

Missing Data

and how to deal with them...

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Machine Learning development from Model-Centric to Data-Centric

Andrew Ng:

When a system isn't performing well, many teams instinctually try to improve the code.

But for many practical applications, it's more effective instead to focus on improving the data,

<https://www.deeplearning.ai/the-batch/issue-84/>

Model-Centric view

- Collect what data you can, and develop a model good enough to deal with the noise in the data
- Hold the data fixed and iteratively improve the code/model

Data-Centric view

- The consistency of the data is paramount. Use tools to improve the data quality
 - *this will allow multiple models to do well*
- Hold the model fixed and iteratively improve the data

<https://www.deeplearning.ai/the-batch/issue-84/>

From big data to good data

MLOps' most important task: **ensure consistently high-quality data in all phases of the ML project lifecycle**

Good data is

- Defined consistently (definition of labels y is unambiguous)
- Cover of important cases (good coverage of inputs x)
- Has timely feedback from production data (distribution covers data drift and concept drift)
- Sized appropriately

<https://www.deeplearning.ai/the-batch/issue-84/>

Good data without missing data

- Getting high-quality data also includes tackling noise data
- Data can become noise caused of missings

Missing data

Missing data is everywhere sooner or later anyone who does statistics will encounter missing data

Can arise for many reasons:

- Non-Response e.g. in surveys
- Lost data due to machine or human mistakes
- Bug issues in non-mandatory fields
- join, merge
- different variable per source
- different number of categories per source
- ...

The problem

- Using only the complete cases for the analysis can lead to a dramatic information loss
- Many AI/ML/Data science methods are developed for complete data
- Inappropriate approach imposes noise or bias on data
- Missing data can lead to the risk of incorrect conclusions due to absence of relevant information leading to invalid results
- The quality of statistical analysis can be only as good as the quality of the data

Terminology

- **full data** $Z = (Z_{\text{obs}}, Z_{\text{mis}})$
- **observed data** Z_{obs}
- **missing data** Z_{mis}
- Given $n \times p$ data matrix Z , which can contain missing data
- $Z = (Y, X)$, i.e. Y matrix dependent and X matrix independent variables
- Indicator matrix R build from Z as

$$R_{ij} = \begin{cases} 1 & \text{if } Z_{ij} \text{ obs} \\ 0 & \text{if } Z_{ij} \text{ mis} \end{cases} \quad \text{for } i = 1, \dots, n \text{ and } j = 1, \dots, p.$$

Types of missingness

Missing completely at random (MCAR)

Probability of missingness is completely independent from observed and unobserved/missing values

$$P(r_i \mid z_i) = P(r_i \mid z_{i, \text{obs}}, z_{i, \text{mis}}) = P(r_i), \quad \text{for } i = 1, \dots, n,$$

where $z_{i, \text{obs}}$ represents the observed and $z_{i, \text{mis}}$ the missing values from the i -th row z_i of the data matrix Z .

- No particular reason that the data is missing
- Often an unrealistic assumption
- **Example:** Weighing scale that ran out of batteries

Missing at random (MAR)

The probability for missiness of values is only dependent of the observed values $z_{i, \text{obs}}$

$$P(r_i \mid z_i) = P(r_i \mid z_{i, \text{obs}}, z_{i, \text{mis}}) = P(r_i \mid z_{i, \text{obs}}), \quad \text{for } i = 1, \dots, n.$$

- Relationship between missing values and observed ones
- More realistic than MCAR
- Modern missing data methods generally start from the MAR assumption
- **Example:** Weighing scale may produce more missing data when placed on a soft surface and type of surface is known

Missing not at random (MNAR)

The probability for the missingness of values is dependent of the observed $z_{i, \text{obs}}$ and unobserved values $z_{i, \text{mis}}$

$$P(r_i \mid z_i) = P(r_i \mid z_{i, \text{obs}}, z_{i, \text{mis}}), \quad \text{for } i = 1, \dots, n.$$

- Cause of missingness it not known and we cannot draw any conclusion from observed data
- **Example:** Weighing scale mechanism may wear out over time, but time is not part of the dataset

Best practices (vanBuuren (2018))

- Distinguishing the type of missingness is not easy, sometimes it's impossible
- The size and balance of data must be considered before distinguishing the type
- Under MCAR, one can analyze the observed observation and ignore or discard any missing observations
- Rule of thumb: assume missing at random unless there is a good reason not to!

