

## WENJIE CHEN (陈文杰)

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<http://wjchen84.github.io/>

### 教育背景

- 博士**      美国加州大学伯克利分校      机械工程      08/2012  
毕业论文：非匹配动力学和非匹配感知下的机器人智能控制  
导师：Professor Masayoshi Tomizuka
- 硕士**      美国加州大学伯克利分校      机械工程      05/2009  
毕业论文：利用关节传感器信息融合的非直驱传动链的混合自适应摩擦补偿  
导师：Professor Masayoshi Tomizuka
- 学士**      浙江大学      机械电子工程      06/2007  
排名：1/55 (专业)      竺可桢学院工高班 (从6000多本科生中选拔63人)  
毕业论文：两轴直线驱动平台的协调运动控制  
导师：姚斌 教授, 王庆丰 教授

### 工作经历

- 美的集团中央研究院**      机器人与自动化研究所      所长      12/2019 – 现在
- 负责研究所的全面工作，组建和领导研究所的研发团队
  - 布局 and 探索机器人与自动化领域的核心技术、前沿技术和基础技术
- 浙江大学伊利诺伊大学厄巴纳香槟校区联合学院**      副教授（兼）      01/2019 – 现在
- 思核科技**      CTO      07/2018 – 11/2019
- 以工业AI和机器人为重点，领导和管理公司的研发团队和研发项目
  - 探索并确立技术战略以实现公司的商业目标
- 发那科株式会社**      基础研究所 机器人软件研究部      主任      10/2017 – 06/2018
- 下一代机器人软件研发的技术负责人：动作规划和控制，优化和学习，人机协作等
  - 作为技术负责人主导跟知名大学的前沿机器人研究合作
- 发那科株式会社**      机器人研究所 学习机器人开发部      主任      11/2013 – 09/2017
- 下一代机器人概念控制器研发的技术负责人：动作规划和控制，优化和学习，人机协作等
  - 作为技术负责人主导跟知名大学的前沿机器人研究合作
  - 负责“学习机器人”产品的算法研究和技术研发
- 美国加州大学伯克利分校**      机械系统控制实验室      博士后研究员      08/2012 – 10/2013
- 主导脑机交互研究中的外骨骼机器人的设计和控制
  - 主导机械臂的智能控制研究，包括控制、运动规划、传感器融合、系统建模和辨识等

## 荣誉和获奖 (节选)

- 浙江省“创新嘉兴-精英引领计划”领军人才 (A级) 2019
- 浙江省海宁市“潮乡精英引领计划”领军人才 2018
- 一等奖, “潮乡精英引领计划”智能制造创业大赛, 浙江海宁 2018
- 最佳应用论文提名奖, 第12届IEEE自动化科学与工程国际会议 (CASE) 2016
- 最佳学生论文提名奖, IEEE/ASME先进智能机电一体化国际会议(AIM) 2015
- 最佳学生论文提名奖, 第6届IFAC机电系统国际论坛(MECHATRONICS) 2013
- 最佳论文(学习控制分会), ASME动态系统与控制国际会议(DSCC) 2012
- 第三名, 美国Big Ideas @ Berkeley创新大赛, “The PikaPen”  
“社会信息科技”类别, 125个参赛团队中的5个优胜团队 04/2012
- Block Grant 奖, 美国加州大学伯克利分校 01/2011
- 蒋震海外留学生奖学金, 中国 2007 – 2008  
每年从中国的海外留学生中选拔10名
- 浙江省和浙江大学的各种本科生奖项 2002 – 2007  
具体请参照: <http://wjchen84.github.io/index.html#Honors>

## 专业领域职务

## 专业奖项评委:

IEEE/IFR IERA Award (机器人和自动化的创新创业大奖), 2017

## 研究计划评委:

香港政府研究资助局(RGC)-外部评委 (2013, 2014, 2016, 2017, 2020)

## 顾问&amp;学术委员会:

之江实验室青年人才委员会

美的集团中央研究院学术评审委员会

美的集团中央研究院学术委员会

## 期刊编辑委员会:

国际先进机器人系统杂志 (IJARS) 编委会委员

## 国际会议委员会:

程序委员会, 2016 ASME 柔性自动化国际论坛 (ISFA)

编委, 2016 美国控制会议 (ACC)

编委和分会组织者, 2015 ASME 动态系统与控制国际会议 (DSCC)

编委, 2015 美国控制会议 (ACC)

专题和分会组织者, 2014 ASME 动态系统与控制国际会议 (DSCC)

程序委员会, 2013 IEEE 信息与自动化国际会议 (ICIA)

