

# Machine Learning 2018-19

## Final Exam

12 December 2018

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**Question 1:** 2 points In linear regression, the *hat matrix*  $H = X(X^\top X)^{-1}X^\top$  puts the “hat” on the true output  $\mathbf{y}$ , i.e. the estimated output equals  $\hat{\mathbf{y}} = H\mathbf{y}$ . Show that a)  $H^\top = H$ ; b)  $H^2 = H$ ; c)  $(I - H)^2 = (I - H)$ . Hints: For any multiplicable matrices  $A$  and  $B$ ,  $(AB)^\top = B^\top A^\top$ , and for any square matrix  $C$ ,  $(C^{-1})^\top = (C^\top)^{-1}$ .

**Question 2:** 2 point Which are the components of supervised learning? Which of these components can be controlled by a machine learning practitioner?

**Question 3:** 1 point What is overfitting? Name three factors that increase the amount of overfitting.

**Question 4:** 1 point What is regularization? Explain how regularization is defined theoretically, and how regularization is usually implemented in practice. Why is there a difference?

**Question 5:** 1 point In decision tree learning, how is information gain defined? Describe the standard algorithm for learning decision trees.

**Question 6:** 1 point Explain how recurrent neural networks differ from feedforward neural networks. Describe one advantage and one disadvantage of recurrent neural networks, compared to feedforward neural networks.

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**Question 7:** 1 point Write down the Bayes Theorem. Describe two possible uses of this theorem in Machine Learning. For each use, describe precisely each term in the formula.