Look at the data

airquality dataset

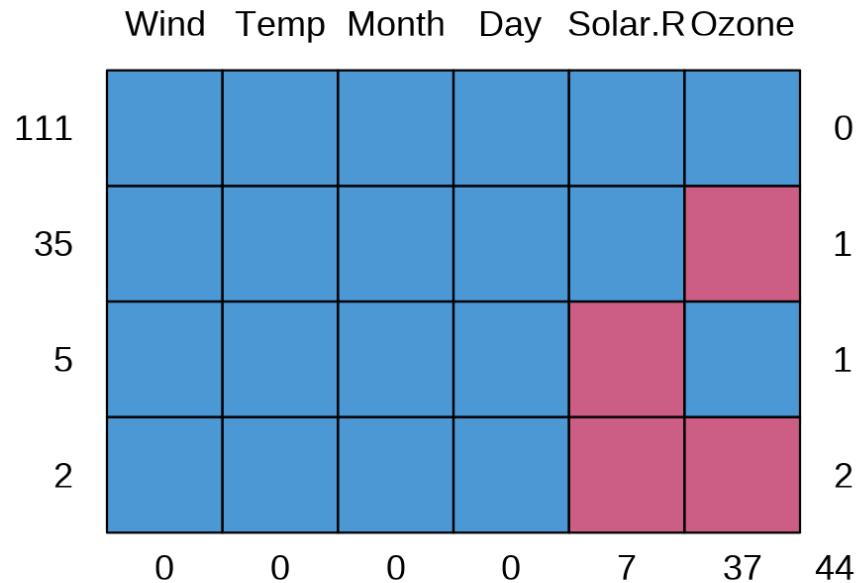
- Daily air quality measurements in New York, May to September 1973.
- Daily readings of the following air quality values for May 1, 1973 (a Tuesday) to September 30, 1973.
 - **Ozone:** Mean ozone in parts per billion from 1300 to 1500 hours at Roosevelt Island
 - **Solar.R:** Solar radiation in Langleys in the frequency band 4000–7700 Angstroms from 0800 to 1200 hours at Central Park
 - **Wind:** Average wind speed in miles per hour at 0700 and 1000 hours at LaGuardia Airport
 - **Temp:** Maximum daily temperature in degrees Fahrenheit at La Guardia Airport.

Source: The data were obtained from the New York State Department of Conservation (ozone data) and the National Weather Service (meteorological data).

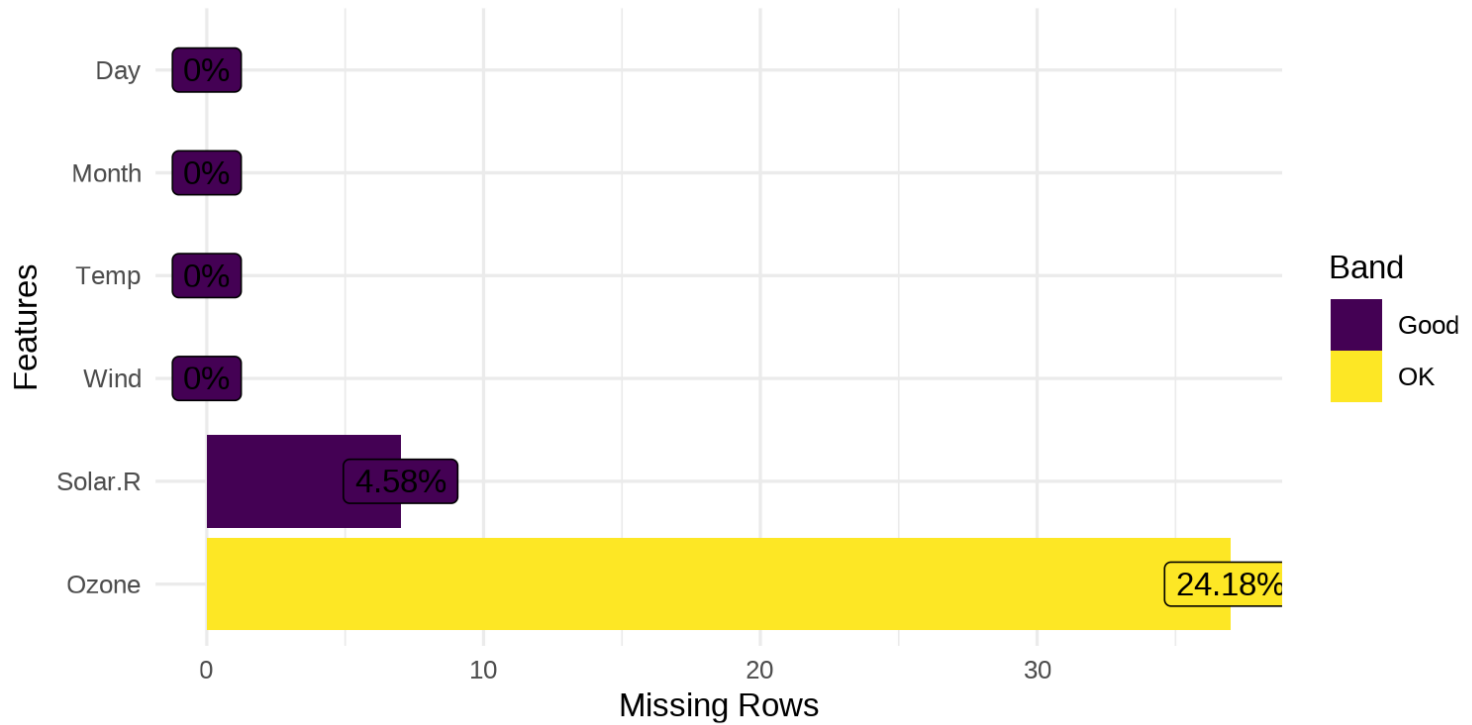
airquality dataset

Ozone	Solar.R	Wind	Temp	Month	Day
41	190	7.4	67	5	1
36	118	8.0	72	5	2
12	149	12.6	74	5	3
18	313	11.5	62	5	4
NA	NA	14.3	56	5	5
28	NA	14.9	66	5	6
23	299	8.6	65	5	7
19	99	13.8	59	5	8
8	19	20.1	61	5	9
NA	194	8.6	69	5	10

