

1. (a) oversampling 이 무엇?

1. higher sampling rate eliminates aliasing
2. increase resolution
3. leads to the use of simple anti-aliasing filters
4. improved SNR (signal noise ratio) (reduces noise)  
↳ aliasing component
5. To achieve easily the requirements of variable cut off frequency

\* down sampling 이 무엇?

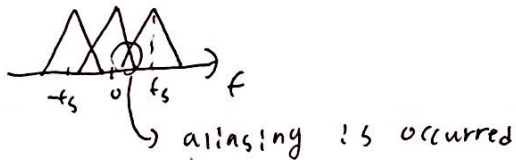
1. reducing data size
2. compression or image reduction)  
but have a possibility to break up Nyquist rule  
→ should pass pre lowpass filter first

(b) Aliasing 무엇?

If frequency break up the Nyquist rule ( $f_s \geq 2f_m$ )

( $f_s$ : sampling frequency,  $f_m$ : maximum frequency)

the we ~~define~~ ~~define~~ Aliasing is occurred  
define



(c) fast convolution  $H_0 H_1$ ?

$$x_1[n] * x_2[n] = F^{-1}(X_1(k) \cdot X_2(k))$$

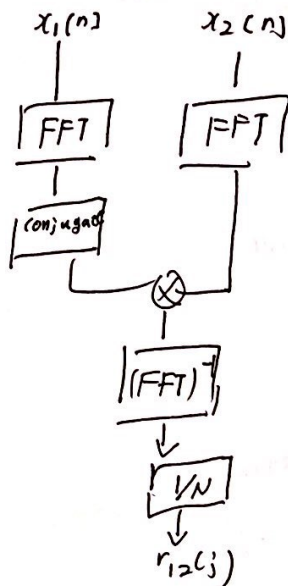
using Fast Fourier Transform

The convolution of two signal is obtained by taking a fast Fourier Transform, ~~and~~ multiplying each signal, and performing inverse transformation

## \* Fast correlation

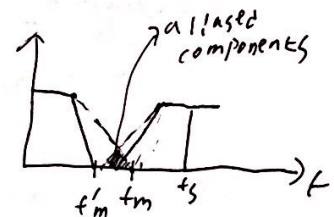
$$r_{12}(j) = \frac{1}{N} \text{IFFT} [X_1^*(k) X_2(k)]$$

The correlation of two signals is obtained by taking a fast Fourier transform, conjugate  $X_1(k)$  multiplying  $X_2(k)$  and performing inverse transformation, ~~then~~ normalized by  $N$   
 Finally  $\wedge$  take



## (d) Aliasing 방지 방법?

1. increase sampling frequency
2. use anti aliasing filter ex pre filter.  
eliminates aliased portion of spectrum



2. (a) DWT [1, 1, 0, 0, 1, 0, -2, 1]

Definition of DWT

$$X^{WH}(k) = \frac{1}{N} x_N^H \quad (\because N \text{ is length of data sequence})$$

(N is even  $N=2m$ )

$$2_H = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \quad 4_H = \begin{bmatrix} 2_H & 2_H \\ 2_H & -2_H \end{bmatrix} \quad 8_H = \begin{bmatrix} 4_H & 4_H \\ 4_H & -4_H \end{bmatrix}$$

$$8_H = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 & 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 & 1 & -1 & -1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 & 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & 1 & 1 & -1 & -1 & 1 \\ 1 & -1 & -1 & 1 & 1 & -1 & -1 & 1 \end{bmatrix}$$

	1	1	0	0	-1	0	-2	1	sum
$X^{WH}(0)$	1	1	0	0	-1	0	-2	1	0
$X^{WH}(1)$	1	-1	0	0	-1	0	-2	-1	-4
$X^{WH}(2)$	1	1	0	0	-1	0	2	-1	2
$X^{WH}(3)$	1	-1	0	0	-1	0	2	1	2
$X^{WH}(4)$	1	1	0	0	-1	0	-2	1	0
$X^{WH}(5)$	1	-1	0	0	-1	0	-2	-1	-4
$X^{WH}(6)$	1	1	0	0	-1	0	2	-1	2
$X^{WH}(7)$	1	-1	0	0	-1	0	2	1	2

$$X^{WH}(k) = \left\{ 0, -\frac{1}{2}, \frac{1}{4}, \frac{1}{4}, 0, -\frac{1}{2}, \frac{1}{4}, \frac{1}{4} \right\}$$

