

# Binomial geostatistical models

Dr Emanuele Giorgi  
Lancaster University  
`e.giorgi@lancaster.ac.uk`

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# Binomial geostatistical models

- ▶ Binomial sampling, extra-binomial variation.
- ▶ Binomial generalized linear model with spatially correlated and uncorrelated random effects.
- ▶ Maximum likelihood estimation.
- ▶ Plug-in and Bayesian prediction.

# Binomial sampling and extra-binomial variation

- ▶ **Bernoulli trial:** binary random variable,  $Y = 1/0$  with probabilities  $p$  and  $1 - p$ , respectively.
- ▶ **binomial distribution:** discrete random variable,  $Y \sim \text{Bin}(m, p)$  is the sum of  $m$  independent Bernoulli trials

Mean and variance:

$$\mu = E[Y] = p, \quad \text{Var}(Y) = mp(1 - p) = \mu(1 - \mu/m)$$

- ▶ **extra-binomial variation:** discrete random variable  $Y$  is the sum of  $m$  binary outcomes,  $E[Y] = \mu$ ,  $\text{Var}(Y) > \mu(1 - \mu/m)$

**Blue:** how many boys are there in a family of twins?

# How does extra-binomial variation arise?

Binary random variables  $X_i : i = 1, \dots, m$ ,

$$Y = \sum_{i=1}^m X_i$$

**Heterogeneity:**  $X_i$  are mutually independent, with  $P(X_i = 1) = p_i$

**Dependence:**  $P(X_i = 1) = p$  for all  $i$ , but  $\text{Corr}(X_i, X_j) = \rho > 0$

**Exercise:** In either case, prove that  $\text{Var}(Y) > E[Y](1 - E[Y]/m)$

# Binomial logistic geostatistical model

- ▶ Latent spatial process

$$S(x) \sim \text{SGP}\{0, \sigma^2, \rho(u)\}$$

$$\rho(u) = \exp(-|u|/\phi)$$

- ▶ Linear predictor

$d(x)$  = environmental variables at location  $x$

$$\eta(x) = d(x)' \beta + S(x)$$

$$\eta(x) = \log[p(x)/\{1 - p(x)\}]$$

- ▶ Error distribution

$$Y_i | S(\cdot) \sim \text{rmBin}\{m_i, p(x_i)\}$$

# Parameter estimation

For convenience, write

$$T_i = d(x_i)' \beta + S(x_i) \quad T = (T_1, \dots, T_n)$$

Then, all model parameters,  $\theta$  say, are contained within  $[T]$ .

**Data:**  $(m_i, y_i) : i = 1, \dots, n$

**Model:**

$$T = \text{MVN}(\theta) \quad [Y|T] = \prod_{i=1}^n [Y_i|T_i] \quad [Y_i|T_i] = \text{Bin}(m_i, p_i), \quad p_i = p(T_i)$$

**Likelihood:**

$$L(\theta) = \int_T [T; \theta] \times [Y|T] dT$$

**Problem** ... how to evaluate the high-dimensional integral?

# Monte Carlo maximum likelihood: a general method for parameter estimation with intractable likelihoods

## Scenario

$L(\theta) = f(y; \theta) = c(\theta)g(y; \theta)$ , with  $g(\cdot)$  known but  $c(\cdot)$  intractable.

## Method

1. Note first that  $c(\theta)^{-1} = \int g(y; \theta) dy$
2. Choose any **fixed** value  $\theta_0$ , and let  $E_0[\cdot]$  mean “expectation when  $\theta = \theta_0$ ” Then,

$$E_0 \left[ \frac{g(y; \theta)}{g(y; \theta_0)} \right] = \int \frac{g(y; \theta)}{g(y; \theta_0)} c(\theta_0) g(y; \theta_0) dy = \frac{c(\theta_0)}{c(\theta)}$$

# Monte Carlo maximum likelihood: continued

3. Write the **likelihood ratio** wrt  $\theta_0$  as

$$LR(\theta) = \frac{f(y; \theta)}{f(y; \theta_0)} = \frac{c(\theta)g(y; \theta)}{c(\theta_0)g(y; \theta_0)} = \frac{g(y; \theta)}{g(y; \theta_0)} / E_0 \left[ \frac{g(y; \theta)}{g(y; \theta_0)} \right]$$

