## TencorFlow

TensorFlow API r1.4

## tf.reverse\_sequence

```
reverse_sequence(
   input,
   seq_lengths,
   seq_axis=None,
   batch_axis=None,
   name=None,
   seq_dim=None,
   batch_dim=None
)
```

Defined in tensorflow/python/ops/array\_ops.py.

See the guide: Tensor Transformations > Slicing and Joining

Reverses variable length slices.

This op first slices **input** along the dimension **batch\_axis**, and for each slice **i**, reverses the first **seq\_lengths[i]** elements along the dimension **seq\_axis**.

The elements of seq\_lengths must obey seq\_lengths[i] <= input.dims[seq\_dim], and seq\_lengths must be a vector of length input.dims[batch\_dim].

The output slice i along dimension batch\_axis is then given by input slice i, with the first seq\_lengths[i] slices along dimension seq\_axis reversed.

For example:

```
# Given this:
batch_dim = 0
seq_dim = 1
input.dims = (4, 8, ...)
seq_lengths = [7, 2, 3, 5]

# then slices of input are reversed on seq_dim, but only up to seq_lengths:
output[0, 0:7, :, ...] = input[0, 7:0:-1, :, ...]
output[1, 0:2, :, ...] = input[1, 2:0:-1, :, ...]
output[2, 0:3, :, ...] = input[2, 3:0:-1, :, ...]
output[3, 0:5, :, ...] = input[3, 5:0:-1, :, ...]

# while entries past seq_lens are copied through:
output[0, 7:, :, ...] = input[0, 7:, :, ...]
output[1, 2:, :, ...] = input[1, 2:, :, ...]
output[2, 3:, :, ...] = input[2, 3:, :, ...]
output[3, 2:, :, ...] = input[3, 2:, :, ...]
```

In contrast, if:

```
# Given this:
batch_dim = 2
seq_dim = 0
input.dims = (8, ?, 4, ...)
seq_lengths = [7, 2, 3, 5]

# then slices of input are reversed on seq_dim, but only up to seq_lengths:
output[0:7, :, 0, :, ...] = input[7:0:-1, :, 0, :, ...]
output[0:2, :, 1, :, ...] = input[2:0:-1, :, 1, :, ...]
output[0:3, :, 2, :, ...] = input[3:0:-1, :, 2, :, ...]
output[0:5, :, 3, :, ...] = input[5:0:-1, :, 3, :, ...]

# while entries past seq_lens are copied through:
output[7:, :, 0, :, ...] = input[7:, :, 0, :, ...]
output[2:, :, 1, :, ...] = input[2:, :, 1, :, ...]
output[3:, :, 2, :, ...] = input[3:, :, 2, :, ...]
output[2:, :, 3, :, ...] = input[2:, :, 3, :, ...]
```

## Args:

- input: A **Tensor**. The input to reverse.
- seq\_lengths: A Tensor. Must be one of the following types: int32, int64.1-D with length input.dims(batch\_dim) and max(seq\_lengths) <= input.dims(seq\_dim)</li>
- seq\_axis: An int. The dimension which is partially reversed.
- batch\_axis: An optional int. Defaults to 0. The dimension along which reversal is performed.
- name: A name for the operation (optional).

## Returns:

A Tensor . Has the same type as input . The partially reversed input. It has the same shape as input .

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