Chapter 1

Integration

Substitution, 1.1 Change of Variables

We want to apply a Change of Variables to substitute in order to

- 1. Simplify the integrand
- 2. Find Antiderivatives that result from the chain rule. This is a more common use.

For example, Type (i):

$$\int \frac{x}{1+x} dx = \int \frac{y_1}{y} dy$$

which can be broken apart (sums in numerator can be decomposed). Then, we can find the integral of $\int 1 - \frac{1}{y} dy = 1 + x - \ln|1 + x| + c$ via backsubstitution of the variable y = 1-x.

For Type (ii) the general solution can be described as follows:

For an integral of the form

$$\int f(g(x))g'(x)dx$$

, ie. where we have an outer function f of Recall the $\frac{1}{2}$ comes out of the derivative, and some inner function g and the derivative of we take it as a factor to get dx inside the

A the inner function (or some constant multiple of it/simple algebraic manipulation) inside the integral multiplied by f(q(x)), we can use integration by parts.

We take

$$u = g(x) \Rightarrow u' = g'(x)dx$$

$$I = \int f(u)d(u) = F(u) + c$$
$$= F(g(x)) + C$$

For definite variables, you have to change the bounds with the change of the variables, where you apply g(x) to the bounds of x as well as to x itself.

Ex. for

$$\int_0^{\frac{pi}{4}} (\sin 2\theta)^3 \cos(2\theta) = \frac{1}{2} \int_{\sin(2(0))}^{\sin \frac{\pi}{4}} = \int_0^1 w^3 dw$$

integral.

The general formula is thus

$$\int_{a}^{b} f(g(x))g'(x)dx = \int_{g(a)}^{g(b)} f(u)du|u = g(x)$$

1.1.1 Some Interesting Techniques

- 1. Taking powers and breaking them apart into multiplication
- 2. Using trig identities, especially the pythagorean identity
- 3. Using shortcut for even/odd functions

1.1.2 Integrating Even and Odd Functions Symmetrically

By intuition, it should be obvious that integrating over the bounds [-a, a] for a symmetric about y (even) function should give twice the integral from [0,a], which can simplify things greatly as we may only need evaluate one endpoint then double it. It's even easier for odd functions, which from [-a, 0] are negative and from [0, a] are equal and opposite, so the integral from [-a, a] cancels and is just zero.

To summarize, for $\int_{-a}^{a} f(x)dx$

- 1. evaluated for even functions $2\int_0^a f(x)dx$
- 2. evaluated for odd functions is just 0

1.2 Mean Value Theorem of Integrals

Let's say F is continuous on [a,b] amd subdivided into n equal intervals. We take the Riemann sum and the Δx with some simple calculations to get that the average value for n intervals is

$$\frac{1}{n} \sum_{i=1}^{n} f(x_1^*) \delta x$$

where x_1^* is any point in the interval, like the right or left bound, or the midpoint. As we do this, we end up with the formula for the Mean Value Theorem of Integrals Below.

The average value of a function over [a, b] given as

$$F_{avg} = \frac{1}{b-a} \int_{a}^{b} f(x)dx$$

Ex. Suppose x(t) gives position and v(t) gives velocity,

$$v_{avg} = \frac{1}{b-a} \int_{a}^{b} \frac{dx}{dt}(x)dt$$

and by fundamental theorem we get that equal to

$$\frac{x_b - x_a}{b - a}$$

Ex. Find the average value of f(x) = 1 on [0,5]:

$$f_{avg} = \frac{1}{5} \int_0^5 (x+1)dx = \frac{1}{5} (5^2/2 + 10/2) = \frac{7}{2}$$

is

Theorem: The MVT of Integrals: If f is

continuous on [a,b] there exists some point on the interval $c \in [a,b]$ where $f(c) = \frac{1}{b-a} \int_a^b f(x) dx = f_{avg}(x)$.

As an interesting corrolary, $\int_a^b f(x)dx = f(c)(b-a)$ - rectangle reduction.

Proof Since f is continuous, by the Extreme Value Theorem, it attains its max M and min m, where $m \leq f(x) \leq M$ for all $x \in [a, b]$.

Since if $g(x) \le h(x) \implies$ the integral of g(x) over [a,b] is less or equal to the integral of h(x) over the range.

Thus $\int_a^b m dx \leq \int_a^b f(x) dx \leq \int_a^b M dx \implies m(b-a) \leq \int_a^b f(x) dx \leq M(b-a) \implies m \leq f_{avg} \leq M$ by dividing by (b-a).

