \land (x > 0 \Rightarrow y*x! = N! \land N \ge x) \}
\{ y = N! \wedge N > 0 \}
```

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Total Correctness

- We introduce an alternative form of Hoare triple $\{ \mathbf{P} \} s \{ \downarrow \mathbf{Q} \}$
- The informal meaning of $\{ \mathbf{P} \} s \{ \downarrow \mathbf{Q} \}$ is

If ${\bf P}$ evaluates to true in the initial state σ then the execution of ${\bf s}$ from σ terminates and ${\bf Q}$ will evaluate to true in the final state

- This meaning describes total correctness, that is, termination is required
- We do not mix these triples with those of partial correctness; the two form two separate axiomatic semantics (and corresponding derivation systems)
- However, all total correctness derivation rules are analogous to those for partial correctness, except for the rule for loops

Loop Variants

- Termination is proved using loop variants
- A loop variant is an expression that evaluates to a value in a well-founded set (for instance, \mathbb{N}) before each iteration
- Each loop iteration must decrease the value of the loop variant
- The loop has to terminate when a minimal value of the well-founded set is reached (or earlier than this)
- For example:

```
x := 5;
while x # 0 do x := x - 1 end
```

x is a possible loop variant for this loop

While Rule for Total Correctness

- ullet For simplicity, we consider loop variants that evaluate to values in ${\mathbb N}$
 - We use arithmetic expressions e of IMP to represent loop variants
 - We prove explicitly that the value of e will be non-negative before each loop iteration
 - Intuition: a correct loop variant provides an upper bound on the number of loop iterations
- Total correctness derivation rule for loops:

```
\frac{\{b \land \mathbf{P} \land e = Z\} s \{ \downarrow \mathbf{P} \land e < Z\}}{\{\mathbf{P}\} \text{ while } b \text{ do } s \text{ end } \{ \downarrow \neg b \land \mathbf{P} \}} (\text{WHTOT}_{Ax}) \text{ if } b \land \mathbf{P} \models 0 \le e
```

where Z is a fresh logical variable (not used in \mathbf{P})

Note: in practice, other well-founded sets and orderings can be useful

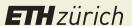
Total Correctness of Factorial

```
 \left\{ \begin{array}{l} x = N \wedge x > 0 \\ y := 1; \text{while not } x = 1 \text{ do } y := y*x; x := x-1 \text{ end} \\ \left\{ \begin{array}{l} \downarrow y = N! \end{array} \right\}
```

- Invariant: $P \equiv x > 0 \land N > 0 \land y*x! = N!$
- Variant: x
- In the proof outline (on the next slide) we explicitly note the side-condition for the while-rule, concerning the loop variant

Proof Outline for Factorial Statement

```
\{ \mathbf{x} = \mathbf{N} \wedge \mathbf{x} > 0 \}
\{ x > 0 \land N > 0 \land 1*x! = N! \}
   |y := 1;|
\{ x > 0 \land N > 0 \land y * x! = N! \}
    while not x = 1 do
   \{ x \neq 1 \land x > 0 \land N > 0 \land y * x! = N! \land x = Z \}
   \{ x-1 > 0 \land N > 0 \land (y*x)*(x-1)! = N! \land x-1 < Z \}
       y := y*x;
   \{ x-1 > 0 \land N > 0 \land y*(x-1)! = N! \land x-1 < Z \}
       |x := x-1|
   \{ \downarrow x > 0 \land N > 0 \land y * x! = N! \land x < Z \}
    end
\{ \ \  \  \, \neg \neg x = 1 \land x > 0 \land N > 0 \land y * x! = N! \ \}
\{ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \}
                                                   *x \neq 1 \land x > 0 \land N > 0 \land y*x! = N! \models 0 \leq x
```



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Motivation

Developing an axiomatic semantics is difficult

Soundness:

If a property can be proved then it does indeed hold

An unsound derivation system is useless

Completeness:

If a property does hold then it can be proved

 With an incomplete derivation system, a program might be correct, but we cannot prove it

Unsoundness: Example

$$\frac{\{b \land \mathbf{P} \land e = Z\} s \{ \downarrow \mathbf{P} \land e < Z\}}{\{\mathbf{P} \land 0 \le e\} \text{ while } b \text{ do } s \text{ end } \{ \downarrow \neg b \land \mathbf{P} \}} (WHU_{Ax})$$

• With $e \equiv x$, we can derive:

```
\frac{-\frac{1}{\{\text{ true } \land \text{ x-1} < Z\} \text{ x } := \text{x-1} \{ \text{ $\downarrow$ true } \land \text{ x } < Z \}} (\text{Ass}_{Ax})}{\{\text{ true } \land \text{ true } \land \text{ x } = Z\} \text{ x } := \text{x-1} \{ \text{ $\downarrow$ true } \land \text{ x } < Z \}} (\text{Cons}_{Ax})}
\frac{\{\text{ true } \land \text{ 0} \leq \text{ x }\} \text{ while true do x } := \text{x-1} \text{ end } \{ \text{ $\downarrow$ -true } \land \text{ true }\}}}{\{\text{ 0} \leq \text{ x }\} \text{ while true do x } := \text{x-1} \text{ end } \{ \text{ $\downarrow$ true }\}} (\text{Cons}_{Ax})}
```

- This derivation is not sound (the derived triple does not hold)
- The rule does not ensure that the loop variant is non-negative before each loop iteration

Incompleteness: Example

$$\frac{\{b \land \mathbf{P} \land e = Z\} s \{ \downarrow \mathbf{P} \land e < Z\}}{\{\mathbf{P}\} \text{ while } b \text{ do } s \text{ end } \{ \downarrow \neg b \land \mathbf{P} \}} (\text{WHI}_{\mathcal{A}_X}) \quad \text{if } \mathbf{P} \models 0 \le e$$

With this rule, we cannot prove termination for the following loop

- The strongest possible loop invariant is true (because we want to show termination for all initial states)
- ullet For the natural loop variant, x, the loop invariant is not strong enough to show the side condition
- The loop variant required to prove termination is |x|, which cannot be expressed as IMP expression
- Other examples require lexicographic ordering (e.g., Ackermann function)

Soundness and Completeness

 Soundness and completeness can be proved w.r.t. an operational semantics (here, big-step semantics)

```
The partial correctness triple \{ P \} s \{ Q \} is valid, written as \models \{ P \} s \{ Q \}, iff: \forall \sigma, \sigma'. \ \mathcal{B}[[P]]\sigma = tt \land \vdash \langle s, \sigma \rangle \rightarrow \sigma' \Rightarrow \mathcal{B}[[Q]]\sigma' = tt
```

- This is the intuitive interpretation of triples: \models { $\bf P$ } s { $\bf Q$ } is true if, whenever we start execution of s from a state in which $\bf P$ holds, if the execution terminates, then $\bf Q$ will hold in the final state
- Conversely, recall that \vdash { \mathbf{P} } s { \mathbf{Q} } is defined purely in terms of the derivation rules of the axiomatic semantics
- Soundness: $\vdash \{ P \} s \{ Q \} \Rightarrow \models \{ P \} s \{ Q \}$
- Completeness: $\models \{ P \} s \{ Q \} \Rightarrow \vdash \{ P \} s \{ Q \}$

Theorem

Soundness and Completeness Theorem (Partial Correctness):

For all partial correctness triples $\{ \mathbf{P} \} s \{ \mathbf{Q} \}$ of IMP we have $\vdash \{ \mathbf{P} \} s \{ \mathbf{Q} \} \Leftrightarrow \models \{ \mathbf{P} \} s \{ \mathbf{Q} \}$

Summary: Axiomatic Semantics

- Axiomatic semantics
 - is concerned with specific properties of the effect of executing programs
 - allows for succinct proofs about program properties
- Axiomatic semantics is used to verify programs
 - Partial correctness
 - Total correctness
 - Other properties, e.g., resource consumption
- The derivation system for partial correctness of IMP programs is sound and complete