$$\widetilde{1-3}$$

$$\sin\left(5x + \frac{\pi}{4}\right) = -\frac{\sqrt{3}}{2}$$
Set as 6

consider
$$5 \text{ in } \theta = -\frac{\sqrt{3}}{2}$$

0 is 60° in quadrents where sin (-) is resative

so solutions are $\theta = \frac{4\pi}{3} + 2\pi k$, $\frac{5\pi}{3} + 2\pi k$.

Now bring back the subexpression indig x i and solve.

$$\int S \times + \frac{\pi}{4} = \frac{4\pi}{3} + 2\pi k$$

$$\int S \times + \frac{\pi}{4} = \frac{S\pi}{3} + 2\pi k$$

$$\int \times + \frac{\pi}{4} = \frac{4\pi}{3} + 2\pi k$$

$$\int \times + \frac{\pi}{4} = \frac{5\pi}{3} + 2\pi k$$

$$\int \times + \frac{\pi}{4} = \frac{5\pi}{3} + 2\pi k$$

$$\int \frac{4\pi}{3} - \frac{\pi}{4} = \frac{6\pi}{12} - \frac{3\pi}{12}$$

$$= \frac{15\pi}{12}$$

$$\frac{\pi}{3} - \frac{\pi}{4} = \frac{20\pi}{12} - \frac{3\pi}{12} = \frac{17\pi}{12}$$

$$\Rightarrow \int 5x = \frac{13T}{12} + 2TK$$

$$\int 5x = \frac{17T}{12} + 2TK$$

$$\Rightarrow = \frac{13\pi}{60} + \frac{2\pi}{5}k, \frac{77\pi}{60} + \frac{2\pi}{5}k, \frac{12\pi}{5}k, \frac{12\pi}{5}k$$

5]
$$4 \sin^2 y = \cos y - 1$$

Rewrite $\sin^2 y$ in terms of $\cos y$ using Pythag identity

 $5 \sin^2 + \cos^2 = 1$
 $\Rightarrow 5 \sin^2 = 1 - \cos^2$

$$=) 4 cos^2 y + cos y - 5 = 0$$

$$4 \cos y + 5 = 0$$

$$\cos y = \frac{-5}{4}$$

$$\cos y = \frac{-5}{4}$$

$$y = 2\pi k, k \in \mathbb{Z}$$

$$Imposible$$

this is $4x^2 + x - 5 = 0$, letting x = cory

Otherise use quadratic formula to get factorization.

This factors (4x+5)(x-1)=0

« Crucial step is to spot this factorizes.

$$=$$
 $\int \sin u^{-1} = 0$ OR $\cos u + 1 = 0$
 $\sin u^{-1} = 0$ $\cos u = -1$

$$\vec{V}_1 \cdot \vec{V}_2 = (-5)(3) + (-7)(-2)$$

$$= -15 + 14 = \boxed{1}$$

$$\vec{V}_1 \cdot \vec{V}_2 = (-5)(-2) - (3)(-7)$$

$$= 10 + 21 = \boxed{31}$$

$$||\vec{v}_1|| = 3$$
, $||\vec{v}_2|| = 6$, $||\vec{v}_1 - \vec{v}_2|| = 5$. Find $|\vec{v}_1 - \vec{v}_2|| = 5$.

$$||\vec{v}_1 - \vec{v}_2||^2 = ||\vec{v}_1||^2 + ||\vec{v}_2||^2 - 2(\vec{v}_1 \cdot \vec{v}_2)$$
 = generalized Pythagoreun theeron
$$5^2 = 3^2 + 6^2 - 2(\vec{v}_1 \cdot \vec{v}_2)$$
 Plug in values

 $\overrightarrow{V_1} \cdot \overrightarrow{V_2} = x_1 x_2 + y_1 y_2$ $\overrightarrow{V_1} \wedge \overrightarrow{V_2} = x_1 y_2 - x_2 y_1$

$$= 25 - 9 - 36 = -2 (\vec{v_1} \cdot \vec{v_2})$$

$$-20 = -2 (\vec{v_1} \cdot \vec{v_2})$$

$$\vec{v_1} \cdot \vec{v_2} = \boxed{0}$$

$$V_1 = \frac{12-13}{5}$$
 $V_2 = \frac{4}{-2\sqrt{3}}$

Find geometric only of both trains angles. Exout values.

$$= arccor \left(-\frac{\sqrt{3}}{2}\right)$$

$$=$$
 $\frac{5\pi}{6}$

$$= arcco \left(\frac{-14\sqrt{3}}{24.7} \right)$$

$$= arcco \left(\frac{-14\sqrt{3}}{2} \right)^{2} + (5)^{2}$$

$$= \sqrt{3} + 25 = \sqrt{28}$$

$$= \sqrt{4} + 25 = \sqrt{28}$$

$$= \sqrt{4} + (-2\sqrt{3})^{2}$$

$$\frac{\nabla_{V_1 \text{ over } V_2}}{= -\frac{5\pi}{6}}$$

$$V_2$$
 over $V_1 = \frac{5\pi}{6}$

$$V_{1} \cdot V_{2} = (-\sqrt{3})(4) + (5)(-2\sqrt{3})$$

$$= -4\sqrt{3} - 10\sqrt{3}$$

$$= -14\sqrt{3}$$

$$1|V_{1}| = \sqrt{(-\sqrt{3})^{2} + (5)^{2}}$$

$$= \sqrt{3} + 25 = \sqrt{28} = 2\sqrt{7}$$

$$\frac{|V_2|| = \sqrt{(4)} + (-2\sqrt{3})}{7} = \sqrt{16 + 12} = 2\sqrt{28} = 2\sqrt{7}$$

$$V_1 NV_2 = (-V_3)(-2V_3) - 5(4)$$

= 6 - 20 = -14

cum see there the visually: V3 2 1.718

| Cat runs 600 yds in \$60°E

| Jag runs 500 yds North.

| Find distance b/t pets. Road 2 derival plus.

| Let vi=cot, v_2 =day.

| Weat $||v_1-v_2||$,

| Generalized pythons:

| $||v_1-v_2||^2 = ||v_1||^2 + ||v_2||^2 - 2(v_1 \cdot v_2)$ | $||v_1-v_2||^2 = ||v_1||^2 + ||v_2||^2 - 2(v_1 \cdot v_2)$ | $||v_1-v_2||^2 = \sqrt{6\omega^2 + 500^2 + 300000}$

 $||v_1 - v_2|| = \sqrt{600^2 + 500^2 + 300000}$ $\approx 953.94 \text{ yds}$

Find distur (T, B) often 1 hr.

.
$$T_{init} = 20 \cdot \vec{u}_{45^\circ} = 20 \left[\frac{1}{\sqrt{2}} \right] = \left[\frac{10\sqrt{2}}{10\sqrt{2}} \right]$$
 (with position.

· Direction of trovel: 540°E

400

I prefer this netation

Unit diretion vector: 12-500 = (cos(-50°), 5in (-50°))

· dist
$$(T_{\frac{1}{2}hr}, B) = \sqrt{(50-33.4258)^2 + (0-(-8.8392))^2}$$
 $\leftarrow distant formula.$