## Lecture 12: Estimation (continued)

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Asymptotic properties of MLE: For a stationary and invertible ARMA model

$$\phi(B)Z_t = \theta(B)a_t$$

where  $\phi(B) = 1 - \phi_1 B - \dots - \phi_p B^p$  and  $\theta(B) = 1 - \theta_1 B - \dots - \theta_q B^q$  are polynomials with no common factors and  $\{a_t\}$  is a sequence of *iid* Gaussian random variables with mean zero and variance  $\sigma_a^2$ , the MLE (both conditional and exact) of the parameters  $\phi$ 's and  $\theta$ 's are (a) consistent and (b) asymptotically normal. More precisely, let  $\beta = (\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q)'$ , and  $\hat{\beta}$  the MLE of  $\beta$ . Then,

$$\sqrt{n}(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \sim N(\boldsymbol{O}, \boldsymbol{V}_{\beta})$$
 as  $n \to \infty$ 

where n is the sample size and  $V_{\beta}$  is a  $(p+q)\times(p+q)$  covariance matrix defined by

$$oldsymbol{V}_{eta} = \sigma_a^2 \left[ egin{array}{ccc} E(oldsymbol{u}_t oldsymbol{u}_t') & E(oldsymbol{u}_t oldsymbol{v}_t') \ E(oldsymbol{v}_t oldsymbol{u}_t') & E(oldsymbol{v}_t oldsymbol{v}_t') \end{array} 
ight]^{-1}$$

where  $\boldsymbol{u}_t = (u_t, u_{t-1}, \dots, u_{t-p+1})'$  and  $\boldsymbol{v}_t = (v_t, v_{t-1}, \dots, v_{t-q+1})'$  with  $u_t$  and  $v_t$  satisfying

$$\phi(B)u_t = a_t, \quad \theta(B)v_t = -a_t.$$

The asymptotic normality of the MLE follows basically the usual argument as that of the iid case with CLT replaced by certain functional central limit theorem. You may consult standard time series textbooks for details, e.g. Box and Jenkins (1976) and Brockwell and Davis (1991, Ch. 8 & 10). Here we shall discuss the reason supporting the asymptotic variance  $V_{\beta}$ .

Recall that the log-likelihood function of  $Z_t$  is approximately

$$\ell_n(\boldsymbol{\beta}) \propto -\frac{n}{2} \ln \sigma_a^2 - \frac{1}{2\sigma_a^2} \sum_{t=1}^n a_t^2$$

where  $a_t = Z_t - \phi_1 Z_{t-1} - \cdots - \phi_p Z_{t-p} + \theta_1 a_{t-1} + \cdots + \theta_q a_{t-q}$ . The asymptotic covariance matrix of the MLE of  $\beta$  is then the inverse of the expected Fisher information matrix

$$E\left[-\frac{\partial^2 \ell_n(\boldsymbol{\beta})}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}'}\right] = E\left[\left(\frac{\partial \ell_n(\boldsymbol{\beta})}{\partial \boldsymbol{\beta}}\right)\left(\frac{\partial \ell_n(\boldsymbol{\beta})}{\partial \boldsymbol{\beta}}\right)'\right].$$

From the log-likelihood function, it is important to consider the derivatives of  $a_t$  with respect to  $\beta$  in order to compute the Fisher information matrix. It can also be shown that

the MLE of  $\boldsymbol{\beta}$  is asymptotically uncorrelated with that of  $\sigma_a^2$  so that we can work on  $\boldsymbol{\beta}$  and  $\sigma_a^2$  separately.

