▼ 이미지 증강(Image Augmentation)을 사용하여 CNN 학습

Overfitting 대응책

```
import warnings
warnings.filterwarnings('ignore')
```

Import Keras

```
import keras
keras.__version__
'2.4.3'
```

I. Google Drive Mount

• 'dogs_and_cats_small.zip' 디렉토리를 구글드라이브에 업로드

```
from google.colab import drive
drive.mount('<u>/content/drive</u>')
```

Mounted at /content/drive

▼ 1) 구글 드라이브 마운트 결과 확인

```
!Is -I '/content/drive/My Drive/Colab Notebooks/datasets/dogs_and_cats_small.zip'
-rw------ 1 root root 90618980 Mar 4 04:51 '/content/drive/My Drive/Colab Notebooks/dataset
```

2) unzip 'dogs_and_cats_small.zip'

inflating: test/cats/cat.1503.jpg

```
!unzip /content/drive/MyW Drive/ColabW Notebooks/datasets/dogs_and_cats_small.zip

Archive: /content/drive/My Drive/Colab Notebooks/datasets/dogs_and_cats_small.zip
inflating: test/cats/cat.1501.jpg
inflating: test/cats/cat.1502.jpg
```

```
inflating: test/cats/cat.1504.jpg
inflating: test/cats/cat.1505.jpg
inflating: test/cats/cat.1506.jpg
inflating: test/cats/cat.1507.jpg
inflating: test/cats/cat.1508.jpg
inflating: test/cats/cat.1509.jpg
inflating: test/cats/cat.1510.jpg
inflating: test/cats/cat.1511.jpg
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inflating: test/cats/cat.1555.jpg
inflating: test/cats/cat.1556.jpg
inflating: test/cats/cat.1557.jpg
inflating: test/cats/cat.1558.jpg
inflation: toot/outs/out 1EEO inc
```

```
total 20
drwx---- 5 root root 4096 Mar 8 07:35 drive
```

!|s -|

```
drwxr-xr-x 1 root root 4096 Mar 1 14:35 sample_data
drwxr-xr-x 4 root root 4096 Mar 8 07:35 test
drwxr-xr-x 4 root root 4096 Mar 8 07:35 train
drwxr-xr-x 4 root root 4096 Mar 8 07:35 validation
```

→ 3) [Optional] Image Augmentation Test

- rotation_range = 40: 0도에서 40도 사이에서 임의의 각도록 회전
- width_shift_range = 0.2: 20% 픽셀 내외로 좌우 이동
- height_shift_range = 0.2: 20% 픽셀 내외로 상하 이동
- shear_range = 0.2: 0.2 라디안 내외로 시계 반대방향으로 변형
- zoom_range = 0.2:80%에서 120% 범위에서 확대/축소
- horizontal_flip = True : 수평방향 뒤집기
- vertical_flip = True : 수직방향 뒤집기
- fill_mode = 'nearest' : 주변 픽셀로 이미지 채우기

```
from keras.preprocessing import image import matplotlib.pyplot as plt import os

train_cats_dir = train_dir = os.path.join('train', 'cats') fnames = sorted([os.path.join(train_cats_dir, fname) for fname in os.listdir(train_cats_dir)])

# 테스트 이미지 선택 img_path = fnames[77]

# 이미지 읽고 크기 변경 img = image.load_img(img_path, target_size=(150, 150))

# (150, 150, 3) 배열 변환 x = image.img_to_array(img)

# (1, 150, 150, 3) 변환 x = x.reshape((1,) + x.shape)

# 랜덤하게 변환된 이미지 배치 생성 i = 0
```

```
for batch in datagen.flow(x, batch_size=1):
    plt.figure(i)
    imgplot = plt.imshow(image.array_to_img(batch[0]))
    i += 1
    if i % 4 == 0:
        break

plt.show()
```

II. Data Preprocessing

→ 1) Image_File Directory Setting

- train_dir
- valid_dir
- test_dir

```
train_dir = 'train'
valid_dir = 'validation'
test_dir = 'test'
```

2) ImageDataGenerator() & flow_from_directory()

- Normalization & Augmentation
 - ImageDataGenerator()
- · Resizing & Generator
 - flow_from_directory()

Found 2000 images belonging to 2 classes. Found 1000 images belonging to 2 classes.