程序委员会, 2013 IEEE 机器人与仿生学国际会议 (ROBIO)

分会主席, 2013 ASME 动态系统与控制国际会议 (DSCC)

**期刊评审人:**

IEEE Transactions on Robotics (T-RO)  
 IEEE Transactions on Industrial Electronics (TIE)  
 IEEE Transactions on Industrial Informatics (TII)  
 IEEE/ASME Transactions on Mechatronics (TMECH)  
 IEEE Transactions on Control Systems Technology (TCST)  
 IEEE Transactions on Automation Science and Engineering (T-ASE)  
 ASME Journal of Dynamic Systems, Measurement, and Control (JDSMC)  
 Robotics and Computer Integrated Manufacturing (Elsevier-RCIM)  
 Robotics and Autonomous Systems (RAS)  
 International Journal of Advanced Robotic Systems (IJARS)  
 International Journal of Intelligent Robotics and Applications (JIRA)  
 Advanced Robotics (RSJ-AR)  
 Asian Journal of Control (AJC)  
 Control and Cybernetics  
 Sensors (MDPI Journal)  
 Journal of Zhejiang University Science C (Computers & Electronics) (ZUSC)

**学术会议评审人:**

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)  
 IEEE International Conference on Robotics and Automation (ICRA)  
 IEEE Conference on Decision and Control (CDC)  
 American Control Conference (ACC)  
 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM)  
 ASME Dynamic Systems and Control Conference (DSCC)  
 ASME International Symposium on Flexible Automation (ISFA)  
 IFAC Symposium on Robot Control (SYROCO)  
 IEEE International Conference on Information and Automation (ICIA)  
 IEEE International Conference on Robotics and Biomimetics (ROBIO)

**专利**

**12项已授权 + 24项已国际公开 + 7项审批中, 涵盖 中国、日本、美国、德国**

1. 具备计算传感器的位置和方向的功能的机器人系统  
*JP6174654B2 (已授权), US9937620 (已授权),*  
*CN106584489B (已授权), DE102016012065B4 (已授权)*
2. 物体的姿势计算系统  
*JP6208724B2 (已授权), US9903698 (已授权),*  
*CN106514712B (已授权), DE102016116404A1 (已授权)*
3. 具备学习功能的机器人装置  
*JP6386516B2 (已授权), US10254741B2 (已授权),*  
*CN106965171A (国际公开), DE102017000063A1 (国际公开)*
4. 机器人控制装置  
*JP2018027580A (国际公开), US20180050452A1 (国际公开),*

- CN107756423A (国际公开), DE102017118276A1 (国际公开)
5. 具有学习控制功能的机器人系统以及学习控制方法  
JP6484265B2 (已授权), US20180229364A1 (国际公开),  
CN108422420A (国际公开), DE102018001026A1 (国际公开)
  6. 自动地生成机器人的动作轨迹的装置、系统以及方法  
JP2018176332A (国际公开), US20180290302A1 (国际公开),  
CN108687770A (国际公开), DE102018107857A1 (国际公开)
  7. 形状识别装置、形状识别方法以及计算机可读介质  
JP6499716B2 (已授权), US20180341828A1 (国际公开),  
CN108932363A (国际公开), DE102018206193A1 (国际公开)
  8. 手控制装置、手控制方法和手的模拟装置  
JP2019010713A (国际公开), US20190001508A1 (国际公开),  
CN109202942A (国际公开), DE102018115451A1 (国际公开)
  9. 机器人系统  
JP2019038089A (国际公开), US20190061149A1 (国际公开),  
CN109421049A (国际公开), DE102018214272A1 (国际公开)
  10. 控制装置和机器学习装置  
JP2018079450 (审批中)
  11. 机械手爪控制装置和手爪控制系统  
JP2018075572 (审批中)
  12. 机器人控制装置和机器人控制方法  
JP2018079505 (审批中)
  13. 机器人动作教示装置、机器人系统和机器人控制装置  
JP2018079583 (审批中)
  14. 鲁棒控制调整系统、方法及程序  
JP2018122023 (审批中)
  15. 鲁棒调整装置及模型生成方法  
JP2018120417 (审批中)
  16. 根据动作指令进行的参数适应  
JP2018134393 (审批中)