(b) z-transform of  $x[n]$

$x[n] = \left(\frac{1}{2}\right)^{|n|}$  1) using definition

$$\begin{aligned} X(z) &= \sum_{n=-\infty}^{\infty} x[n] z^{-n} = \sum_{n=-\infty}^{-1} \left(\frac{1}{2}\right)^{-n} z^{-n} + \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^n z^{-n} = \sum_{k=1}^{\infty} \left(\frac{1}{2}\right)^k z^k + \sum_{n=0}^{\infty} \left(\frac{1}{2} z^{-1}\right)^n \\ &= \sum_{k=1}^{\infty} \left(\frac{1}{2} z\right)^k + \sum_{n=0}^{\infty} \left(\frac{1}{2} z^{-1}\right)^n = \frac{\frac{1}{2} z}{1 - \frac{1}{2} z} + \frac{1}{1 - \frac{1}{2} z^{-1}} = \frac{z}{z - \frac{1}{2}} - \frac{z}{z - 2} \end{aligned}$$

$$\text{ROC } \left\{ \begin{array}{l} \left|\frac{1}{2} z\right| < 1 \Rightarrow |z| < 2 \\ \left|\frac{1}{2} z^{-1}\right| < 1 \Rightarrow |z| > \frac{1}{2} \end{array} \right\} \Rightarrow \frac{1}{2} < |z| < 2$$

$$\therefore X(z) = \frac{z}{z - \frac{1}{2}} - \frac{z}{z - 2} \quad \text{ROC } \frac{1}{2} < |z| < 2$$



1:) using pairs

$$x(n) = \left(\frac{1}{2}\right)^{|n|} = \left(\frac{1}{2}\right)^n u[n] + \left(\frac{1}{2}\right)^{-n} u[-n-1] = \underbrace{\left(\frac{1}{2}\right)^n u[n]}_{\text{ROC } |z| > \frac{1}{2}} + \underbrace{\left(\frac{1}{2}\right)^{-n} u[-n-1]}_{\text{ROC } |z| < 2}$$

$$X(z) = \frac{z}{z - \frac{1}{2}} - \frac{z}{z - 2} \quad \text{ROC } \frac{1}{2} < |z| < 2$$

3.  $B = 12$  (a) SQNR?  
 $f_s = 100 \text{ KHz}$  (b) ADR?  
 $BW = 20 \text{ KHz}$

step size  $q = \frac{V_{PP}}{2^B - 1} \approx \frac{V_{PP}}{2^B}$

Averaged quantization noise power  $N_q = \frac{q^2}{12}$

RMS quantization noise power  $N_{q-rms} = \frac{0.5 V_{PP}}{\sqrt{3 \times 2^B}} = \sqrt{\frac{q^2}{12}} \quad q = \frac{V_{PP}}{2^B}$

SQNR =  $10 \log \frac{\text{signal power}}{\text{quantization noise power}}$   
 (signal to quantization noise ratio)  $= 10 \log \frac{3}{2} \cdot 2^{2B} = 6.02B + 1.76 \text{ [dB]}$  (dynamic range)  
 The ratio of the maximum and minimum signal levels

Quantization noise power per unit bandwidth  $N_{qW} = \frac{q^2/12}{f_s/2}$   
 ADR =  $10 \log \frac{\text{signal power}}{N_{qW} \cdot BW} = 10 \log \frac{P_s}{N_{qW}} - 10 \log BW$  that the ADC can handle  
 (Actual dynamic range)

$$= 10 \log \left( \frac{3}{4} f_s 2^{2B} \right) - 10 \log BW = \underbrace{6.02B}_{10 \log 2^{2B}} + \underbrace{10 \log f_s - 1.249}_{10 \log \frac{3}{4}} - 10 \log BW \text{ [dB]}$$