So there exists a d < e where f(e) = m and f(d) = M, then on [d,e] as a subset of [a,b] then by IVT, there exists a $c \in [a, b]$ where

$$f(c) = \frac{1}{b-a} \int_{a}^{b} f(x) dx = \bar{f}$$

HOMEWORK (1): Determine the point C that satisfies the MVTI for $f(x) = x^2 + 3x + 2$ on [1, 2].

Say we wanted to do this on a discontinuous function, we'll have to break it along

the discontinuities. Then, we might get an average value for the function that isn't **The MVT of Integrals:** actually taken on by said function.

1.3 Integration by Parts

Recall the product rule for differentiable functions f and g:

$$(fg)' = f'g + g'f$$

$$\int (fg)'dx = \int f'g(dx) + g'f(dx)$$

Then

$$\int f \cdot g' dx = f \cdot g - \int f' g dx$$

Set u as f(x) and v as g(x) Then du = f'(x)dx and dv = g'(x)dx:

$$\int f \cdot g' dx = f \cdot g - \int f' g dx$$

$$\int udv = uv - \int vdu$$

u, in this case, is being differentiated while dv is being integrated in the LHS term. Also, $v = \int dv = \int g'(x)dx$ by Fundamental Thm. of Calculus, so returns the inside of the bracket (v).

Ex. $\int (3t+5)\cos(\frac{t}{4})dt$ We can take the first term (3t+5) as u, and $\cos(\frac{t}{4})$ as dv. Thus, du = 3dt and $v = 4\sin(\frac{t}{4})$

So:

$$\int (3t+5)\cos(\frac{t}{4})dt = 4(3t+5)\sin\frac{t}{4} - 1^2 \int \sin(\frac{t}{4}dt) \text{ point (a, f(a)) is an inflection point if f is continuous at a and concavity changes sign,}$$

$$= 4(3t+5)\sin\frac{t}{4} + 48\cos\frac{t}{4} + C \qquad \text{eg. when:}$$

You should try to integrate the term that will drop powers.

Easier Ex.

$$x^7 \times lnxdx$$

. We should take u as ln x (because we don't yet know how to integrate it, and differentiating it will give us a power of x, so we'll be done.) and dv as $x^7 dx$.

$$x^7 \times lnxdx = \frac{1}{8}x^8 lnx - \frac{1}{8}\int x^8 \frac{1}{x}$$

$$= \frac{1}{8}x^8 ln(x) - \frac{1}{8}x^8 + C$$

Another Ex.

$$\int \ln x \times 1 dx = \int 1 \times \ln x$$

u is ln x, dv is just 1dx or dx. Our du becomes x^{-1} and our v becomes x via approxpiate differentiation and integration. Thus:

$$\int \ln x \times 1 dx = x \ln x - x + C$$

Homework (2) Integrate

$$\int x\sqrt{x+1}dx$$

- Using substitution
- Using integration by parts

Old Remark about points 1.3.1of inflection

continuous at a and concavity changes sign, eg. when:

- f''(a) = 0 OR
- f''(a) =undefined (vertical)
- - These are NOT sufficient conditions

ex, $f(x) = x^{4}$ $f''(x) = 12x^2$, x = 0 causes f''(x) to be zero However (0,0) is not an inflection point, because the concavity doesn't change.

ex,
$$f(x) = x^{\frac{1}{3}}$$

 $f''x = \frac{-2}{9}x^{\frac{-5}{2}}$

f'(0) is not defined. It has a vertical tangent at zero, Though f" is undefined at that point, (0,0) is still in the original domain so it is a POIfx

ex.
$$f(x) = x^{\frac{2}{3}}$$

 $f''(x) = \frac{-2}{9}x^{\frac{-4}{3}}$

On the line of f'(x), it goes from negative to positive, and from f''(x) it is concave down (negative) both left and right of (0), so it is not a POIFX.

Tabular Integration 1.3.2

Recall:

$$\int_{a}^{b} u dv = uv|_{a}^{b} - \int_{a}^{b} v du$$

Remember, if we are given bounds we take fxgx evaluated at those bounds! (f(b)g(b) - f(a)g(a))

Ex. of Tabular integration:

We need to make a table. Say we had

$$I = \int x^4 e^{\frac{x}{2}}$$

. We want to keep x^4 as u, because differentiating this will get down to 0. To do this, we'd have to make probably 4 I.B.P. executions. We should make a table with the derivatives of x:

$$x^{4} e^{\frac{x}{2}}$$

$$4x^{3} 2e^{\frac{x}{2}}$$

$$12x^{2} 4e^{\frac{x}{2}}$$

$$24x 8e^{\frac{x}{2}}$$

$$24 16e^{\frac{x}{2}}$$

$$0 32e^{\frac{x}{2}}$$

and integrals of $e^{\frac{x}{2}}$.

