### Spatio-temporal analysis

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### Overview

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- ▶ Repeated cross-sectional surveys.
- ▶ Analysing reported cases to health facilities.

# Geostatistical problems and geostatistical methods

- ▶ Geostatistical problems: The object of scientific interest is to make inference an spatially continuous surface (e.g. disease risk) or some of its properties (e.g. regional prevalence) in a geographical area of interest.
- Model-based geostatistics: Likelihood-based methods of inference that use spatially sparse noisy data to make inference on a spatially continuous surface of interest.

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# Geostatistical problems and geostatistical methods

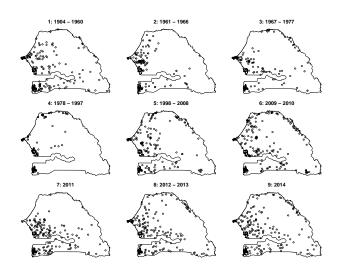
- ▶ Geostatistical problems: The object of scientific interest is to make inference an spatially continuous surface (e.g. disease risk) or some of its properties (e.g. regional prevalence) in a geographical area of interest.
- Model-based geostatistics: Likelihood-based methods of inference that use spatially sparse noisy data to make inference on a spatially continuous surface of interest.
- ▶ Geostatistical problems are <u>NOT</u> dependent on the data-format (e.g. point-level or areal-level data).

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## Geostatistical problems: some examples

- Spatio-temporal interpolation of disease risk.
- ▶ Identification of disease hotspots (i.e. areas where disease risk exceeds policy relevant thresholds).
- ▶ Identification of low transmission areas (i.e. areas where disease risk is below policy relevant thresholds).
- Estimating the association between risk factors and disease risk metrics.
- Accounting for the excess of zero-reported cases (spatially structured zero-inflation).
- ► Combining data from randomised survey and convenience samples.

### The data



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- A model for the data.

$$\log \left\{ \frac{p(x_i, t_i)}{1 - p(x_i, t_i)} \right\} = d(x_i, t_i)^{\top} \beta + S(x_i, t_i) + Z(x_i, t_i).$$
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$$E[S(x,t)] = E[Z(x,t)] = 0$$
;  $V[S(x,t)] = \sigma^2$ ;  $V[Z(x,t)] = \tau^2$  and  $corr(S(x,t),S(x',t')) = \rho(x,x',t,t';\theta)$ .

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Question. What can we do with this model?

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- The theoretical STV

$$\gamma(u, v; \theta) = E[\{W(x, t) - W(x', t')\}^{2}] 
= \tau^{2} + \sigma^{2}[1 - \rho(u, v; \theta)].$$
(2)

The empirical STV

$$\tilde{\gamma}(u,v) = \frac{1}{2|N(u,v)|} \sum_{(i,j) \in N(u,v)} {\{\tilde{Z}(x_i,t_i) - \tilde{Z}(x_j,t_j)\}^2}.$$
 (3)

 $\tilde{Z}(x,t)$  =point estimate from a non-spatial binomial mixed model.

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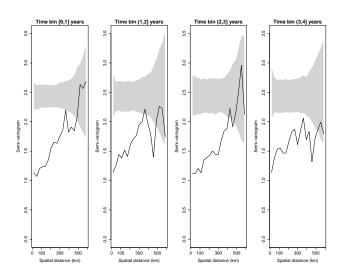
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  - (iv) use the resulting B empirical semi-variograms to generate 95% tolerance intervals at each of the pre-defined distance bins.



#### The covariance model

▶ The Gneiting's spatio-temporal correlation function.

$$\rho(u, v; \theta) = \frac{1}{(1 + v/\psi)^{\delta+1}} \exp\left\{-\frac{u/\phi}{(1 + v/\psi)^{\xi/2}}\right\}.$$
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- ► How to choose a covariance model?
- ► Guiding principle: **parsimony**, e.g. find the simplest model that can explain the variation of the data.

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- ▶ The likelihood function.

$$L(\lambda) = [y|\lambda] = \int [W, y|\lambda] dW.$$

Bayesian inference.

