

## tf.contrib.rnn.PhasedLSTMCell

### Contents

Class PhasedLSTMCell

### Properties

activity\_regularizer

dtype

## Class PhasedLSTMCell

---

Inherits From: [RNNCell](#)

Defined in [tensorflow/contrib/rnn/python/ops/rnn\\_cell.py](#).

Phased LSTM recurrent network cell.

<https://arxiv.org/pdf/1610.09513v1.pdf>

## Properties

---

### activity\_regularizer

Optional regularizer function for the output of this layer.

### dtype

### graph

### input

Retrieves the input tensor(s) of a layer.

Only applicable if the layer has exactly one input, i.e. if it is connected to one incoming layer.

Returns:

Input tensor or list of input tensors.

Raises:

- `AttributeError` : if the layer is connected to more than one incoming layers.

Raises:

- `RuntimeError` : If called in Eager mode.

- `AttributeError` : If no inbound nodes are found.

## **input\_shape**

Retrieves the input shape(s) of a layer.

Only applicable if the layer has exactly one input, i.e. if it is connected to one incoming layer, or if all inputs have the same shape.

Returns:

Input shape, as an integer shape tuple (or list of shape tuples, one tuple per input tensor).

Raises:

- `AttributeError` : if the layer has no defined input\_shape.
- `RuntimeError` : if called in Eager mode.

## **losses**

**name**

**non\_trainable\_variables**

**non\_trainable\_weights**

**output**

Retrieves the output tensor(s) of a layer.

Only applicable if the layer has exactly one output, i.e. if it is connected to one incoming layer.

Returns:

Output tensor or list of output tensors.

Raises:

- `AttributeError` : if the layer is connected to more than one incoming layers.
- `RuntimeError` : if called in Eager mode.

## **output\_shape**

Retrieves the output shape(s) of a layer.

Only applicable if the layer has one output, or if all outputs have the same shape.

Returns:

Output shape, as an integer shape tuple (or list of shape tuples, one tuple per output tensor).

Raises:

- `AttributeError` : if the layer has no defined output shape.
- `RuntimeError` : if called in Eager mode.

**output\_size**

**scope\_name**

**state\_size**

**trainable\_variables**

**trainable\_weights**

**updates**

**variables**

Returns the list of all layer variables/weights.

Returns:

A list of variables.

**weights**

Returns the list of all layer variables/weights.

Returns:

A list of variables.

## Methods

---

**`__init__`**

```
__init__(
    num_units,
    use_peepholes=False,
    leak=0.001,
    ratio_on=0.1,
    trainable_ratio_on=True,
    period_init_min=1.0,
    period_init_max=1000.0,
    reuse=None
)
```

Initialize the Phased LSTM cell.

Args:

- `num_units` : int, The number of units in the Phased LSTM cell.
- `use_peepholes` : bool, set True to enable peephole connections.
- `leak` : float or scalar float Tensor with value in [0, 1]. Leak applied during training.
- `ratio_on` : float or scalar float Tensor with value in [0, 1]. Ratio of the period during which the gates are open.
- `trainable_ratio_on` : bool, whether ratio\_on is trainable.
- `period_init_min` : float or scalar float Tensor. With value > 0. Minimum value of the initialized period. The period values are initialized by drawing from the distribution:  $e^U(\log(\text{period\_init\_min}), \log(\text{period\_init\_max}))$  Where  $U(.,.)$  is the uniform distribution.
- `period_init_max` : float or scalar float Tensor. With value > period\_init\_min. Maximum value of the initialized period.
- `reuse` : (optional) Python boolean describing whether to reuse variables in an existing scope. If not **True**, and the existing scope already has the given variables, an error is raised.

## `__call__`

```
__call__(
    inputs,
    state,
    scope=None
)
```

Run this RNN cell on inputs, starting from the given state.

Args:

- `inputs` : 2-D tensor with shape `[batch_size x input_size]`.
- `state` : if `self.state_size` is an integer, this should be a 2-D Tensor with shape `[batch_size x self.state_size]`. Otherwise, if `self.state_size` is a tuple of integers, this should be a tuple with shapes `[batch_size x s]` for `s in self.state_size`.
- `scope` : VariableScope for the created subgraph; defaults to class name.

Returns:

A pair containing:

- Output: A 2-D tensor with shape `[batch_size x self.output_size]`.
- New state: Either a single 2-D tensor, or a tuple of tensors matching the arity and shapes of `state`.

## `__deepcopy__`

```
__deepcopy__(memo)
```

## `add_loss`

```
add_loss(
    losses,
    inputs=None
)
```

Add loss tensor(s), potentially dependent on layer inputs.

Some losses (for instance, activity regularization losses) may be dependent on the inputs passed when calling a layer. Hence, when reusing a same layer on different inputs **a** and **b**, some entries in **layer.losses** may be dependent on **a** and some on **b**. This method automatically keeps track of dependencies.

The **get\_losses\_for** method allows to retrieve the losses relevant to a specific set of inputs.

#### Arguments:

- **losses** : Loss tensor, or list/tuple of tensors.
- **inputs** : Optional input tensor(s) that the loss(es) depend on. Must match the **inputs** argument passed to the **\_\_call\_\_** method at the time the losses are created. If **None** is passed, the losses are assumed to be unconditional, and will apply across all dataflows of the layer (e.g. weight regularization losses).