We take $1,1 \ 2,2 +; \ 2,1, \ 3,2 - \dots$

$$I=x^4-2e^{\frac{x}{2}}-4x^34e^{\frac{x}{2}}+12x^28e^{\frac{x}{2}}-24x16e^{\frac{x}{2}}+24\cdot 32e^{\frac{x}{2}}$$

This alternates signs from integration by parts. This will simplify the integration by parts, because you'd have to do it five times otherwise.

Ex. from hw

$$I = \int e^{2x} \cos(3x)$$

we take either as u or v. By the standard method, it may be easier to take u = cos3x.

$$\begin{array}{ccc} u & dv \\ cos(3x) & e^{2x} \\ \hline -3sin(3x) & \frac{1}{2}e^{2x} \\ -9cos3x & \frac{1}{4}e^{2x} \end{array}$$

 $du = -3sin3x \ v = 0.5e^{2x}$ $= \frac{1}{2}e^{2x}cos(3x) + \frac{3}{2}\int sin(3x)e^{2x}dx.$ Doing the integration by parts again: $= \frac{1}{2}e^{2x}cos(3x) - \frac{9}{4}\int e^{2x}sin(3x)dx$ again $I = \frac{1}{2}e^{2x}cos(3x) + \frac{3}{4}\int sin(3x)e^{2x}dx - \frac{9}{4}I.$

Then we solve for I.

By Tabular Integration: the table is at the top of the column here.

1.4 11 Applications of Integration

1.4.1 11.1 Velocity and Net Change

Let s(t) be the position for t in [a,b] and the total displacement is s(b) - s(a).

This is also $\int_a^b s'(t)dt$.

The total distance is given by

$$\int_{a}^{b} |s'(t)| dt$$

. This involves splitting the integral into positive and negative sections, and multiplying the integral of the negative sections by -1.

Suppose the velocity $v(t) = t^2 - 11t + 24|t \in [0, 8]$. The total displacement is

$$\int_0^8 v(t)dt = \frac{1}{3}t^3 - \frac{11}{2}t^2 + 24t \Big|_0^8 = \frac{32}{3}$$

However, the total distance is

$$D|_{0}^{8} = \int_{0}^{3} v(t)dt + (-) \int_{3}^{8} v(t)dt$$

. Computing this gives $\frac{157}{3}$

Generally, you want to find the zeroes and sum the integrals so you take all of them as positive, multiplying the negative sections by -1 to get the total distance.

As with previously, the average velocity is given by

$$V(t) = \frac{1}{b-a} \int_a^b V(t)dt$$

However, for average speed, we need to take the integrals of positive and negative with $\int -V(t)dt$ for the negative setions and $\int V(t)dt$ for the positive sections.

CHECK THE SIGNS!

1.4.2 11.2 Area Between Curves

There are two ways we can have a region between curves. Let f, g be continuous on [a,b] such that $f(x) \geq g(x)$. We want to find the

area below f and above g. This is computed by

$$\int_{a}^{b} (f(x) - g(x)dx)$$

We could also determine the area between x = f(y) and x = g(y) where $f(y) \ge g(y)$. These are more like left and right functions, where f(y) is on the right of g(y) on some interval [c,d].

$$A = \int_{a}^{b} f(y) - g(y)dy$$

Ex. find the area of the region bounded by f(x) = |x| and $g(x) = x^4$.

- 1. Identify the upper function (-x—) and lower function (x^4) by graphing or substitution. Try a quick sketch.
- 2. Find the bounds.

$$x - x^4 | x > 0$$
 and $x + x^4 | x < 0$

gives $1-x^2$, $1+x^2$, so our bands are [1,1]

3. Compute the appropriate integral:

$$A = \int_{-1}^{1} |x| - x^4 dx = 2 \int_{0}^{1} x - x^4 dx$$

1. Alternatively we can compute this about the y axis, we take the correct functions $x = y^{\frac{1}{4}}$ and x = y. Then,

$$A_R = 2\int_0^1 (y^{\frac{1}{4}} - y)dy$$

Carrying out the computation yields $\frac{3}{5}$

Ex. Find the area bounded by $f(x) = \sqrt{x}$ and $g(x) = \frac{3}{2} - \frac{x}{2}$ above and the x axis below.