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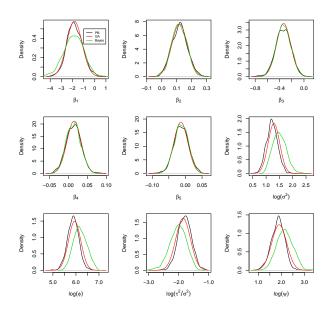
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- Prior distributions.
  - ▶  $\beta \sim N(0, 10^4)$
  - $\sigma^2 \sim \text{Uniform}(0, 20)$
  - $\phi \sim \mathsf{Uniform}(0, 1000)$
  - $\tau^2/\sigma^2 \sim \text{Uniform}(0,20)$
  - $\psi \sim \text{Uniform}(0, 20)$

# Estimation: Likelihood-based vs Bayesian inference



### Validation of the covariance model

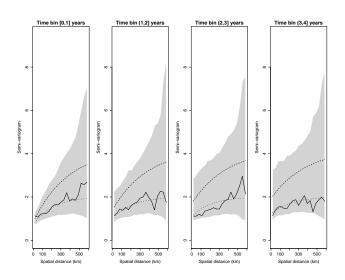
- ► Replace (i) with
  - (a) Simulate  $W(x_i, t_i)$  at observed locations  $x_i$  and times  $t_i$ , for i = 1, ..., n, from its marginal multivariate distribution under the assumed model.
  - (b) Conditionally on the simulated values of  $W(x_i, t_i)$ , simulate binomial data  $y_i$  from (1).
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- Test statistics.

$$T = \sum_{k=1}^{K} |N(u_k, t_k)| [\tilde{\gamma}(u_k, v_k) - \gamma(u_k, v_k; \theta)]^2.$$
 (5)

### Validation of the covariance model



# Spatio-temporal prediction

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Likelihood-based inference (accounting for parameter uncertainty).

$$[W^*|y] = \int \int [\hat{\Lambda}|y][W|y,\hat{\Lambda}][W^*|W,\hat{\Lambda}] dW d\hat{\Lambda},$$

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► Exceedance probability surface.

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District-wide average prevalence.

$$p_t(D) = \frac{1}{|D|} \int_D p(x,t) dx, \qquad (7)$$

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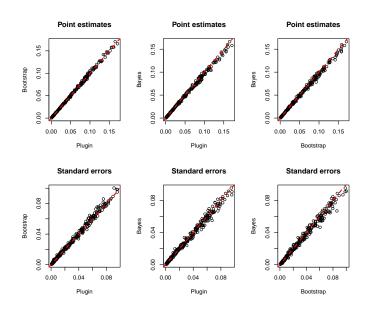
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$$\rho_t(D) = \frac{1}{|D|} \int_D \rho(x, t) dx, \qquad (7)$$

http://fhm-chicas-apps.lancs.ac.uk/shiny/users/giorgi/mapMalariaSEN/

### Prediction: Likelihood-based vs Bayesian inference



#### What is a disease outbreak?

▶ WHO: "A disease outbreak is the occurrence of cases of disease in excess of what would normally be expected in a defined community, geographical area or season. An outbreak may occur in a restricted geographical area, or may extend over several countries. It may last for a few days or weeks, or for several years."

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▶ A disease outbreak is the occurrence of cases of disease in excess of a policy-relevant risk threshold in a defined community, geographical area or season.

#### Data

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- ▶ **Population:** WorldPop + 2007 Census Data.
- ▶ Climatic variables: FLDAS data are available from NASA at daily temporal resolution and 0.1 degree spatial resolution.
  - total rainfall (mm)
  - average weekly temperature (°C)
  - average weekly relative humidity (%)
  - average weekly surface barometric pressure (hPa)
  - average weekly saturation vapour pressure deficit (mmHg)

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### Objective

Spatio-temporal mapping of exceedance probabilities

$$Prob{exp{S_{it}} > I|data}$$

at a future week t.

$$S_{it} = \frac{1}{|\mathcal{D}_i|} \int_{\mathcal{D}_i} S(x, t) dx$$

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► Spatial covariance structure

$$\operatorname{cov}\{S_{it}, S_{jt}\} = \frac{\sigma^2}{|\mathcal{D}_i||\mathcal{D}_j|} \int_{\mathcal{D}_i} \int_{\mathcal{D}_j} \exp\{-\|x - x'\|/\phi\} \ dxdx'$$

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- ► Temporal covariance structure

$$S_t = \rho S_{t-1} + W_t.$$

$$\blacktriangleright \mathcal{M}_1 : \log\{\lambda_{it}\} = d_{it}^{\top}\beta$$