(a) SQNR =  $6.02B + 1.76 \text{ [dB]}$   
 $= 10 \log \frac{3}{2} \cdot 2^{2B} = 114.008 \text{ [dB]}$

(b) ADR =  $6.02B + 10 \log f_s - 1.249 - 10 \log BW \text{ [dB]}$   
 $= 10 \log \left( \frac{3}{4} f_s 2^{2B} \right) - 10 \log BW = 111.9875 \text{ [dB]}$

$$4. \quad x(z) = \frac{1 - \frac{1}{3}z^{-1}}{(1-z^{-1})(1+2z^{-1})} \quad |z| > 2?$$

\* order of Numerator  $M$   $N > M$   $c_0 = 0$   
 order of Denominator  $N$   $N = M$   $c_0 = x(z)|_{z=0}$

multiple order

$$C_k = x(z) \frac{z^{-p_k}}{z} \Big|_{z=p_k} \quad \sum_{i=1}^m \frac{D_i z}{(z-p_k)^i} = \frac{D_1 z}{z-p_k} + \frac{D_2 z}{(z-p_k)^2} + \dots + \frac{D_m z}{(z-p_k)^m}$$

$$D_i = \frac{1}{(m-i)!} \frac{d^{m-i}}{dz^{m-i}} \left[ \frac{(z-p_k)^m}{z} x(z) \right] \Big|_{z=p_k}$$

pair  $a^n u[n] \longleftrightarrow \frac{z}{z-a} \quad |z| > |a|$   $1/a^n u[-n-1] \longleftrightarrow \frac{a z}{(z-a)^2} \quad |z| > |a|$   
 $-a^n u[-n-1] \longleftrightarrow \frac{z}{z-a} \quad |z| < |a|$   $-n a^n u[-n-1] \longleftrightarrow \frac{a z}{(z-a)^2} \quad |z| < |a|$

$$x(z) = \frac{z(z-\frac{1}{3})}{(z-1)(z+2)}$$

$$c_0 = x(z)|_{z=0} = 0$$

$$C_1 = \frac{z(z-\frac{1}{3})}{(z-1)(z+2)} \cdot \frac{z-1}{z} \Big|_{z=1} = \frac{z-\frac{1}{3}}{z+2} \Big|_{z=1} = \frac{\frac{2}{3}}{3} = \frac{2}{9}$$

$$C_2 = \frac{z(z-\frac{1}{3})}{(z-1)(z+2)} \cdot \frac{z+2}{z} \Big|_{z=-2} = \frac{z-\frac{1}{3}}{z-1} \Big|_{z=-2} = \frac{-\frac{5}{3}}{-3} = \frac{5}{9}$$

$$x(z) = \frac{2}{9} \cdot \frac{z}{z-1} + \frac{5}{9} \cdot \frac{z}{z+2}$$

i) ROC  $|z| > 2 \rightarrow$  unstable

$$x[n] = \frac{2}{9} (1)^n u[n] + \frac{5}{9} (-2)^n u[n] = \left( \frac{2}{9} + \frac{5}{9} (-2)^n \right) u[n]$$

ii) ROC  $1 < |z| < 2 \rightarrow$  unstable  
 causal non causal

$$x[n] = \frac{2}{9} (1)^n u[n] - \frac{5}{9} (-2)^n u[-n-1]$$

iii) ROC  $|z| < 1 \rightarrow$  unstable.