This is a bit different as these curves intersect, above the x axis, so we'd have to find their intersection and take two integrals.

$$4x = (3 - x)^{2}$$

$$\Rightarrow x^{2} - 10x + 9 = 0$$

$$x = 1, 9$$

. The area of this region is then

$$\int_0^1 (\sqrt{x} - 0) dx + \int_1^3 \frac{3}{2} - \frac{x}{2} - 0 dx$$

Then we carry out this computation. The upper bound of the last integral is 3 as that is the last point above or equal to the x axis of q(x). Then, it goes below the axis.

We can also try integrating this on the Y axis. We solve for y for both functions, x = 3 - 2y(right), $y = sqrt(x) \Rightarrow x = y^2$. (left). The area is then $A_R = \int_0^1 (3-2y) - y^2 dy$.

Both solutions yield $\frac{5}{3}$ for the area.

Ex. Find the area bounded by the equations 2y = x and $y^2 = 8 - x$. A good way to visualize integrating over x is by taking the vertical slices and over y is by taking horizontal ones.

You might end up with curves with multiple intersections. This is rather annoying to square cut at y, and a is the side length at

solve, and you must find all the intersections, and figure out which functions are on top at each interval.

Volumes by Slicing 1.4.3

Say we had a solid that we could split up into the subsections. The sumall volume element of the subsection dV = A(x)dx. The total volume can be found by taking a cross sectional area and integrating this over the length:

$$V = \int_{a}^{b} A(x)dx \Rightarrow \lim_{h \to \infty} \sum_{i=1}^{h} A(x_{1}^{*}) \Delta x$$

Eg, for a cylinder with height h, on its side with r on the vertical axis and x on the horizontal axis (h being the final value), we take the cross sectional area πr^2 which is just a constant function, and we integrate this over $0 \to h$. So, $V = \int_0^h A(x) dx = \pi r^2 h$.

If we wanted to do this for a pyramid with a square base a^2 and height h. way we slice it depends on the orientation. If we slice it along the vertical axis, the cross section is composed of squares. Now, we can find a side length b of a square horizontal cut, given some distance to the top/bottom and the total height. We can slice the triangle into first right and then similar triangles, and get

$$\frac{h-y}{y\frac{b}{2}} = \frac{h}{\frac{a}{2}}$$

. In this case, b is the side length of the

the bottom. Via algebra we get

$$A(y) = b^2 = a^2(1 - \frac{y}{h})^2$$

. Then, we integrate over the height to get

$$V = a^2 \int_0^h (1 - \frac{y}{h})^2 dy$$

Via integration by substitution, we can compute this to get $\frac{1}{3}a^2h$. Integrating this on its side gives a rather different, and easier integration onverall.

Ex. Suppose we want to find a solid whose base is bounded by the circle $x^2 + y^2 = 4$ (radius 2), where the cross sections are equilateral triangles perpendicular to the X axis We should find a function for the area of the cross section.

We know how to find the base of the triangle (it's a chord) and how to find the area from the base and we combine these facts, to get

$$A_{\Delta} = \frac{\sqrt{3}}{4}a^2$$

and the volume is then

$$V = \int_{-2}^{2} \frac{\sqrt{3}}{4} 2(\sqrt{4 - x^2})^2 da$$

1.4.4 Disc and Shell Methods for Solids of revolution

We're inspecting figures, Solids of Revolution that are obtained by rotation of a curve around an axis. They will have radial symmetry. These are shapes whose curves are expressed as f(x), and a section rotated around a bound [a,b]. The idea is that we're rotating vertical slices of the curve, and getting discs, so we're summing the volumes of discs of infinitesimal thickness.

Method of Discs (Integrating Parallel to the Axis of Rotation)

Due to rotational symmetry, the cross sections are given by

$$\pi(f(x))^2$$

, so we're integrating to get a volume of

$$V = \int_{a}^{b} \pi (f(x))^{2} dx$$

along the x axis (rotation about x), or

$$V = \int_{c}^{d} \pi(g(y))^{2} dy$$

For a cylinder of radius r, and height h (base at origin), we get $V = \int_0^h pi \times r^2 dx = \pi r^2$.