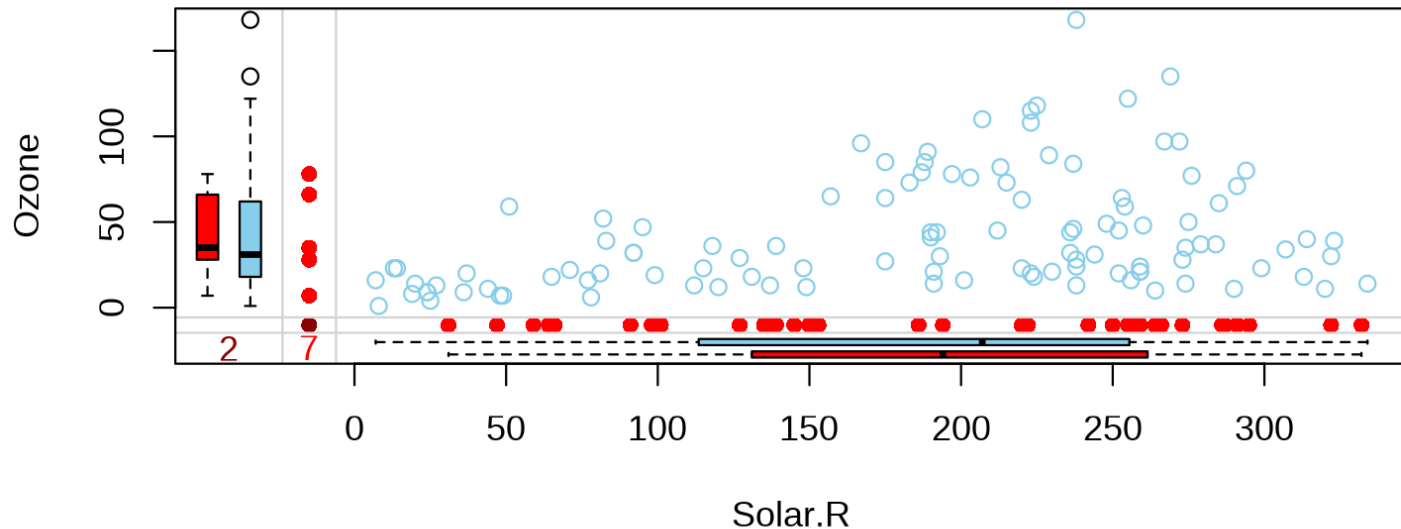
missing data pattern



missing value frequency



marginplot



- blue one summarizes the distribution of Ozone when Solar.R is missing, red one summarizes it when it is unobserved
- distribution of observed data given the other variable is observed for MCAR, blue and red box plots should be similar

How to deal with missingness

Missing values methods

- Dropping missing values
- Imputation techniques
 - Single imputation
 - Multiple imputation

Dropping (ignoring) missing values

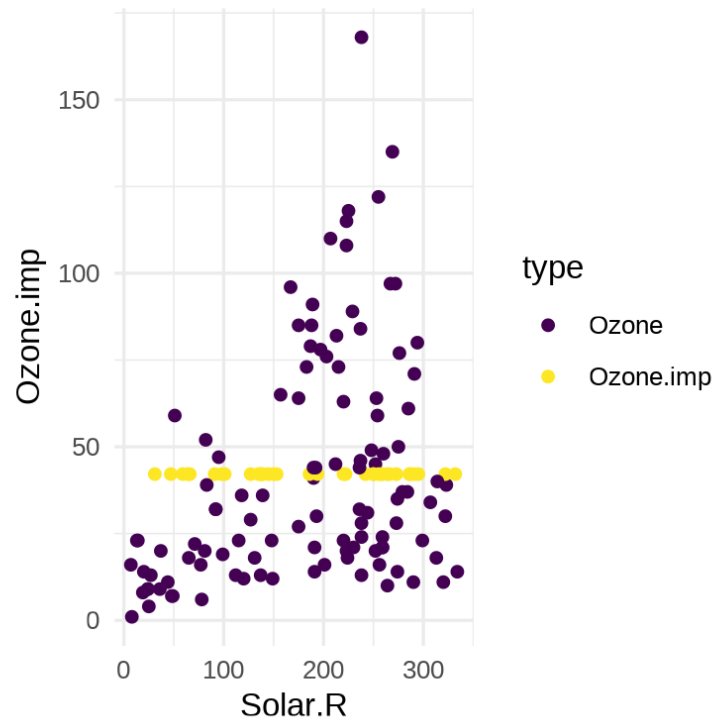
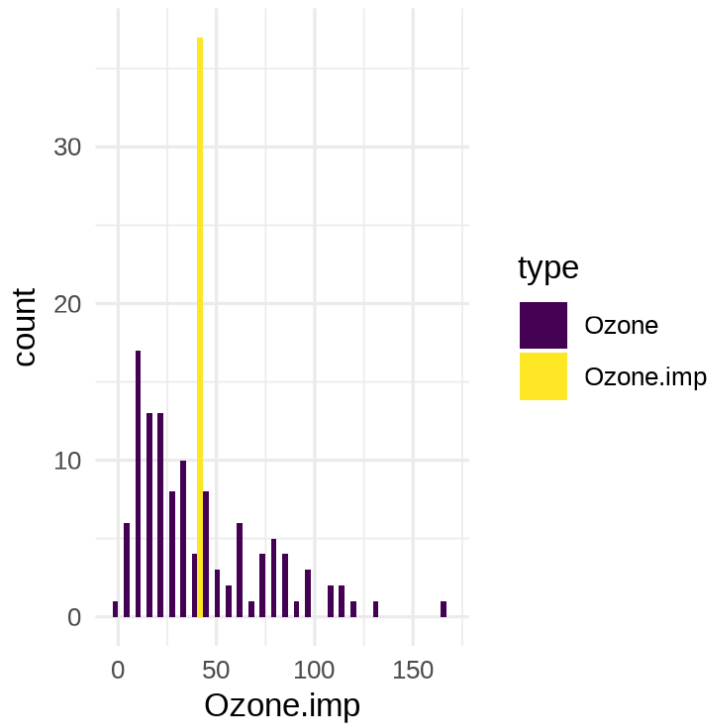
Listwise deletion