III. CNN Keras Modeling

→ 1) Model Define

- Feature Extraction & Classification
 - Dropout Layer

```
from keras import layers
from keras import models

model = models.Sequential()
model.add(layers.Conv2D(32, (3, 3), activation = 'relu', input_shape = (150, 150, 3)))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(64, (3, 3), activation = 'relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(128, (3, 3), activation = 'relu'))
model.add(layers.MaxPooling2D((2, 2)))
model.add(layers.Conv2D(128, (3, 3), activation = 'relu'))
model.add(layers.MaxPooling2D((2, 2)))

model.add(layers.Flatten())
model.add(layers.Dense(512, activation = 'relu'))
model.add(layers.Dense(512, activation = 'relu'))
model.add(layers.Dense(1, activation = 'sigmoid'))
```

```
model.summary()
```

Model: "sequential"

Layer (type)	Output	Shape	Param #
conv2d (Conv2D)	(None,	148, 148, 32)	896
max_pooling2d (MaxPooling2D)	(None,	74, 74, 32)	0
conv2d_1 (Conv2D)	(None,	72, 72, 64)	18496
max_pooling2d_1 (MaxPooling2	(None,	36, 36, 64)	0
conv2d_2 (Conv2D)	(None,	34, 34, 128)	73856
max_pooling2d_2 (MaxPooling2	(None,	17, 17, 128)	0
conv2d_3 (Conv2D)	(None,	15, 15, 128)	147584
max_pooling2d_3 (MaxPooling2	(None,	7, 7, 128)	0
flatten (Flatten)	(None,	6272)	0
dropout (Dropout)	(None,	6272)	0
dense (Dense)	(None,	512)	3211776
dense_1 (Dense)	(None,	1)	513