A more interesting example might be the volume of a sphere with radius r, and we can take a semicircle and rotate that around the axis. The equation of this would be $y^2 + x^2 = r^2$ so $y = \sqrt{r^2 - x^2}$, and we can integrate [-r, r] to get (even function can be simplified further)

$$V = \int_{-r}^{r} \pi \sqrt{r^2 - x^2}^2 dx = 2\pi [r^2 x - \frac{1}{3}x^3]_0^r$$

A more general problem would be like: Find the volume of the solid obtained by rotating $f(x) = \sqrt{x}|x \in [0,1]$ around (A) the line y = -2 (B) x = 0 (Y axis).

(A)

We can add 2 to the radius of each disc, so we get $V = \int_0^1 \pi (\sqrt{x} + 2)^2 dx$. This integral is pretty easy to solve.

(B)

We need some function g(y) which is just y(x) in terms of y as the dependent, and also a bound ([y(0), y(1)]) which helpfully is [0, 1] also.

$$V = \int_0^1 \pi(y^2)^2 dy$$

In general, we must find a function for the radius of the VoR, and integrate it over the bounds on the correct axis.

Washer Method - Find the volume of revolution of the region bounded by $f(x) = \sqrt{x}$ and $g(x) = x^{-1}$ for $x \in [1,3]$. These curves intersect at 1, and form a semitriangular shape which, when rotated forms a toridal-type object. We can just subtract the volume of the lower function from the volume of the upper function. (subtracting a bowl from a wedge).

We take the volume

$$V = \int_{1}^{3} \pi(\sqrt{x})^{2} dx - \int_{1}^{3} \pi(x^{-1})^{2} dx$$

Method of Cylindrical Shells (integrate \perp to axis)

Solids of revolution as decomposed into cylindrical shells - imagine we have a cylinder with a conical divot in the middle, we can section and split it to get a bunch of smaller concentric shells, which can be unwrapde so we get a width of dx, and a length of $2\pi r = 2\pi x$ and a height of f(x). The volume can then be expressed as

$$V = \int_{a}^{b} 2\pi x \times f(x) dx$$

. Notice that though we're rotating the curve around y, but taking the integral about x.

Ex. Volume of a sphere about y, with radius r.

We start with a vertical semicircle. As we move out to in, our cylinders get taller and the radius shrinks so they're skinnier too.

The equation that governs the height (which we'll mulliply by two) is $y = \sqrt{r^2 - x^2}$ and the height is thus $2\sqrt{r^2 - x^2}$ and our integral becomes

$$V = 2 \int_0^r 2\pi x \sqrt{r^2 - x^2}$$

It's solvable by integrating with a u-sub for x^2 to get

$$w = x^2 - r^2, dw = -2xdx$$

$$V = -2\pi \int_{r^2}^0 \sqrt{w} dw = \frac{4\pi r^3}{3}$$

. It's a bit more complex, and thus maybe better to use the disc method for this.

Ex. Find the volume of the solid bounded above by $f(x) = 3x - x^2$ and below by y = 0 over [0,3] around the y axis. By the disc method, we'll probably have to do a subtraction, and we can do this in one step with the shell method. The volume is given by $V = \int_0^3 2\pi x (3x - x^2) dx$ which can be easily integrated.

Q: Why is the disc method problematic?

We'd have to subtract an inner region from an outer one. $y = 3x - x^2$ would need to be expressed in terms of y by factoring, and you'd get a bundt cake looking thing, and we'd have to use the washer method and do a LOT of different integrations.

Ex. Find the volume of the region by revolving around the x axis bounded by $y = 2 - x^2$ and $y = x^2$. By the disc method:

$$V = \int_0^1 \pi (2 - x^2)^2 - (x^2)^2 dx$$

By the shell method, we'd integrate in y. The height of our cyinders are given by the value of the function on wrt y and we have to break it as it looks piecewise, and we get our volume as

$$V = \int_{1}^{2} 2\pi y \sqrt{2 - y} dy + \int_{0}^{1} 2\pi y \sqrt{y} dy$$

1.4.5 Arc Length

If we had some arbitrary curve, a piece of f, we could break the curve up [a to b], and get infinitesimal striaght line sections dl, which corresponds to some $\frac{dy}{dx}$ right triangle. We get via pythagorean theorem $dl = \sqrt{dx^2 + dy^2} = \sqrt{1 + (\frac{dy}{dx})^2} \cdot dx$. We can put this into an integral and get $\mathbb{L} = \int_a^b dl = \int_a^b \sqrt{1 - (\frac{dy}{dx})^2} \cdot dx$.