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- $\blacktriangleright \mathcal{M}_1 : \log\{\lambda_{it}\} = d_{it}^{\top}\beta$
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- $\qquad \qquad \mathbf{\mathcal{M}}_3: \log\{\lambda_{it}\} = d_{it}^{\top}\beta + S_{it}$
- ► Root-mean-square-error (RMSE)

$$\text{RMSE}_t = \sqrt{\frac{1}{142} \sum_{i=1}^{142} (\lambda_{it}^{emp} - \hat{\lambda}_{it})^2}$$

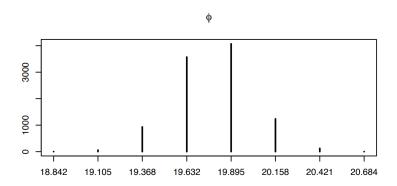
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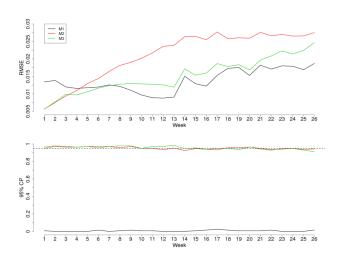
▶ 95% coverage probabilities (CI)

$$ext{CI}_t = rac{1}{142} \sum_{i=1}^{142} I(\lambda_{it}^{0.025} < \lambda_{it}^{emp} < \lambda_{it}^{0.975})$$

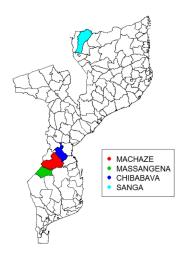
# Results: scale of spatial correlation



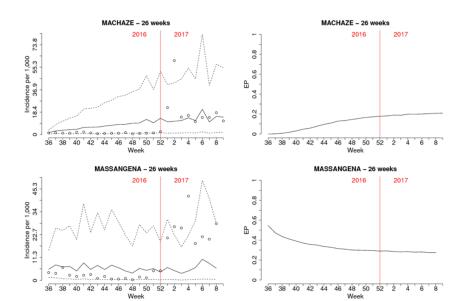
#### Results: validation



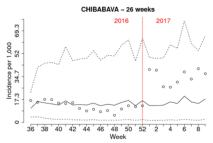
## Results: exceedance probabilities

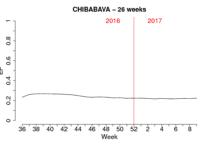


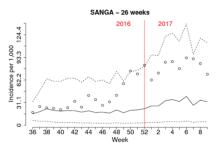
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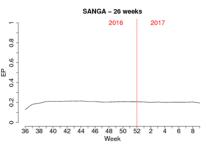








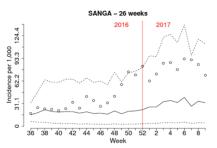


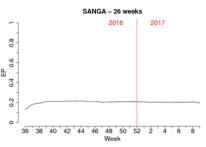




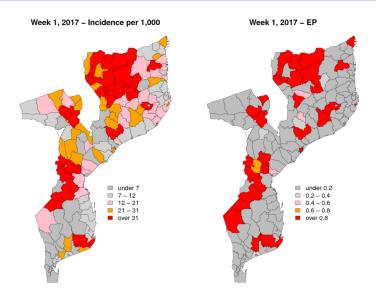




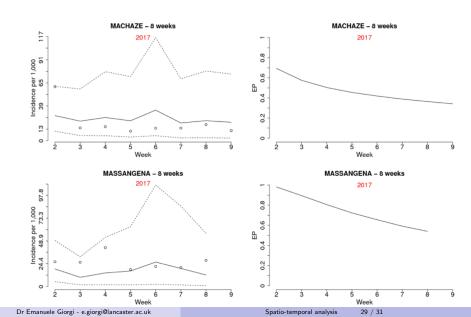


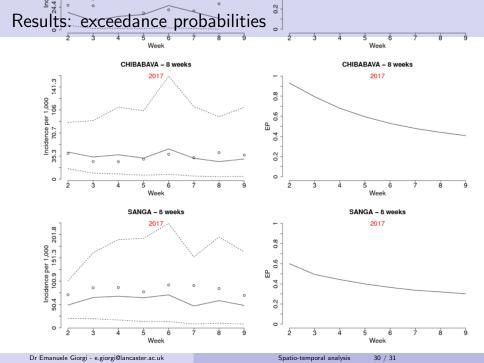


### Results: incidence vs exceedance probabilities



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