## Machine Learning 2015-16 Final Exam

16 December 2015				
Name:				
Questions				
<b>Question 1:</b> 2.5 points In linear regression, the <i>hat matrix</i> $H = X(X^{T}X)^{-1}X^{T}$ is defined such that $\hat{\mathbf{y}} = H\mathbf{y}$ , where $\mathbf{y}$ are the true outputs and $\hat{\mathbf{y}}$ are the estimated outputs. Show that a) $H^{T} = H$ ; b) $H^{2} = H$ ; c) $(I - H)^{2} = (I - H)$ . Hints: $(AB)^{T} = B^{T}A^{T}$ and $(A^{-1})^{T} = (A^{T})^{-1}$ .				
Question 2: 2.5 points Late one night, a woman was mugged at the UPF Poblenou Campus. The perpetrator was masked and did not speak, but the woman claims it was another woman who robbed her. In tests under similar circumstances (same light level, same clothing, same distance), the woman correctly predicted the gender (male or female) of different people 80% of the time. Of the people working and studying at the Poblenou Campus, 70% are male and 30% are female. What is the probability that the perpetrator was a woman?				

regarding the out-of-sample error?	Question 3:	1 points T	he Hoeffding	inequality a	pplied to lea	rning is		
Question 4: 1 points Given a hypothesis set $\mathcal{H}$ , how is a break point for $\mathcal{H}$ defined?  Question 5: 1 points What is the main difference between the union bound and the VC bound regarding the out-of-sample error?			$\mathbb{P}[ E_{in}$	$(h) - E_{out}($	$ h)  > \epsilon] \le 2$	$e^{-2\epsilon^2N}$ .		
Question 5: 1 points What is the main difference between the union bound and the VC bound regarding the out-of-sample error?	What is	the meanin	g of this inequ	ality, and w	hy is it impo	ortant for m	achine learr	ning?
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estion 11:	1 points	Describe two different techniques for multiclass classification.			
I	1 points algorithm	How does the error measure affect the final hypothesis of a machine n?			
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**Question 13:** 5 points The QMR-DT database is a bipartite graphical model in which the upper layer of nodes represent diseases and the lower layer of nodes represent symptoms. The evidence is a set of observed symptoms (findings) and represent the vector of findings with the symbol f. The symbol d denotes the vector of diseases. All nodes are binary, thus the components  $f_i$  and  $d_i$  are binary random variables.

- 1. Write down the joint probability model p(f, d).
- 2. Draw the structure of the QMR-DT graphical model as a Bayesian network (represent the evidence as shaded nodes).
- 3. Draw the corresponding factor graph model of the QMR-DT Bayesian network.
- 4. Given the following "noisy-OR" model for the conditional probabilities:

$$P(f_i = 0|d) = (1 - q_{i0}) \prod_{j \in \pi(i)} (1 - q_{ij})^{d_j},$$

where  $q_{i0}$  is the probability that the *i*th finding is present even though no disease is present; and  $q_{ij}$  is the probability that the *i*th finding is present when disease *j*th is present ( $q_{i0}$  and  $q_{ij}$  are given by experts).

- (a) Suggest a graphical transformation that represents each factor involving n variables in terms of factors that involve at most 3 variables.
- (b) What is the main bottleneck for inference in this model? [hint: rewrite the noisy-OR model on an exponential form using  $\theta_{ij} \equiv -\log(1-q_{ij})$ ].

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