- Cases with missing values are excluded from the data set.
- Only the complete cases are analyzed or used.
- Loss of information dependent on the fraction of missing data
- Often the default way of handling incomplete data
- If the data are MCAR, listwise deletion produces unbiased estimates of means, variances and regression weights.
- **Schafer and Graham (2002)**: *If a missing data problem can be resolved by discarding only a small part of the sample, then the method can be quite effective.*

Mean/Median imputation

- Missing values are replaced by
 - the mean value for quantitative variables
 - by the most frequently occurring category for qualitative variables
- Imputed value is an estimate, thus there is uncertainty about its true value
- Uncertainty is measured by its standard error
- Too small standard errors

Mean/Median imputation

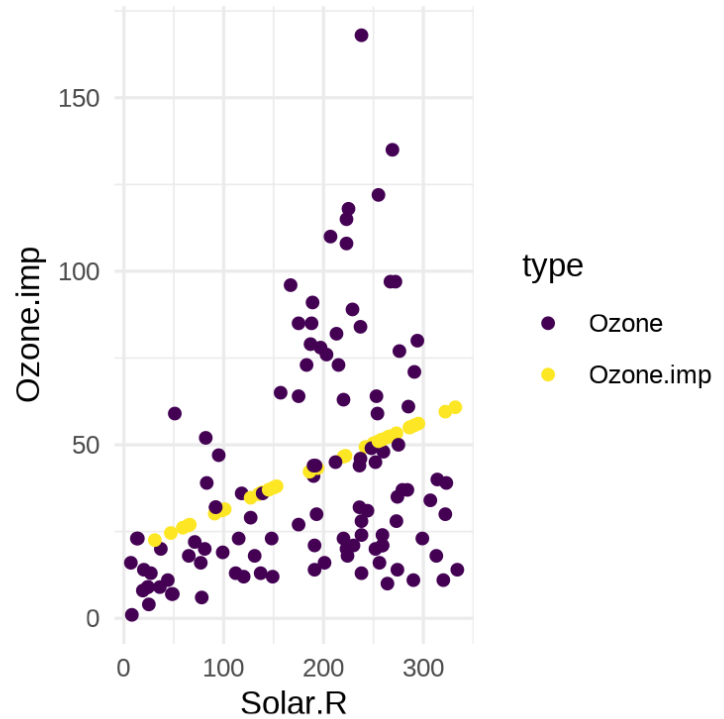
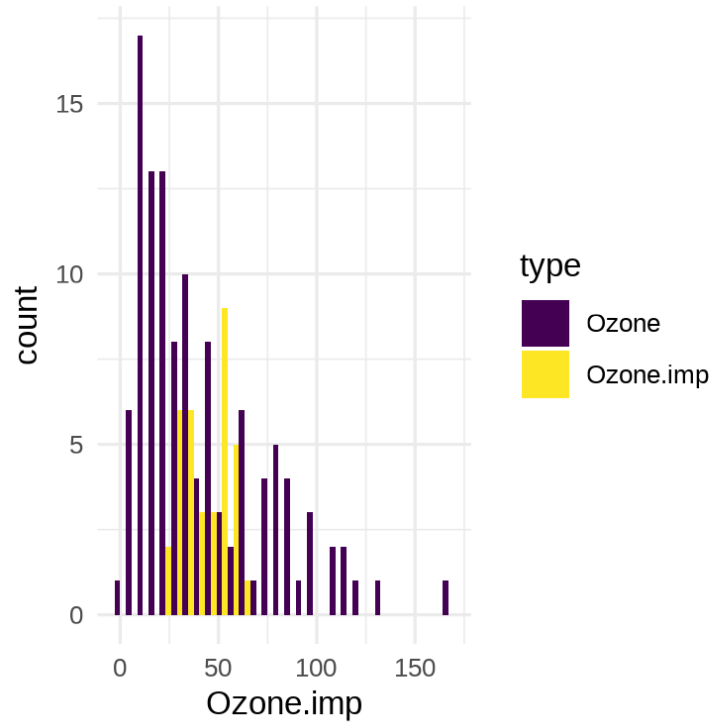


Regression Imputation

- Regression imputation incorporates knowledge of other variables with the idea of producing smarter imputations.
- The first step involves building a model from the observed data.
- Predictions for the incomplete cases are then calculated under the fitted model, and serve as replacements for the missing data.