## 论文

### 杂志论文

8. Zheng Chen, Fanghao Huang, **Wenjie Chen**, Junhui Zhang, Weichao Sun, Jiawang Chen, Jason Gu, Shiqiang Zhu, "RBFNN-based Adaptive Sliding Mode Control Design for Delayed Nonlinear Multilateral Tele-robotic System With Cooperative Manipulation," *IEEE Transactions on Industrial Informatics*, July 10, 2019, doi: 10.1109/TII.2019.2927806
7. Junkai Lu, Kevin Haninger, **Wenjie Chen**, Masayoshi Tomizuka, Suraj Gowda, and Jose M. Carmena, "Design of a Passive Upper Limb Exoskeleton for Macaque Monkeys,"

- ASME Journal of Dynamic Systems, Measurement, and Control*, 138(11), 111011 (Jul 27, 2016); doi: 10.1115/1.4033837
6. Pedro Reynoso-Mora, **Wenjie Chen**, and Masayoshi Tomizuka, "A Convex Relaxation for the Time-optimal Trajectory Planning of Robotic Manipulators along Predetermined Geometric Paths," *Optimal Control Applications and Methods*, vol. 37, no. 6, pp. 1263–1281, Nov./Dec. 2016; doi: 10.1002/oca.2234
  5. **Wenjie Chen**, Kyoungchul Kong, and Masayoshi Tomizuka, "Dual-Stage Adaptive Friction Compensation for Precise Load Side Position Tracking of Indirect Drive Mechanisms," *Control Systems Technology, IEEE Transactions on*, vol. 23, no. 1, pp. 164–175, Jan. 2015; doi: 10.1109/TCST.2014.2317776
  4. **Wenjie Chen**, and Masayoshi Tomizuka, "Dual-Stage Iterative Learning Control for MIMO Mismatched System with Application to Robots with Joint Elasticity," *Control Systems Technology, IEEE Transactions on*, vol. 22, no. 4, pp. 1350–1361, July 2014; doi: 10.1109/TCST.2013.2279652
  3. **Wenjie Chen**, and Masayoshi Tomizuka, "Direct Joint Space State Estimation in Robots with Multiple Elastic Joints," *Mechatronics, IEEE/ASME Transactions on*, vol. 19, no. 2, pp. 697–706, April 2014; doi: 10.1109/TMECH.2013.2255308
  2. **Wenjie Chen**, and Masayoshi Tomizuka, "Comparative Study on State Estimation in Elastic Joints," *Asian Journal of Control*, vol. 16, no. 3, pp. 818–829, May 2014; doi: 10.1002/asjc.755
  1. Jonathan Asensio, **Wenjie Chen**, and Masayoshi Tomizuka, "Feedforward Input Generation Based on Neural Network Prediction in Multi-Joint Robots," *Journal of Dynamic Systems, Measurement, and Control*, 136(3), 031002, May 2014; doi:10.1115/1.4025986

#### 会议论文(同行评审)

26. Yongxiang Fan, Wei Gao, **Wenjie Chen**, and Masayoshi Tomizuka, "Real-Time Finger Gaits Planning for Dexterous Manipulation," in *Proceedings of the 20th World Congress of the International Federation of Automatic Control (IFAC)*, Toulouse, France, July 9–14, 2017
25. Chung-Yen Lin, **Wenjie Chen**, and Masayoshi Tomizuka, "Learning Control for Task Specific Industrial Robots," in *Proceedings of the 55th IEEE Conference on Decision and Control (CDC)*, Las Vegas, USA, December 12–14, 2016
24. Te Tang, Changliu Liu, **Wenjie Chen**, and Masayoshi Tomizuka, "Robotic Manipulation of Deformable Objects by Tangent Space Mapping and Non-Rigid Registration," in *Proceedings of the 2016 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Deajeon, Korea, pp. 2689–2696, October 9–14, 2016
23. Yu Zhao, **Wenjie Chen**, Te Tang, and Masayoshi Tomizuka, "Zero Time Delay Input Shaping for Smooth Settling of Industrial Robots," in *Proceedings of the 12th IEEE International Conference on Automation Science and Engineering (CASE)*, Fort Worth, TX, USA, August 21–24, 2016