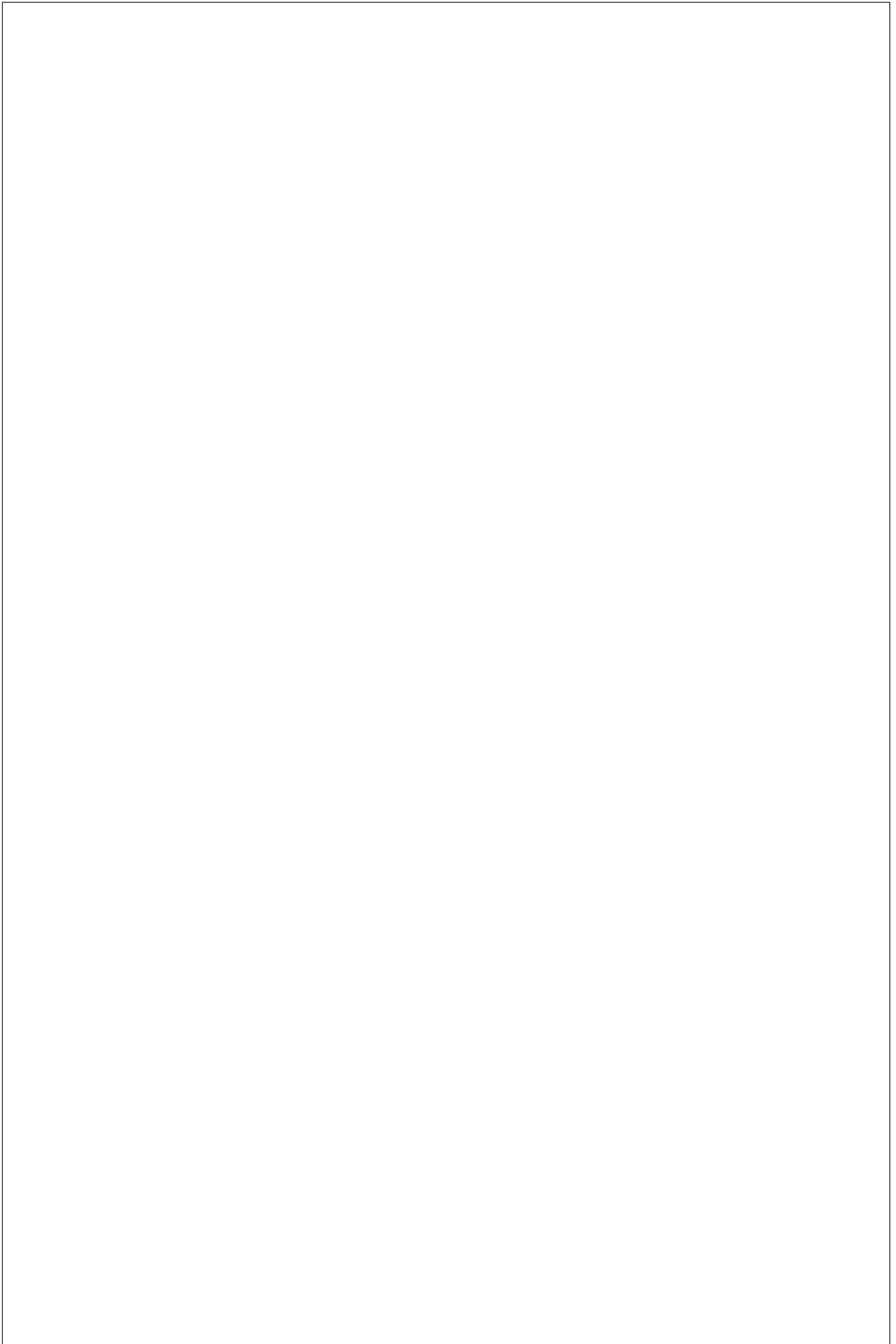
**Question 8:** 2 point

A belief network models the relation between the variables oil (*oil*), inflation (*inf*), economy health (*eh*), British petroleum stock price (*bp*), and retailer stock price (*rt*). Each variable takes the states  $\{low, high\}$  except for *bp* which has states  $\{low, high, normal\}$ . The Bayesian network model for these variables has tables

$$\begin{aligned} p(eh = low) &= 0.2 \\ p(bp = low|oil = low) &= 0.9 & p(bp = normal|oil = low) &= 0.1 \\ p(bp = low|oil = high) &= 0.1 & p(bp = normal|oil = high) &= 0.4 \\ p(oil = low|eh = low) &= 0.9 & p(oil = low|eh = high) &= 0.05 \\ p(rt = low|inf = low, eh = low) &= 0.9 & p(rt = low|inf = low, eh = high) &= 0.1 \\ p(rt = low|inf = high, eh = low) &= 0.1 & p(rt = low|inf = high, eh = high) &= 0.01 \\ p(inf = low|oil = low, eh = low) &= 0.9 & p(inf = low|oil = low, eh = high) &= 0.1 \\ p(inf = low|oil = high, eh = low) &= 0.1 & p(inf = low|oil = high, eh = high) &= 0.01 \end{aligned}$$

1. **(1pt)** Draw the corresponding Bayesian network for this distribution.
2. **(0.5pt)** Use the D-Separation algorithm to argue whether the following conditional independences are satisfied or not.
  - (a) Is *eh* independent of *bp* if no evidence is provided? Why?
  - (b) Is *eh* independent of *bp* if we observe that the *oil* is *high*? Why?
  - (c) Is *rt* independent of *bp* if we observe that *eh* is *low*? Why?
3. **(0.5pt)** Given that the British stock price is normal (*bp* = *normal*) and the retailer stock price is high (*rt* = *high*), what is the probability that inflation is high (*inf* = *high*)?

(answers on next page)



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**Question 9:** 1 point In the context of discounted Markov decision processes, define the value function  $V^\pi$  associated with a deterministic policy  $\pi : \mathcal{X} \rightarrow \mathcal{A}$ .

Hint: give either the basic definition involving an infinite sum, or the Bellman equations.

**Question 10:** 1 point The Policy Iteration algorithm for discounted Markov decision processes iteratively computes a sequence of value functions and policies  $V_1, \pi_1, V_2, \pi_2, \dots, V_k, \pi_k$ . In a given iteration  $k$  of the algorithm, what is the relation between  $V_k$  and  $\pi_k$  (i.e., the policy computed right after computing  $V_k$ )?

**Question 11:** 2 point Describe the SARSA and the Q-learning algorithms for discounted Markov decision processes. What are the respective behavior and target policies of the two algorithms?