$$\text{Ozone} = \alpha + \beta_1(\text{Solar. R}) + \epsilon$$

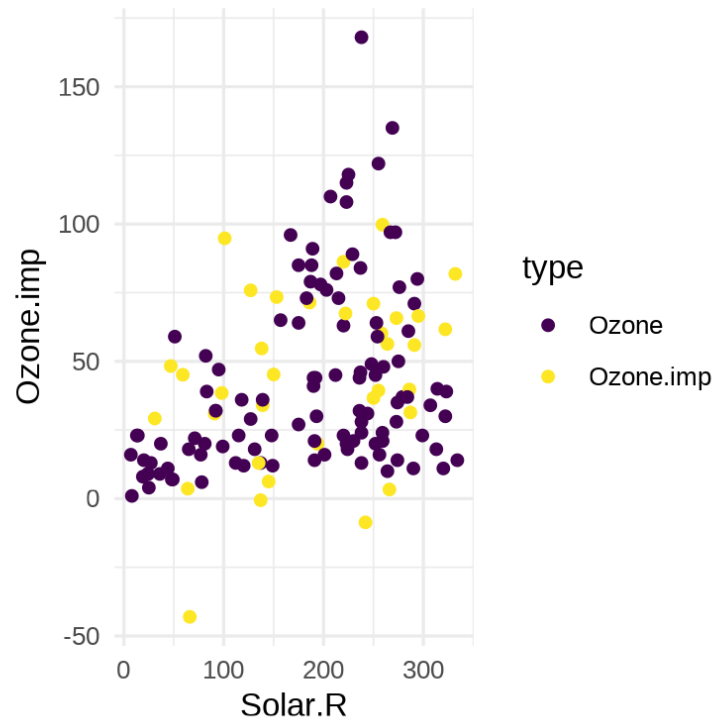
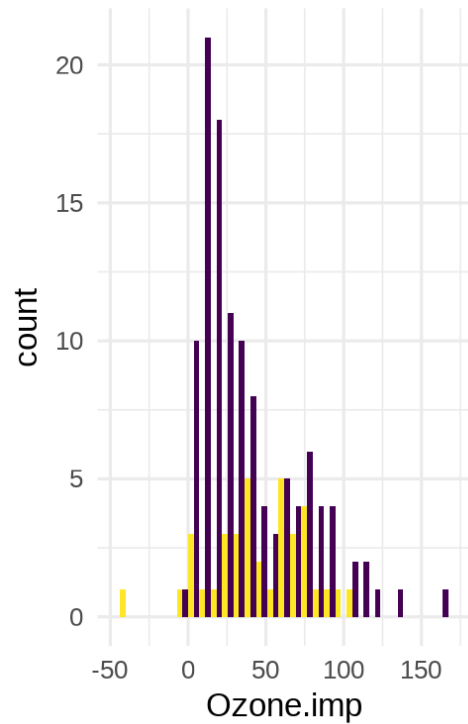
Regression Imputation



Stochastic Regression Imputation

- One disadvantage to regression imputation is that it used the fitted model without error terms. Therefore, the imputed results are too close to the regression line and biased the correlations, reduced the variance of the data.
- Stochastic regression corrected this problem by adding a error term when imputing the values, which potentially better reflect the correlations between variables

