$$201[-2, 4u] \ge \frac{1}{1} + \frac{1}{2} = \frac{1}{3} \ge \frac{1}{2}$$
(1) Find the inverse 2-transform DL

$$X(2) = \frac{1 - \frac{1}{3} \ge 1}{1 - 21 \cdot (1 + 22^{\frac{1}{3}})^2}$$

$$X' \text{ order of } \text{ Numerator } \text{ M} \qquad \text{NPM } (6 = 0)$$
order of Denoininator N \qquad \text{NPM } \quad \text{(6 = X(2)]} \frac{2^{2} \text{Pr}}{2^{2}} \Big|_{2^{2}} \text{Pr} \quad \frac{x^{2}}{2^{2}} \Big|_{2^{2}} \Big|_{2^{2}} \text{Pr} \quad \frac{x^{2}}{2^{2}} \Big|_{2^{2}} \Big|_{2^{2}} \\
\text{Antino } \frac{x^{2}}{2^{2}} \Big|_{2^{2}} \Big|_{2^{2}}

$$= \frac{2}{2n} \cdot \frac{z}{z+1} + \frac{25}{2n} \cdot \frac{z}{z+2} - \frac{14}{9} \cdot \frac{z}{(z+2)^2}$$

$$\frac{2}{5} \cdot \frac{z}{z+1} + \frac{25}{2n} \cdot \frac{z}{z+2} - \frac{14}{9} \cdot \frac{z}{(z+2)^2}$$

$$\frac{2}{5} \cdot \frac{12}{2} \cdot \frac{1}{2} \cdot \frac{1}$$

$$X[n] = \frac{2}{2\eta} (1)^{\eta} u(n) + \frac{2\zeta}{2\eta} (-2)^{\eta} u(n) + \frac{\eta}{4} \eta (-2)^{\eta} u(n)$$

$$= \left(\frac{2}{2\eta} + \frac{2\zeta}{2\eta} (-2)^{\eta} + \frac{\eta}{4} \eta (-2)^{\eta} \right) u(n) - \eta \eta \zeta t \eta d \ell \ell$$

[2] Determine the 2-thanstorm of the following sequence, she too the pole Zero plot and indicate the region of convergence. Indicate whether or not the pour er transform of the seavence exists

Using definition of z transform

Let n=-k

$$\sum_{k=0}^{\infty} z^{-k} z^{k} + \sum_{n=1}^{\infty} (\frac{1}{4}z^{1})^{n} = \sum_{k=0}^{\infty} (\frac{1}{2}z)^{k} + \sum_{n=1}^{\infty} (\frac{1}{4}z^{-1})^{n} = \frac{1}{1-\frac{1}{2}z} + \frac{\frac{1}{4}z^{-1}}{1-\frac{1}{4}z^{1}}$$

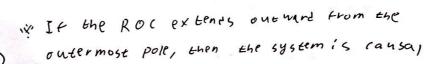
$$ROC$$
 $|\frac{1}{2}|(1) = |\frac{1}{2}|(2)$ $|\frac{1}{4}|(1) = |\frac{1}{4}|(2)$ $|\frac{1}{4}|(1) = |\frac{1}{4}|(1)$

$$\times (2) = \frac{1}{1 - \frac{1}{2}z} + \frac{\frac{1}{4}z^{-1}}{1 - \frac{1}{4}z^{-1}} = \frac{-\frac{2}{4}z}{z^{2} - \frac{9}{4}zt^{\frac{1}{2}}} = \frac{-\frac{2}{4}z}{(z^{-2})(z^{-\frac{1}{4}})}$$

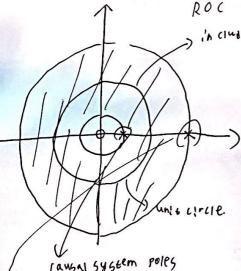
ROC 4<121<2.

-) in clude unle circle -) stabil.

fourier transform of the spanence is existed



x! If the ROC includes the unit circle, then the system is stable



ransal system poles un causal system poles

X when systemis stable and causal inside unitione - stable all of the poles are in side the unit circle un causal system poles is when system is stable and uncausal outside unle circle all of the poles are outside the unle circle [3] The input X(n) and output y(n) of a causal LTI system are related through the black-diagram representation as shown in the following figure

$$y(n) \rightarrow (1) \rightarrow (1)$$

$$W[n] = \chi[n] - \frac{1}{3}w[n-1] + \frac{2}{4}w[n-2] = \chi(z) = w(z)(1 + \frac{1}{3}z^{2} - \frac{2}{4}z^{-2})$$

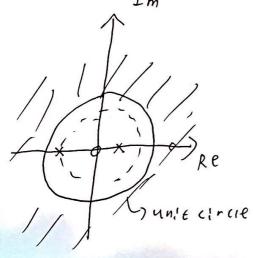
$$Y[n] = w[n] - \frac{1}{8}w[n-1] = \chi(z) = w(z)(1 - \frac{9}{8}z^{-1})$$

$$H(z) = \frac{\chi(z)}{\chi(z)} = \frac{1 - \frac{9}{8}z^{-1}}{1 + \frac{1}{3}z^{2} - \frac{2}{9}z^{-2}} = \frac{z(z - \frac{9}{8})}{(z - \frac{1}{3})(z + \frac{2}{9})}$$

$$Ro(1z) = \frac{1}{2}$$

$$y(n) + \frac{1}{3}y(n-1) - \frac{2}{9}y(n-2) = x(n) - \frac{9}{8}x(n-1)$$

It system is stable and lausal all of the poles are inside the unit circle. Im



=) system ! 5 stable.