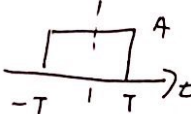
$$x[n] = -\frac{2}{9} (1)^n u[-n-1] - \frac{5}{9} (-2)^n u[-n-1]$$

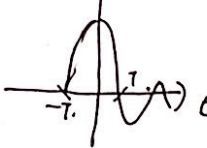
$$= \left( -\frac{2}{9} - \frac{5}{9} (-2)^n \right) u[-n-1]$$

5. CTFT 7 하시오, 밑 밑한 점 8  $x(t)$  도식 하 하시오

(a)  $4 \text{sinc}(\frac{t}{20})$

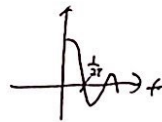
$\times$   $e^{j2\pi f_0 t} = e^{j\omega_0 t} \longleftrightarrow \delta(f-f_0) \cdot 2\pi\delta(\omega-\omega_0)$

$\times$    $\triangleq A \text{rect}(\frac{t}{2T}) = A \Pi(\frac{t}{2T})$   
duration  $2T = \tau$   $A \text{rect}(\frac{t}{\tau})$

  $\triangleq A \text{sinc}(\frac{t}{T})$

$A \text{rect}(\frac{t}{2T}) = A \text{rect}(\frac{t}{\tau}) \rightarrow 2T \cdot A \text{sinc}(f \cdot 2T) = 2T \cdot A \text{sinc}(\frac{\omega \cdot 2T}{2\pi})$

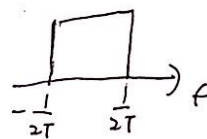
scale  $\frac{1}{2T}$  의역함  
→  $\frac{1}{2T}$ , scale 0  
→  $\frac{1}{2T}$ , scale 0



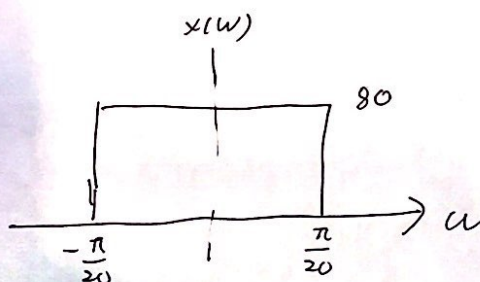
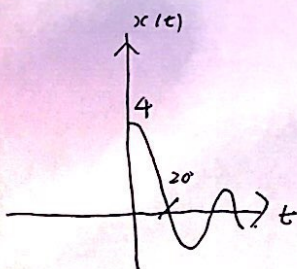
$\rightarrow 2A \text{sinc}(f \cdot 2T) = 2A \text{sinc}(\frac{\omega \cdot 2T}{2\pi})$

$A \text{sinc}(\frac{t}{2T}) \xrightarrow{=2Tf} A \cdot \frac{1}{2T} \text{rect}(t \cdot \frac{1}{2T}) = \frac{A}{2T} \text{rect}(\frac{t}{2T})$   
scale  $\frac{1}{2T} = 2T$  의역함  
→  $\frac{1}{2T}$ , scale 0  
→  $\frac{1}{2T}$ , scale 0

$A \text{sinc}(\frac{t}{T}) \xrightarrow{\text{scale } \frac{1}{T} \text{ 의역함}} A \cdot T \text{rect}(f \cdot T) = AT \text{rect}(f \cdot T)$   
→  $\frac{1}{T}$ , scale 0  
→  $\frac{1}{T}$ , scale 0

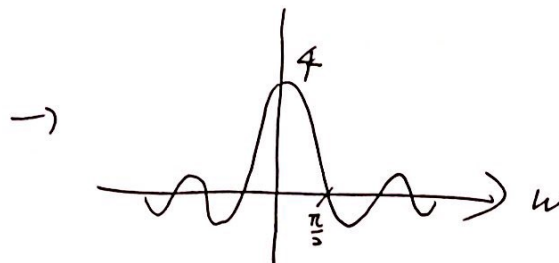
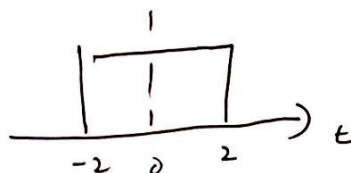


