

tf.contrib.kfac.utils.posdef_inv_matrix_inverse

```
posdef_inv_matrix_inverse(  
    tensor,  
    identity,  
    damping  
)
```

Defined in [tensorflow/contrib/kfac/python/ops/utils.py](#).

Computes $\text{inverse}(\text{tensor} + \text{damping} * \text{identity})$ directly.

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