4. Write  $r(y; \theta) = g(y; \theta)/g(y; \theta_0)$
5. Simulate  $y_1, y_2, \dots, y_s$  from the distribution of  $Y$  when  $\theta = \theta_0$ .
6. For any value of  $\theta$  compute  $\bar{r}(\theta) = \sum_{k=1}^s r(y_k; \theta)$
7. Compute  $\hat{\theta}$  to maximise

$$MClogL(\theta) = \log g(y; \theta) - \log \bar{r}(\theta)$$



# Monte Carlo maximum likelihood for the binomial geostatistical model

$$\begin{aligned} L(\theta) &= \int_T [T; \theta] \times [Y|T] dT \\ &= \int_T [T; \theta] \times \frac{[T; \theta_0]}{[T; \theta_0]} \times [Y|T] dT \\ &= \int \frac{[T; \theta]}{[T; \theta_0]} \times [Y, T; \theta_0] dT \\ &= [Y; \theta_0] \int \frac{[T; \theta]}{[T; \theta_0]} \times [T|Y; \theta_0] dT \\ &= [Y; \theta_0] \times E_0 \left[ \frac{[T; \theta]}{[T; \theta_0]} \right], \end{aligned}$$

where  $E_0[\cdot]$  denotes expectation wrt the conditional distribution of  $T$  given  $Y = y$  when  $\theta = \theta_0$ .

Now replace  $E_0[\cdot]$  by sample mean over simulations of  $Y$  at  $\theta = \theta_0$ , as before.

# Sampling from $[T|Y]$ : Markov chain Monte Carlo

A **Markov chain** is a sequence of random variables  $Y_1, Y_2, \dots, Y_n, \dots$  with the property that, for all  $n$ ,

$$[Y_n | Y_1, \dots, Y_{n-1}] = [Y_n | Y_{n-1}]$$

**Markov chain Monte Carlo** (MCMC) methods are now widely used in applied statistics approximate evaluation of intractable expectations.

**Metroplis** MCMC methods are useful for problems involving distributions that are known up to a constant of proportionality.

Gamerman and Lopez (2010)

# Metropolis MCMC: to simulate a sample from a distribution with pdf $f(y) = c \times g(y)$

Let  $r(y, y^*) = f(y)/f(y^*) = g(y)/g(y^*) \dots$  known for all  $y$  and  $y^*$

A **proposal distribution**,  $p(y, y^*)$ , is any conditional distribution for  $Y^*$  given  $Y$ , with the property that  $[Y^*|Y] = [Y|Y^*]$

**Metropolis update:**  $Y_n \rightarrow Y_{n+1}$

1. sample a **candidate**  $X$  from any proposal distribution  $p(Y_n, X)$
2. calculate the **acceptance probability**

$$a = \min \left\{ 1, \frac{p(Y_n, X)}{p(X, Y_n)} \right\}$$

3. sample  $U$  from the uniform distribution on  $(0, 1)$
4. if  $U \leq a$ , set  $Y_{n+1} = X$ , otherwise set  $Y_{n+1} = Y_n$

**Theorem:** in the limit  $n \rightarrow \infty$ , for any  $Y_1$  and any proposal distribution  $p(\cdot)$ , the distribution of a sequence of Metropolis updates converges to the distribution with pdf  $f(y)$

# Prediction in the binomial model

**Recall** that  $S$  denotes the underlying signal at the data-locations, while  $S^*$  denotes the signal at all prediction locations of interest, typically a finely spaced grid to cover the region of interest,  $A$

## Plug-in prediction

- ▶ Estimate  $\hat{\theta}$  by Monte Carlo maximum likelihood
- ▶ Sample from  $[S|Y; \hat{\theta}]$  by MCMC
- ▶ Sample from multivariate Normal distribution  $[S^*|S]$

## Bayesian prediction

- ▶ Extend hierarchical representation of model to

$$[Y, S, \theta] = [\theta] \times [S|\theta] \times [Y|S, \theta]$$

- ▶ Sample from  $[S, \theta|Y]$  by MCMC
- ▶ Sample from multivariate Normal distribution  $[S^*|S]$

## 9. Prevalence mapping

- ▶ Mapping prevalence: exceedance probability maps.
- ▶ Extensions: combining data form multiple surveys, zero- inflation, spatio-temporal models.

# A non-spatial model for prevalence survey data

## Design

- ▶ Sample communities  $i = 1, \dots, n$ .
- ▶ In community  $i$ , sample  $m_i$  individuals of whom  $Y_i$  test positive for disease of interest.
- ▶ Associated covariates  $w_i$

## Model

- ▶  $p_i$  = probability that a randomly sampled individual in community  $i$  will test positive
- ▶  $\log\{p_i/(1 - p_i)\} = \alpha + w_i'\beta$
- ▶  $Y_i \sim \text{Binomial}(m_i, p_i)$ , mutually independent

# A spatial model for prevalence survey data

## Design

- ▶ Sample communities  $i = 1, \dots, n$  at locations  $x_i$
- ▶ In community  $i$ , sample  $m_i$  individuals of whom  $Y_i$  test positive for disease of interest.
- ▶ Associated covariates  $w_i = w(x_i)$

## Model

- ▶  $\rho_i$  = probability that a randomly sampled individual in community  $i$  will test positive
- ▶  $\log\{P_i/(1 - P_i)\} = \alpha + w(x_i)'\beta + S(x_i)$
- ▶  $Y_i \sim \text{Binomial}(m_i, P_i)$ , conditionally independent given  $S(\cdot)$

# A spatial model for prevalence survey data (continued)

## Two kinds of covariates

- ▶  $w(x_i)$  an intrinsic property of the location  $x_i$
- ▶  $w(x_i)$  a property of the people who live at location  $x_i$

**Practical implication:** when mapping prevalence we need to be able to assign a value  $w(x)$  to **every location** in the study-region.