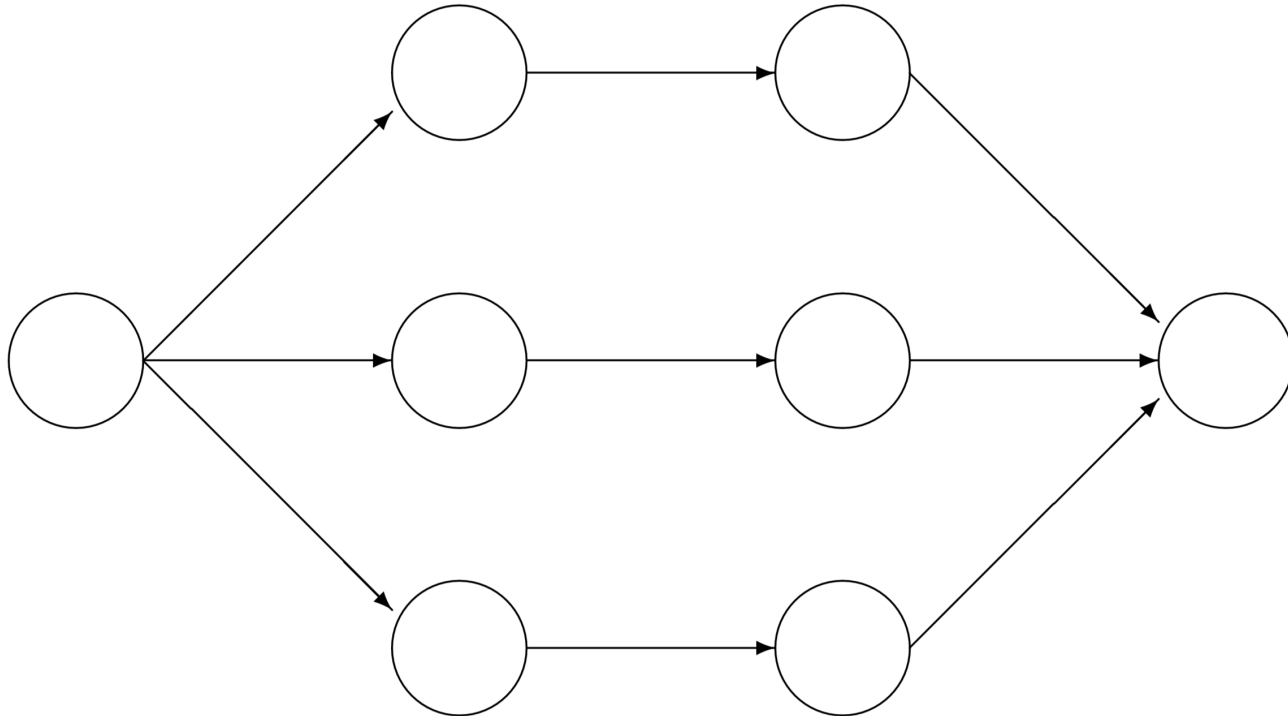
Stochastic Regression Imputation



Multiple imputation

- Missing values are replaced by chained regression, where m complete datasets are generated (Raghunathan, Lepkowski, Van Hoewyk, et al. (2001))
- Bootstrapping (subselection of the data, do the imputation, ...)
- accounts for uncertainty by creating multiple imputed version of data
- Generative models (draw samples from the estimated distribution)
- MICE (multivariate imputation by chained equations)

Multiple imputation



Incomplete data Imputed data Analysis results Pooled result

source: <https://stefvanbuuren.name/fimd/sec-nutshell.html>

Multiple imputation (vanBuuren (2018))

1. Specify an imputation model $P(Y_j^{\text{mis}} | Y_j^{\text{obs}}, Y_{-j}, R)$ for variable Y_j with $j = 1, \dots, p$.
2. For each j , fill in starting imputations \dot{Y}_j^0 by random draws from Y_j^{obs} .
3. Repeat for $t = 1, \dots, m$.
4. Repeat for $j = 1, \dots, p$.
5. Define $\dot{Y}_{-j}^t = (\dot{Y}_1^t, \dots, \dot{Y}_{j-1}^t, \dot{Y}_{j+1}^{t-1}, \dots, \dot{Y}_p^{t-1})$ as the currently complete data except Y_j .
6. Draw $\dot{\phi}_j^t \sim P(\phi_j^t | Y_j^{\text{obs}}, \dot{Y}_{-j}^t, R)$.
7. Draw imputations $\dot{Y}_j^t \sim P(Y_j^{\text{mis}} | Y_j^{\text{obs}}, \dot{Y}_{-j}^t, R, \dot{\phi}_j^t)$.
8. End repeat j .
9. End repeat t .

Multiple imputation

1. Create m complete versions of the data by replacing missing values by plausible ones with a random component (steps 1 to 3)

2. The m imputed datasets are

- identical for the observed data entries
- differ in the imputed values

The magnitude of these difference reflects uncertainty about what value to impute

3. Analyze each of the m complete datasets. Each set of parameter estimates differs slightly because of the random component

4. Pool the m parameter estimates into one estimate. Variance combines

- the conventional sampling variance (within-imputation variance)
- extra variance caused by the missing data (between-imputation variance).

Multiple imputation

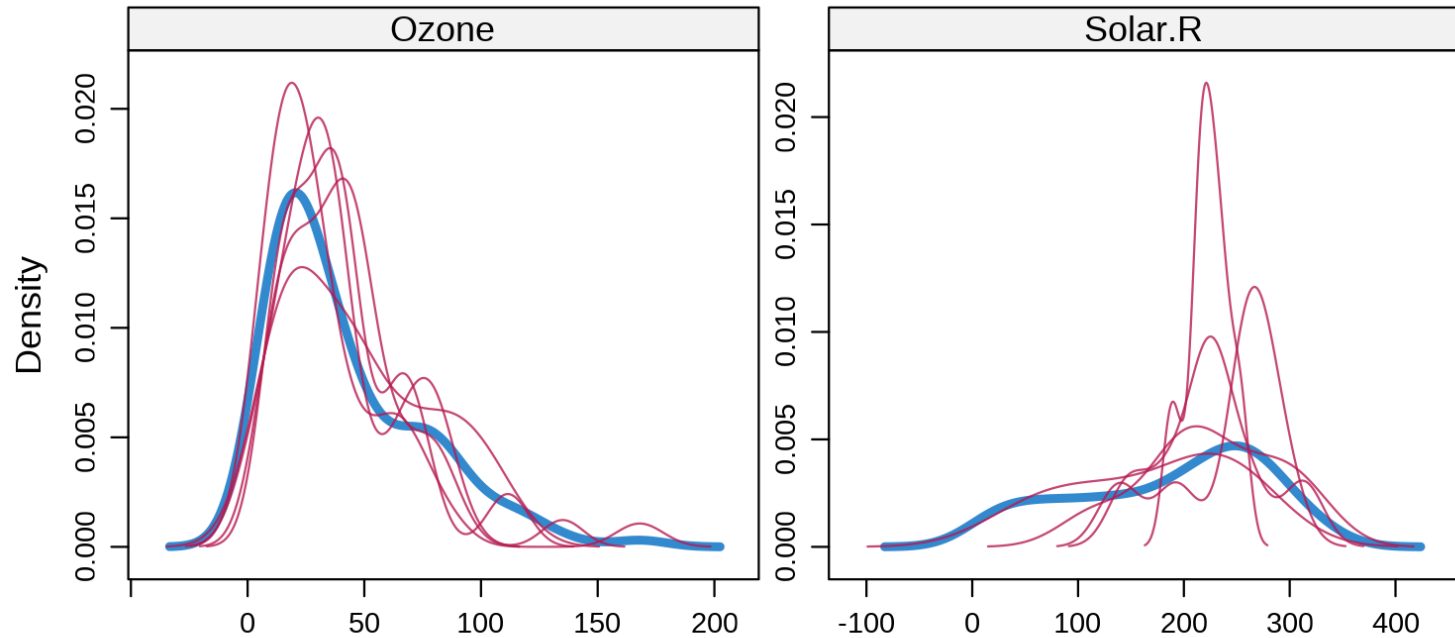
How large should m be (vanBuuren (2018))?