Let

$$-\frac{\partial a_t}{\partial \phi_i} = u_{t-i}, \quad -\frac{\partial a_t}{\partial \theta_j} = v_{t-j}.$$

From  $a_t = Z_t - \phi_1 Z_{t-1} - \dots - \phi_p Z_{t-p} + \theta_1 a_{t-1} + \dots + \theta_q a_{t-q}$ , we have

$$u_{t-i} = Z_{t-i} + \theta_1 u_{t-1-i} + \dots + \theta_q u_{t-q-i}$$

and

$$v_{t-j} = \theta_1 v_{t-1-j} + \dots + \theta_q v_{t-q-j} - a_{t-j}.$$

In other words, we have

$$\theta(B)u_t = Z_t$$
, and  $\theta(B)v_t = -a_t$ .

Next, since  $Z_t = \frac{\theta(B)}{\phi(B)} a_t$ , we further obtain

$$\theta(B)u_t = \frac{\theta(B)}{\phi(B)}a_t$$

so that

$$\phi(B)u_t = a_t.$$

From the stationarity and invertibility of  $Z_t$ , both  $u_t$  and  $v_t$  are stationary processes. Therefore, the Fisher information matrix is

$$V_{\beta}^{-1} = \frac{n}{\sigma_a^2} E\left[ \left( \begin{array}{c} \boldsymbol{u}_t \\ \boldsymbol{v}_t \end{array} \right) \left( \boldsymbol{u}_t', \boldsymbol{v}_t' \right) \right]$$

where  $\boldsymbol{u}_t$  and  $\boldsymbol{v}_t$  are defined as above.

In practice, the Fisher information matrix is evaluated by substituting  $\beta$  by  $\hat{\beta}$ .

Some special cases: In what follows, we consider results of some simple ARMA models.  $\overline{AR(p) \text{ Model}}$ :  $\phi(B)Z_t = a_t$ . For this model, the derived process  $u_t$  is an AR(p) process also. Therefore,

$$oldsymbol{V}_{eta}^{-1}=rac{n}{\sigma_a^2}oldsymbol{\Gamma}_p$$

where  $\Gamma_p$  is the covariance matrix of  $(u_t, \dots, u_{t-p+1})'$ , or equivalently, the covariance matrix of  $(Z_t, \dots, Z_{t-p+1})'$ . Consequently, we have

• AR(1):  $\hat{\phi}_1 \sim N(\phi_1, \frac{1-\phi_1^2}{n})$ .

• AR(2):  $\hat{\boldsymbol{\phi}} \sim N(\boldsymbol{\phi}, \boldsymbol{V})$  where  $\boldsymbol{\phi} = (\phi_1, \phi_2)'$  and

$$V = \frac{1}{n} \begin{bmatrix} 1 - \phi_2^2 & -\phi_1(1 + \phi_2) \\ -\phi_1(1 + \phi_2) & 1 - \phi_2^2 \end{bmatrix}.$$

MA(q) Model:  $Z_t = \theta(B)a_t$ . Since the derived process  $v_t$  satisfies  $\theta(B)v_t = -a_t$ , which is an AR(q) model, we obtain the same results as those of pure AR models.

- MA(1):  $\hat{\theta}_1 \sim N(\theta_1, \frac{1-\theta_1^2}{n})$ .
- MA(2):  $\hat{\theta} \sim N(\boldsymbol{\theta}, V)$  where  $\boldsymbol{\theta} = (\theta_1, \theta_2)'$  and

$$V = \frac{1}{n} \begin{bmatrix} 1 - \theta_2^2 & -\theta_1(1 + \theta_2) \\ -\theta_1(1 + \theta_2) & 1 - \theta_2^2 \end{bmatrix}.$$

Mixed ARMA(1,1) Model:  $Z_t - \phi Z_{t-1} = a_t - \theta a_{t-1}$ . For this process, the asymptotic covariance matrix of MLE of  $\beta = (\phi, \theta)'$  is

$$V = \frac{1}{n} \frac{1 - \phi \theta}{(\phi - \theta)^2} \begin{bmatrix} (1 - \phi^2)(1 - \phi \theta) & (1 - \phi^2)(1 - \theta^2) \\ (1 - \phi^2)(1 - \theta^2) & (1 - \theta^2)(1 - \phi \theta) \end{bmatrix}.$$