(a)  $4 \text{sinc}(\frac{t}{20}) \xrightarrow{\text{scale } \frac{1}{20} \text{ 의역함}} 4 \cdot 20 \text{rect}(f \cdot 20)$   
→  $\frac{1}{20}$ , scale 0  
→  $\frac{1}{20}$ , scale 0  
 $= 80 \text{rect}(20 \cdot f) = 80 \text{rect}(\frac{10}{\pi} \cdot \omega)$   
 $= 80 \text{rect}(\frac{\omega}{\frac{\pi}{10}})$



$$(b) \pi\left(\frac{t}{4}\right) = \text{rect}\left(\frac{t}{4}\right)$$

$$\begin{aligned} \text{rect}\left(\frac{t}{4}\right) &\longrightarrow 4 \text{sinc}(t \cdot 4) \\ &\quad \text{scale } \frac{1}{4} \text{ along } t \\ &\quad \text{scale } 25\% \text{ along } t \\ &= 4 \text{sinc}\left(\frac{4}{2\pi} \cdot \omega\right) = 4 \text{sinc}\left(\frac{\omega}{\pi/2}\right) \end{aligned}$$



$$(c) \cos 100\pi t \cdot \text{sinc}\left(\frac{t}{20}\right)$$

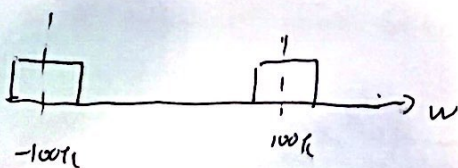
$$\begin{aligned} \cos 100\pi t &= \frac{e^{j100\pi t} + e^{-j100\pi t}}{2} \longrightarrow \frac{2\pi (\delta(\omega - 100\pi) + \delta(\omega + 100\pi))}{2} = \pi (\delta(\omega - 100\pi) + \delta(\omega + 100\pi)) \end{aligned}$$

$$\begin{aligned} \text{sinc}\left(\frac{t}{20}\right) &\longrightarrow 20 \cdot \text{rect}(t \cdot 20) \\ &= 20 \text{rect}\left(\frac{\omega}{\pi/10}\right) \end{aligned}$$

$$\mathcal{F}(\cos 100\pi t \cdot \text{sinc}(t/20)) = \frac{1}{2\pi} \mathcal{F}(\cos 100\pi t) * \mathcal{F}(\text{sinc}(t/20))$$

$$\begin{aligned} \text{shifting properties: } x(t) * \delta(t - t_0) &= x(t - t_0) \\ \text{modulation property: } f(t) \cos \omega_0 t &\longleftrightarrow \frac{1}{2} (F(\omega - \omega_0) + F(\omega + \omega_0)) \\ \text{multiplying, convolution: } x_1(t) \cdot x_2(t) &\longleftrightarrow \frac{1}{2\pi} X_1(\omega) * X_2(\omega) \\ x_1(t) * x_2(t) &\longleftrightarrow X_1(\omega) \cdot X_2(\omega) \end{aligned}$$

$$\begin{aligned} \cos 100\pi t \cdot \text{sinc}\left(\frac{t}{20}\right) &\longrightarrow \frac{1}{2\pi} (\pi (\delta(\omega - 100\pi) + \delta(\omega + 100\pi))) * 20 \text{rect}\left(\frac{\omega}{\pi/10}\right) \\ &= \frac{1}{2\pi} (20\pi \text{rect}\left(\frac{\omega - 100\pi}{\pi/10}\right) + 20\pi \text{rect}\left(\frac{\omega + 100\pi}{\pi/10}\right)) \\ &= 10 \text{rect}\left(\frac{\omega - 100\pi}{\pi/10}\right) + 10 \text{rect}\left(\frac{\omega + 100\pi}{\pi/10}\right) \end{aligned}$$



$$\begin{aligned} \text{multiplication: } \mathcal{F}(x(t) \cdot y(t)) &= \frac{1}{2\pi} X(\omega) * Y(\omega) \\ \mathcal{F}(x(t) * y(t)) &= X(\omega) \cdot Y(\omega) \\ \mathcal{F}(x(t) * y(t)) &= X(\omega) \cdot Y(\omega) \\ \mathcal{F}(x(t) \cdot y(t)) &= \frac{1}{2\pi} X(\omega) * Y(\omega) \end{aligned}$$