22. Te Tang, Hsien-Chung Lin, Yu Zhao, **Wenjie Chen**, and Masayoshi Tomizuka, "Autonomous Alignment of Peg and Hole by Force/Torque Measurement for Robotic Assembly," in *Proceedings of the 12th IEEE International Conference on Automation Science and Engineering (CASE)*, Fort Worth, TX, USA, August 21–24, 2016 (**Best Application Paper Finalist**)
21. Te Tang, Hsien-Chung Lin, Yu Zhao, Yongxiang Fan, **Wenjie Chen**, and Masayoshi Tomizuka, "Teach Industrial Robots Peg-Hole-Insertion by Human Demonstration," in *Proceedings of the 2016 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM)*, Banff, Alberta, Canada, July 12–15, 2016
20. Yongxiang Fan, Hsien-Chung Lin, Yu Zhao, Chung-Yen Lin, Te Tang, Masayoshi Tomizuka, and **Wenjie Chen**, "Object Position and Orientation Tracking for Manipulators Considering Unnegligible Sensor Physics," in *Proceedings of the 2016 ASME International Symposium on Flexible Automation (ISFA)*, Cleveland, USA, August 1–3, 2016
19. Chung-Yen Lin, Yu Zhao, Masayoshi Tomizuka, and **Wenjie Chen**, "Path-Constrained Trajectory Planning for Robot Service Life Optimization," in *Proceedings of the 2016 American Control Conference (ACC)*, Boston, MA, USA, July 6–8, 2016
18. Hsien-Chung Lin, Te Tang, Yongxiang Fan, Yu Zhao, Masayoshi Tomizuka, and **Wenjie Chen**, "Robot Learning from Human Demonstration with Remote Lead through Teaching," in *Proceedings of the 2016 European Control Conference (ECC)*, Aalborg, Denmark, June 29–July 1, 2016
17. Hsien-Chung Lin, Te Tang, Masayoshi Tomizuka, and **Wenjie Chen**, "Remote Lead Through Teaching by Human Demonstration Device," in *Proceedings of the 8th ASME Dynamic Systems and Control Conference (DSCC)*, Columbus, Ohio, USA, October 28–30, 2015
16. Junkai Lu, Kevin Haninger, **Wenjie Chen**, and Masayoshi Tomizuka, "Design and Torque-Mode Control of a Cable-Driven Rotary Series Elastic Actuator for Subject-Robot Interaction," in *Proceedings of the IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM)*, Busan, Korea, pp. 158–164, July 7–11, 2015 (**Best Student Paper Finalist**)
15. Junkai Lu, **Wenjie Chen**, Kevin Haninger, and Masayoshi Tomizuka, "A Passive Upper Limb Exoskeleton for Macaques in a BMI Study – Kinematic Design, Analysis, and Calibration," in *Proceedings of the 7th ASME Dynamic Systems and Control Conference (DSCC)*, San Antonio, Texas, USA, October 22–24, 2014
14. Kevin Haninger, Junkai Lu, **Wenjie Chen**, and Masayoshi Tomizuka, "Kinematic Design and Analysis for a Macaque Upper-Limb Exoskeleton with Shoulder Joint Alignment," in *Proceedings of the 2014 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Chicago, Illinois, USA, pp. 478–483, September 14–18, 2014
13. Yizhou Wang, **Wenjie Chen**, Masayoshi Tomizuka, and Badr N. Alsuwaidan, "Model Predictive Sliding Mode Control – for Constraint Satisfaction and Robustness," in *Proceedings of the 6th ASME Dynamic Systems and Control Conference (DSCC)*, Palo Alto, CA, October 21–23, 2013