Classic advice: $m = 3, 5, 10$. More recently: set m higher: 20 to 100.

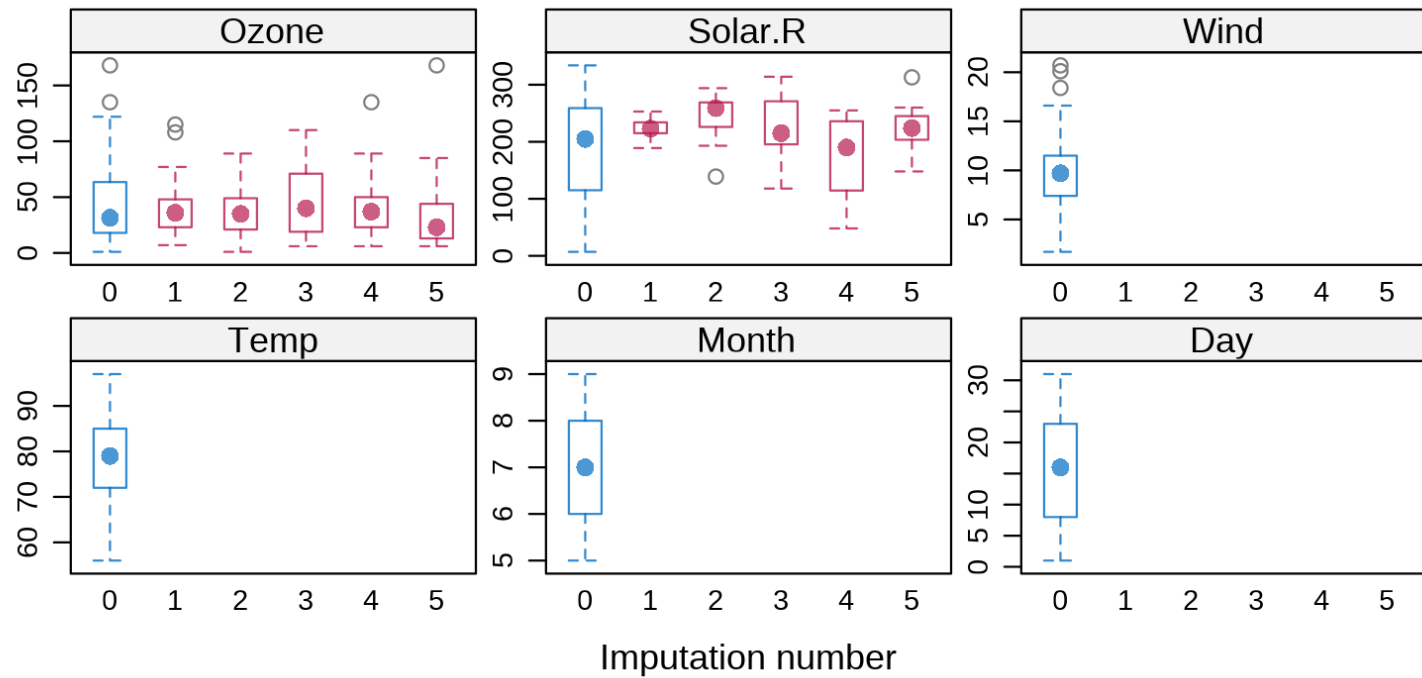
Some advice:

- Use $m = 5$ or $m = 10$ if the fraction of missing information is low
- Develop your model with $m = 5$. Do final run with m equal to percentage of incomplete cases