## What is $S(x)$ ?

- ▶ an unobserved spatially varying stochastic process
- ▶ a proxy for unmeasured, spatially structured covariates

**Practical implication:** in any application where  $S(x)$  turns out to be important, it is worth asking what the missing covariate(s) might be.



# Person or place?

Extend spatial model to

$$\log\{P_i/(1 - P_i)\} = \alpha + \{w(x_i)' \beta + S(x_i)\} + \{d_i' \gamma + U_i\}$$

- ▶  $w(x)$  : measured properties of location  $x$
- ▶  $S(x)$  : stochastic process, proxy for unmeasured properties of  $x$
- ▶  $d_i$  : measured properties of  $i$ th community
- ▶  $U_i$  : independent random variables, proxy for unmeasured properties of  $i$ th community

# Exploratory analysis: empirical logits

- ▶ fitting the binomial logistic model is computationally demanding, and requires judgement:
  - ▶ convergence of iterative algorithms
  - ▶ judicious choice of approximations
- ▶ empirical logit transform:

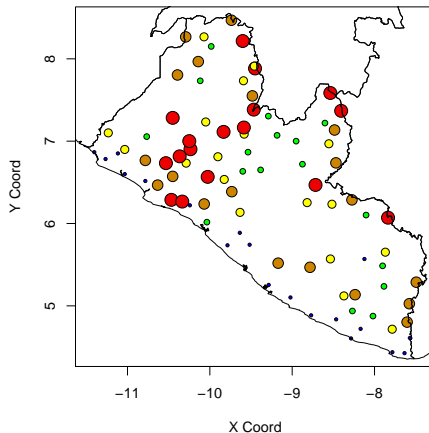
$$Z_i = \log\{(Y_i + 0.5)/(n_i - Y_i + 0.5)\}$$

- ▶ fit **linear** model with  $Z_i$  as response

# Onchocerciasis (river blindness) in Liberia

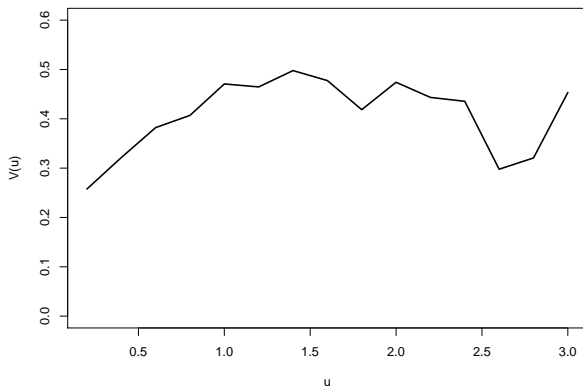
- ▶ prevalence data from 90 villages in Liberia
- ▶ sample sizes 40 to 50
- ▶ empirical prevalences 0% to 35%
- ▶ use empirical logit transformation for exploratory analysis

# Exploratory analysis of onchocerciasis data



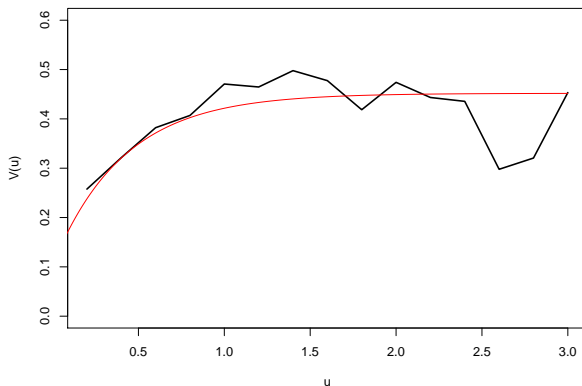
- ▶ patches of high and low prevalence
- ▶ increasing trend away from coast?

## Exploratory analysis of onchocerciasis data (2)



- residual variogram after fitting linear trend surface

# Exploratory analysis of onchocerciasis data (3)



- fitted Matérn model with  $\kappa = 0.5$

# Fitting the binomial logistic model

- ▶ likelihood function involves intractable high-dimensional integral
- ▶ need to use Monte Carlo methods
- ▶ Monte Carlo maximum likelihood or Bayesian estimation according to choice
- ▶ for large data-sets, algorithms need careful tuning to preserve accuracy while remaining computationally feasible