12. Chung-Yen Lin, **Wenjie Chen**, and Masayoshi Tomizuka, "Automatic Sensor Frame Identification in Industrial Robots with Joint Elasticity," in *Proceedings of the 6th ASME Dynamic Systems and Control Conference (DSCC)*, Palo Alto, CA, October 21–23, 2013
11. Pedro Reynoso-Mora, **Wenjie Chen**, and Masayoshi Tomizuka, "On the Time-optimal Trajectory Planning and Control of Robotic Manipulators Along Predefined Paths," in *Proceedings of the 2013 American Control Conference (ACC)*, Washington, DC, pp. 371–377, June 17–19, 2013
10. Chi-Shen Tsai, **Wenjie Chen**, Daekyu Yun, and Masayoshi Tomizuka, "Iterative Learning Control for Vibration Reduction in Industrial Robots with Link Flexibility," in *Proceedings of the 2013 American Control Conference (ACC)*, Washington, DC, June 17–19, 2013
9. Junkai Lu, **Wenjie Chen**, and Masayoshi Tomizuka, "Kinematic Design and Analysis of a 6-DOF Upper Limb Exoskeleton Model for a Brain-Machine Interface Study," in *Proceedings of the 6th IFAC Symposium on Mechatronic Systems (Mechatronics '13)*, Hangzhou, China, pp. 293–300, April 10–12, 2013 (**Best Student Paper Finalist**)
8. Yizhou Wang, **Wenjie Chen**, and Masayoshi Tomizuka, "Extended Kalman Filtering for Robot Joint Angle Estimation Using MEMS Inertial Sensors," in *Proceedings of the 6th IFAC Symposium on Mechatronic Systems (Mechatronics '13)*, Hangzhou, China, pp. 406–413, April 10–12, 2013
7. **Wenjie Chen**, and Masayoshi Tomizuka, "Iterative Learning Control with Sensor Fusion for Robots with Mismatched Dynamics and Mismatched Sensing," in *Proceedings of the 2012 ASME Dynamic Systems and Control Conference (DSCC)*, Fort Lauderdale, Florida, USA, pp. 1480–1488, October 17–19, 2012 (**Best Paper in Session Award**)
6. Jonathan Asensio, **Wenjie Chen**, and Masayoshi Tomizuka, "Robot Learning Control Based on Neural Network Prediction," in *Proceedings of the 2012 ASME Dynamic Systems and Control Conference (DSCC)*, Fort Lauderdale, Florida, USA, pp. 1489–1497, October 17–19, 2012
5. **Wenjie Chen**, and Masayoshi Tomizuka, "Load Side State Estimation in Robot with Joint Elasticity," in *Proceedings of the 2012 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM)*, Kaohsiung, Taiwan, pp. 598–603, July 11–14, 2012
4. **Wenjie Chen**, and Masayoshi Tomizuka, "A Two-Stage Model Based Iterative Learning Control Scheme for a Class of MIMO Mismatched Linear Systems," in *Proceedings of the 2012 ASME International Symposium on Flexible Automation (ISFA)*, St. Louis, Missouri, USA, paper No. ISFA2012–7199, June 18–20, 2012
3. Cong Wang, **Wenjie Chen**, and Masayoshi Tomizuka, "Robot End-effector Sensing with Position Sensitive Detector and Inertial Sensors," in *Proceedings of the 2012 IEEE International Conference on Robotics and Automation (ICRA)*, Saint Paul, Minnesota, USA, pp. 5252–5257, May 14–18, 2012
2. **Wenjie Chen**, and Masayoshi Tomizuka, "Estimation of Load Side Position in Indirect Drive Robots by Sensor Fusion and Kalman Filtering," in *Proceedings of the 2010 Ameri-*

can Control Conference (ACC), Baltimore, Maryland, USA, pp. 6852–6857, June 30–July 2, 2010

1. **Wenjie Chen**, Kyoungchul Kong, and Masayoshi Tomizuka, "Hybrid Adaptive Friction Compensation of Indirect Drive Trains," in *Proceedings of the 2009 ASME Dynamic Systems and Control Conference (DSCC)*, Hollywood, California, USA, pp. 313–320, October 12–14, 2009

## 学术报告

以上会议论文演讲之外

- 01/04/2020 "智能机器人：机器人学习及其工业应用", 浙江大学工程师学院
- 12/22/2018 "智能机器人技术及其产业应用", 浙江大学工程师学院
- 05/29/2017 "Robotic Learning in Industrial Applications", in *Workshop "Recent Advances in Dynamics for Industrial Applications"*, the 2017 IEEE International Conference on Robotics and Automation (ICRA), Singapore
- 08/14/2014 "Mechatronic Considerations for Mismatched Robotic Systems", Google Robotics
- 04/10/2013 "EFRI-M3C: A hybrid control systems approach to brain-machine interfaces for exoskeleton control (Overview)", Qiushi Academy for Advanced Studies, Zhejiang University, China
- 03/11/2013 "Mechatronic Considerations for Mismatched Robotic Systems", Department of Mechanical Engineering, Carnegie Mellon University
- 03/04/2013 "Mechatronic Considerations for Mismatched Robotic Systems", Department of Mechanical Engineering, Worcester Polytechnic Institute
- 02/26/2013 "Mechatronic Considerations for Mismatched Robotic Systems", Department of Mechanical Engineering and Engineering Science, University of North Carolina at Charlotte
- 08/09/2012 "Intelligent Control of Robots with Mismatched Dynamics and Mismatched Sensing", *Ph.D. seminar*, University of California, Berkeley
- 03/08/2012 "EFRI-M3C: A hybrid control systems approach to brain-machine interfaces for exoskeleton control (NSF EFRI-M3C 1137267)", *Poster presentation (group work)*, *NSF EFRI Grantees Conference*, Arlington, VA, Mar. 07–09, 2012
- 02/28/2012 "Estimation in Robots with Mismatched Sensing", *The 1st International Workshop between University of California Berkeley and Keio University*, Berkeley, CA
- 04/26/2011 "Disturbance Cancellation Schemes for Indirect Drive Robot Manipulator", FANUC Corporation, Japan

Updated on March 8, 2020

<http://wjchen84.github.io/>