Total params: 3,453,121 Trainable params: 3,453,121 Non-trainable params: 0

→ 2) Model Compile

• 모델 학습방법 설정

→ 3) Model Fit

• 약 30분

o epochs: 60 -> 100

```
%%time
Hist_dandc = model.fit(train_generator,
```

```
steps_per_epoch = 100,
epochs = 100,
validation_data = valid_generator,
validation_steps = 50)
```

```
Epoch 1/100
                               ======] - 51s 176ms/step - loss: 0.7200 - accuracy: 0.511
100/100 [===
Epoch 2/100
100/100 [==
                                ======] - 17s 171ms/step - loss: 0.6921 - accuracy: 0.505
Epoch 3/100
100/100 [==
                                 =====] - 17s 172ms/step - Ioss: 0.6935 - accuracy: 0.472
Epoch 4/100
                                     ==] - 17s 174ms/step - loss: 0.6939 - accuracy: 0.493
100/100 [==
Epoch 5/100
100/100 [==
                                     ==] - 17s 174ms/step - Ioss: 0.6933 - accuracy: 0.488
Epoch 6/100
                                ======] - 17s 170ms/step - loss: 0.6936 - accuracy: 0.490
100/100 [===
Epoch 7/100
                              =======] - 17s 169ms/step - loss: 0.6933 - accuracy: 0.494
100/100 [===
Epoch 8/100
                                ======] - 17s 172ms/step - loss: 0.6932 - accuracy: 0.499
100/100 [===
Epoch 9/100
100/100 [===
                                ======] - 17s 170ms/step - loss: 0.6934 - accuracy: 0.490
Epoch 10/100
100/100 [==
                                ======] - 17s 170ms/step - loss: 0.6918 - accuracy: 0.509
Epoch 11/100
100/100 [==
                                     ==] - 17s 169ms/step - loss: 0.6905 - accuracy: 0.513
Epoch 12/100
                                      ==] - 17s 171ms/step - Ioss: 0.6919 - accuracy: 0.484
100/100 [===
Epoch 13/100
                               ======] - 17s 171ms/step - loss: 0.6942 - accuracy: 0.489
100/100 [====
Epoch 14/100
                                 =====] - 17s 172ms/step - loss: 0.6932 - accuracy: 0.491
100/100 [===
Epoch 15/100
100/100 [===
                                     ==] - 17s 174ms/step - loss: 0.6925 - accuracy: 0.508
Epoch 16/100
                                ======] - 17s 171ms/step - loss: 0.6932 - accuracy: 0.514
100/100 [===
Epoch 17/100
                             =======] - 17s 169ms/step - loss: 0.6934 - accuracy: 0.502
100/100 [====
Epoch 18/100
                             =======] - 17s 170ms/step - loss: 0.6922 - accuracy: 0.509
100/100 [====
Epoch 19/100
                          ========] - 17s 169ms/step - loss: 0.6910 - accuracy: 0.524
100/100 [====
Epoch 20/100
100/100 [====
                            =======] - 17s 168ms/step - loss: 0.6832 - accuracy: 0.537
Epoch 21/100
100/100 [===
                             =======] - 17s 168ms/step - loss: 0.6910 - accuracy: 0.551
Epoch 22/100
100/100 [====
                                ======] - 17s 169ms/step - loss: 0.6833 - accuracy: 0.547
Epoch 23/100
                           =======] - 17s 169ms/step - loss: 0.6756 - accuracy: 0.571
100/100 [====
Epoch 24/100
100/100 [====
                             ========] - 17s 170ms/step - loss: 0.6787 - accuracy: 0.571
Epoch 25/100
100/100 [====
                               ======] - 17s 174ms/step - loss: 0.6731 - accuracy: 0.603
Epoch 26/100
100/100 [===
                                      ==] - 17s 174ms/step - loss: 0.6644 - accuracy: 0.622
Epoch 27/100
100/100 [===
                                     ==] - 17s 172ms/step - loss: 0.6708 - accuracy: 0.593
Epoch 28/100
100/100 [====
                             =======] - 17s 171ms/step - loss: 0.6607 - accuracy: 0.607
```

```
Epoch 29/100
100/100 [======] - 17s 171ms/step - loss: 0.6482 - accuracy: 0.632
```

▼ 4) 학습 결과 시각화

Loss Visualization

```
import matplotlib.pyplot as plt

epochs = range(1, len(Hist_dandc.history['loss']) + 1)

plt.figure(figsize = (9, 6))
plt.plot(epochs, Hist_dandc.history['loss'])
plt.plot(epochs, Hist_dandc.history['val_loss'])

plt.title('Training & Validation Loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.legend(['Training Loss', 'Validation Loss'])
plt.grid()
plt.show()
```

Accuracy Visualization

```
import matplotlib.pyplot as plt

epochs = range(1, len(Hist_dandc.history['loss']) + 1)

plt.figure(figsize = (9, 6))
plt.plot(epochs, Hist_dandc.history['accuracy'])
plt.plot(epochs, Hist_dandc.history['val_accuracy'])

plt.title('Training & Validation Accuracy')
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.legend(['Training Accuracy', 'Validation Accuracy'])
plt.grid()
plt.show()
```

▼ 5) Model Evaluate

test_generator

```
test_datagen = ImageDataGenerator(rescale = 1./255)

test_denerator = test_datagen_flow_from_directory(
```

```
test_dir,
target_size = (150, 150),
batch_size = 20,
class_mode = 'binary')
```

Found 1000 images belonging to 2 classes.

Loss & Accuracy

IV. Model Save & Load to Google Drive

→ 1) Google Drive Mount

```
from google.colab import drive

drive.mount('<u>/content/drive</u>')

Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/c
```

→ 2) Model Save

```
model.save('/content/drive/My Drive/Colab Notebooks/models/003_dogs_and_cats_augmentation.h5')
```

!ls -l <u>/content/drive/My</u>₩ Drive/Colab₩ Notebooks/models

→ 3) Model Load

#