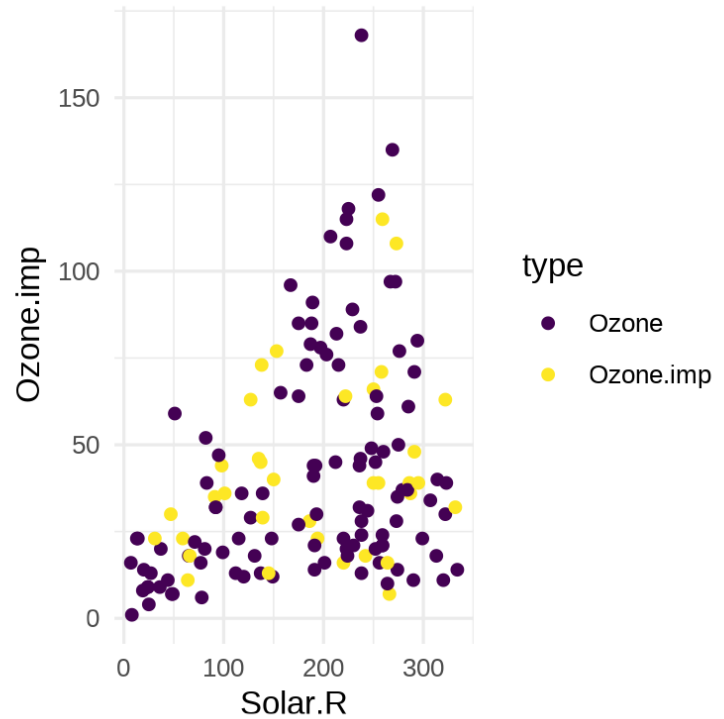
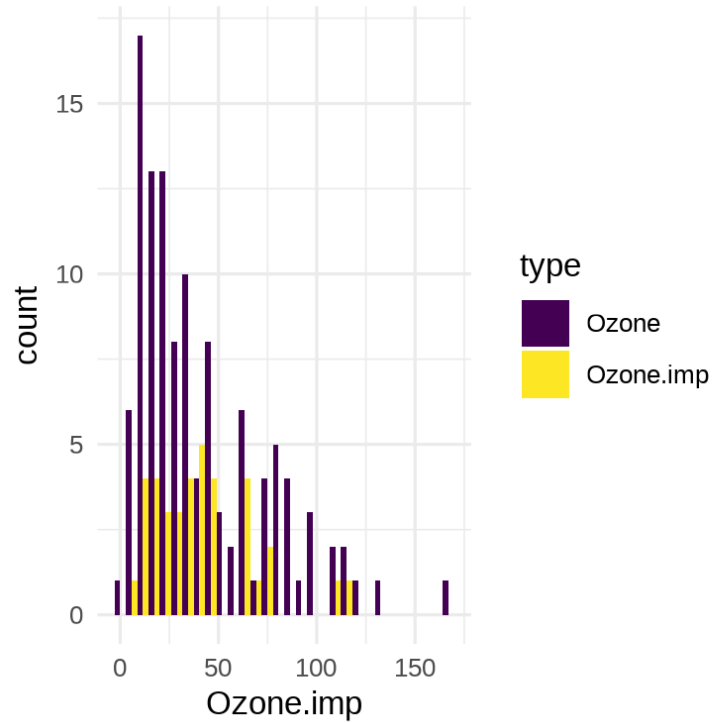
Multiple imputation



Multiple imputation



Multiple imputation



Multiple imputation in detail...

1. Start

Ozone	Solar.R	Wind	Temp	Month	Day
NA	194	8.6	69	5	10
7	NA	6.9	74	5	11
16	256	9.7	69	5	12

2. Mean Imputation

Ozone	Solar.R	Wind	Temp	Month	Day
11.5	194	8.6	69	5	10
7.0	225	6.9	74	5	11
16.0	256	9.7	69	5	12

Multiple imputation in detail...

3. Set Ozone to NA's / Regression on complete cases

Ozone	Solar.R	Wind	Temp	Month	Day
NA	194	8.6	69	5	10
7	225	6.9	74	5	11
16	256	9.7	69	5	12

4. Predict Ozone

Ozone	Solar.R	Wind	Temp	Month	Day
12.51	194	8.6	69	5	10
7.00	225	6.9	74	5	11
16.00	256	9.7	69	5	12

Multiple imputation in detail...

5. Set Solar.R to NA's / Regression on complete cases

Ozone	Solar.R	Wind	Temp	Month	Day
12.51	194	8.6	69	5	10
7.00	NA	6.9	74	5	11
16.00	256	9.7	69	5	12

6. Predict Solar.R

Ozone	Solar.R	Wind	Temp	Month	Day
12.51	194.00	8.6	69	5	10
7.00	201.41	6.9	74	5	11
16.00	256.00	9.7	69	5	12

Multiple imputation in detail...

7. Set Ozone to NA's / Regression on complete cases

Ozone	Solar.R	Wind	Temp	Month	Day
NA	194.00	8.6	69	5	10
7	201.41	6.9	74	5	11
16	256.00	9.7	69	5	12

Repeat until convergence

Software

R

Python

Takeaways

- understand the missing type and data before anything (tips: missing rate, balance, correlation, data size, ...)
- There is no single magical method to deal with missingness, the right choice depends on your data
- Benefit from multiple imputation to account for uncertainty
- Be vigilant in using open source packages
- Check literature for new methodologies

Thank you! Questions?

Slides: <https://github.com/wittmaan/missing-data>

Literature

Raghunathan, T. E., J. M. Lepkowski, J. Van Hoewyk, et al. (2001). "A Multivariate Technique for Multiply Imputing Missing Values Using a Sequence of Regression Models". In: *Survey Methodology* 27, pp. 85-96.

Schafer, J. L. and J. W. Graham (2002). "Missing Data: Our View of the State of the Art". In: *Psychol Methods* 7, pp. 147-177.

vanBuuren, S. (2018). *Flexible Imputation of Missing Data*. second. Accessed: 2021-05-02. CRC Press.

Links

- <https://www.deeplearning.ai/the-batch/issue-84/>
- <https://stefvanbuuren.name/publication/vanbuuren-2018/>
- http://pol346.com/2021/week10_02.html#1
- <https://htmlpreview.github.io/?https://raw.githubusercontent.com/ehsanx/spph504-007/master/Lab6/lab6part1.html>
- https://rstudio-pubs-static.s3.amazonaws.com/445649_5f323f9cc6aa4333b404882e67e9c344.html