Joint Filtering of Intensity Images and Neuromorphic Events for High-Resolution Noise-Robust Imaging

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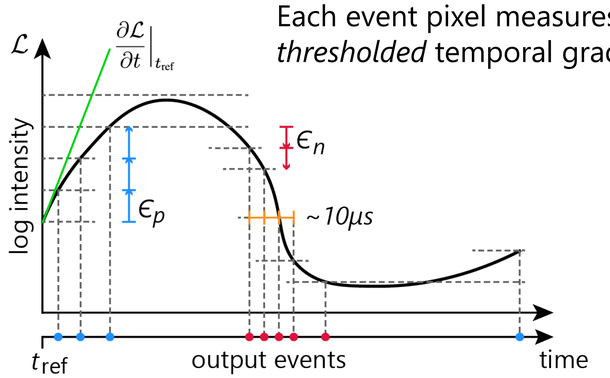
Project page

RGB cam vs. event cam

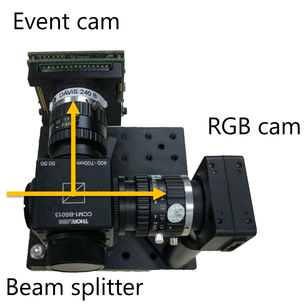
30/60FPS	High speed (1us latency)
~60dB	HDR (120dB)
>1W	Low power (10mW)
HD UHD 4/8k	Low resolution (240x180)
Less noisy	noisy

How does event camera work?

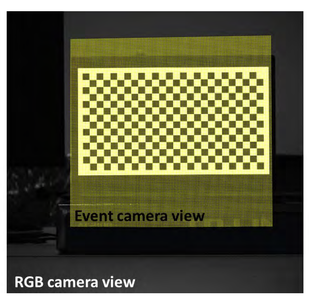


Each event pixel measures *thresholded* temporal gradient

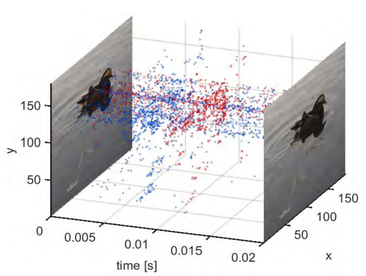
Proposal: RGB + Event hybrid camera



camera



calibration

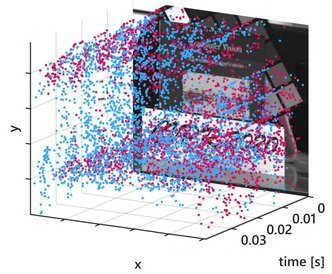


Captured data: regular frame-rate images and events

Guided Event Filtering (GEF): a unifying framework

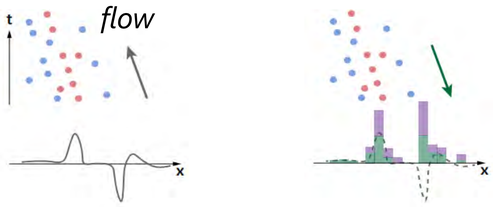
Input

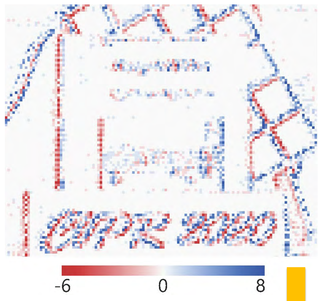
an intensity image
a stream of events



Motion model

Assuming events are generated by moving edges





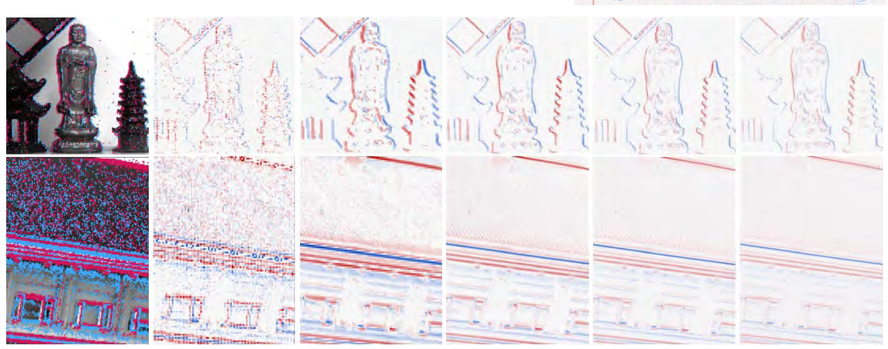
Motion compensation

Step 1: Motion compensation by Joint Contrast Maximization
- *maximizes the contrast of the histogram jointly formed by the image and events*
- *registers events with image edges*
- *estimates optical flow robust to event noise*

Filter output

Step 2: Joint/guided image filtering
- *extracts mutual structure from image and events*
- *recursively upsamples by 2x, until 8x*

Guided event upsampling

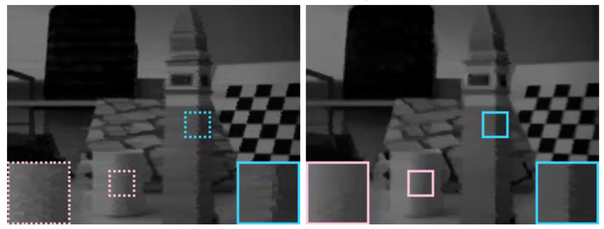


(a) Img+events (b) Q^e (c) 1× (d) 2× (e) 4× (f) 8×

Applications

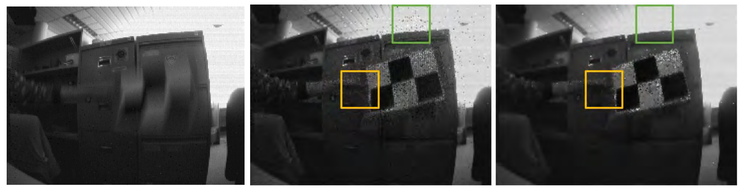
GEF can improve performance for event-based algorithms

#1: video frame synthesis



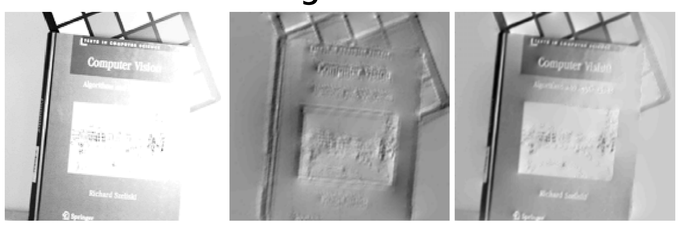
w/o GEF w/ GEF

#2: image motion deblur



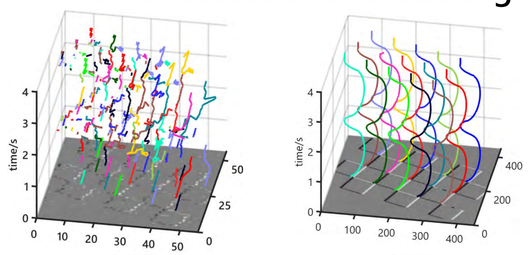
Blurry image deblur w/o GEF w/ GEF

#3: HDR image reconstruction



LDR image HDR w/o GEF w/ GEF

#4: corner detection and tracking



w/o GEF, 1× w/ GEF, 8×

Dataset available at our website