TancarFlow

TensorFlow API r1.4

tf.nn.batch_normalization

```
batch_normalization(
    x,
    mean,
    variance,
    offset,
    scale,
    variance_epsilon,
    name=None
)
```

Defined in tensorflow/python/ops/nn_impl.py.

See the guide: Neural Network > Normalization

Batch normalization.

As described in http://arxiv.org/abs/1502.03167. Normalizes a tensor by **mean** and **variance**, and applies (optionally) a **scale** γ to it, as well as an **offset** β :

```
\frac{\gamma(x-\mu)}{\sigma} + \beta
```

mean, variance, offset and scale are all expected to be of one of two shapes:

- In all generality, they can have the same number of dimensions as the input x, with identical sizes as x for the dimensions that are not normalized over (the 'depth' dimension(s)), and dimension 1 for the others which are being normalized over. mean and variance in this case would typically be the outputs of tf.nn.moments(..., keep_dims=True) during training, or running averages thereof during inference.
- In the common case where the 'depth' dimension is the last dimension in the input tensor x, they may be one dimensional tensors of the same size as the 'depth' dimension. This is the case for example for the common [batch, depth] layout of fully-connected layers, and [batch, height, width, depth] for convolutions. mean and variance in this case would typically be the outputs of tf.nn.moments(..., keep_dims=False) during training, or running averages thereof during inference.

Args:

- x: Input Tensor of arbitrary dimensionality.
- mean: A mean Tensor.
- variance: A variance Tensor.
- offset: An offset Tensor, often denoted β in equations, or None. If present, will be added to the normalized tensor.
- scale : A scale **Tensor**, often denoted γ in equations, or **None**. If present, the scale is applied to the normalized tensor.
- variance_epsilon: A small float number to avoid dividing by 0.
- name: A name for this operation (optional).

Returns:

the normalized, scaled, offset tensor.

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