Applied to the circumference of a circle, we take the top half , and get $y=\sqrt{r^2-x^2}$ and integrate to get $\frac{-x}{r^2-x^2}$ and finally

$$L = 2\int_{-r}^{r} \sqrt{1 + \frac{x^2}{r^2 - x^2}} dx$$

Taking the common denominator we get $\sqrt{\frac{r^2}{r^2-x^2}}dx$ in the integrand so $dl = \frac{r}{\sqrt{r^2-x^2}}dx$. We can pull out the r in the denominator as it's constant, and we can get

$$\frac{2r}{r} \int_{-r}^{r} \frac{dx}{\sqrt{1 - \frac{x^2}{r^2}}}$$

We can use trig substitution and get $4r(arcsin(1) - arcsin(0)) = 4r \times \frac{\pi}{2} = 2\pi r$

1.4.6 Surface Area of Solids of Revolution

We extend the arc length concept to be applied to surface areas.

By dividing infintesimal segments dl out of the whole arc, we get ribbon or sheet or cylinders with some rectangular area. Around the x axis, the area is $dS = dl \times 2\pi f(x)$. Integrating, we get

$$S = \int_a^b ds = \int 2\pi \cdot dl f(x) dx = 2\pi f(x) \sqrt{1 - (1 - \epsilon)^2}$$

about x. If we swap axes, we get

$$\int_{a}^{b} 2\pi x \sqrt{1 + (\frac{dy}{dx})^2} dx$$

For example, the surface area of a sphere of radius r:

$$S = \int_{-r}^{r} 2\pi \sqrt{r^2 - x^2} \times \frac{r}{r^2 - x^2} dx$$

gives $4\pi r^2$.

1.4.7 Work

The work done by a force in moving an object from x = a to x = b, and say the force is non constant and given by F(x), we get

$$W = \int_{a}^{b} F(x)dx$$

The problem ends up being constructing F(x) which requires practise.

Ex. A cable weighs 2 lbs/ft, and is attached to a bucket filled w/ coal that weighs 800 lbs. The bucket is initally at the bottom of a 500 ft well. We should determine (a) the work to get to the middle of the well from the bottom, and (b) midpoint to top and (c) total work (summing a+b)

Our initial formulation of this problem is knowing that force changes, as we need to pull up less cable once we lift it, and add the

constant mass of the bucket. (ie. cable mass is a function of x), $F(x) = (m_B + m_C(x)) \times g$ where relative to a coordinate system $\frac{d(d_{C})}{dE}(x) = 2(900 - x) \cdot g$, and the integral of this takes points from 0 to 250, then 250 to 500, then we can add them for c.

Another standard probelm has to do with a tank in the shape of an inverted cone, with a height h = 15m and a base radius r = 4m filled to a depth of d = 12m. The question is

How much work is required to pump all the water out of the top, assuming $\rho = 1Mg/m^3$. Visualizing this as cross sectional area means we should inspect how the volume changes and how much force it takes to lift individual, infinitesimal discs of the cone on the xsection. We can find a ratio for the radius r(x)/4 = x/15 of the disc by similar triangles, and a function for the distance D(x) = 15 - x. $dV = A(x)dx = \pi(r(x))^2 dx$ We know that $\rho = \frac{m}{v}$

To get r as a function of x, we can use similar triangles: $\frac{r(x)}{x} = \frac{4}{15}$ so we know our volume via substitution is $\pi(\frac{4x}{15})^2 dx$.

The infinitesimal weight is equal to $dF = g \cdot dM = g \cdot \rho_w dV$. Since we know dV we can substitute this in as well. The infinitesimal work dW = D(x)dF. We

The infinitesimal work dW = D(x)dF. We know also that the distance D(x) is the height - x, so D(x) = 15 - x.

Taking all the substitutions, we get total work

$$W = \int_0^1 2(15 - x)(\pi g \rho_w(\frac{4}{15})^2 x^2 dx)$$

Another way to think of this is that we're dividing the water into n pieces, with width $\Delta x = \frac{12}{n}$, so we get the total work as $W(n) = \sum_{i=1}^{n} W_i$. The W_i s: For $x_I^* \in [x_{i-1}, x_i]$ ith disc is given by $W_i = D(x_i^*)F_i$. We know $F_i = \rho_w gV_i$. Breaking this down further we have area $A(x_i^*)$... and so on, we break this down from force into volume into area into radius as a function of x. Then we take the summation of these, as n tends to infinity.

When doing the integration, take care to take the constant terms out of the integral.