#### Raises:

- **RuntimeError** : If called in Eager mode.

### add\_update

```
add_update(  
    updates,  
    inputs=None  
)
```

Add update op(s), potentially dependent on layer inputs.

Weight updates (for instance, the updates of the moving mean and variance in a BatchNormalization layer) may be dependent on the inputs passed when calling a layer. Hence, when reusing a same layer on different inputs **a** and **b**, some entries in **layer.updates** may be dependent on **a** and some on **b**. This method automatically keeps track of dependencies.

The **get\_updates\_for** method allows to retrieve the updates relevant to a specific set of inputs.

This call is ignored in Eager mode.

#### Arguments:

- **updates** : Update op, or list/tuple of update ops.
- **inputs** : Optional input tensor(s) that the update(s) depend on. Must match the **inputs** argument passed to the **\_\_call\_\_** method at the time the updates are created. If **None** is passed, the updates are assumed to be unconditional, and will apply across all dataflows of the layer.

### add\_variable

```
add_variable(  
    name,  
    shape,  
    dtype=None,  
    initializer=None,  
    regularizer=None,  
    trainable=True,  
    constraint=None  
)
```

Adds a new variable to the layer, or gets an existing one; returns it.

## Arguments:

- `name` : variable name.
- `shape` : variable shape.
- `dtype` : The type of the variable. Defaults to `self.dtype` or `float32`.
- `initializer` : initializer instance (callable).
- `regularizer` : regularizer instance (callable).
- `trainable` : whether the variable should be part of the layer's "trainable\_variables" (e.g. variables, biases) or "non\_trainable\_variables" (e.g. BatchNorm mean, stddev).
- `constraint` : constraint instance (callable).

## Returns:

The created variable.

## Raises:

- `RuntimeError` : If called in Eager mode with regularizers.

## apply

```
apply(  
    inputs,  
    *args,  
    **kwargs  
)
```

Apply the layer on a input.

This simply wraps `self.__call__`.

## Arguments:

- `inputs` : Input tensor(s).
- `*args` : additional positional arguments to be passed to `self.call`.
- `**kwargs` : additional keyword arguments to be passed to `self.call`.

## Returns:

Output tensor(s).

## build

```
build(_)
```

## call

```
call(  
    inputs,  
    state  
)
```

Phased LSTM Cell.

Args:

- `inputs`: A tuple of 2 Tensor. The first Tensor has shape [batch, 1], and type float32 or float64. It stores the time. The second Tensor has shape [batch, features\_size], and type float32. It stores the features.
- `state`: `rnn_cell_impl.LSTMStateTuple`, state from previous timestep.

Returns:

A tuple containing: - A Tensor of float32, and shape [batch\_size, num\_units], representing the output of the cell. - A `rnn_cell_impl.LSTMStateTuple`, containing 2 Tensors of float32, shape [batch\_size, num\_units], representing the new state and the output.

## count\_params

```
count_params()
```

Count the total number of scalars composing the weights.

Returns:

An integer count.

Raises:

- `ValueError`: if the layer isn't yet built (in which case its weights aren't yet defined).

## get\_input\_at

```
get_input_at(node_index)
```

Retrieves the input tensor(s) of a layer at a given node.

Arguments:

- `node_index`: Integer, index of the node from which to retrieve the attribute. E.g. `node_index=0` will correspond to the first time the layer was called.

Returns:

A tensor (or list of tensors if the layer has multiple inputs).

Raises:

- `RuntimeError`: If called in Eager mode.

## get\_input\_shape\_at

```
get_input_shape_at(node_index)
```

Retrieves the input shape(s) of a layer at a given node.

Arguments:

- `node_index` : Integer, index of the node from which to retrieve the attribute. E.g. `node_index=0` will correspond to the first time the layer was called.

Returns:

A shape tuple (or list of shape tuples if the layer has multiple inputs).

Raises:

- `RuntimeError` : If called in Eager mode.

## get\_losses\_for

```
get_losses_for(inputs)
```

Retrieves losses relevant to a specific set of inputs.

Arguments:

- `inputs` : Input tensor or list/tuple of input tensors. Must match the `inputs` argument passed to the `__call__` method at the time the losses were created. If you pass `inputs=None`, unconditional losses are returned, such as weight regularization losses.

Returns:

List of loss tensors of the layer that depend on `inputs`.

Raises:

- `RuntimeError` : If called in Eager mode.

## get\_output\_at

```
get_output_at(node_index)
```

Retrieves the output tensor(s) of a layer at a given node.

Arguments:

- `node_index` : Integer, index of the node from which to retrieve the attribute. E.g. `node_index=0` will correspond to the first time the layer was called.



Returns:

A tensor (or list of tensors if the layer has multiple outputs).

Raises:

- `RuntimeError` : If called in Eager mode.

## **get\_output\_shape\_at**

```
get_output_shape_at(node_index)
```

Retrieves the output shape(s) of a layer at a given node.

Arguments:

- `node_index` : Integer, index of the node from which to retrieve the attribute. E.g. `node_index=0` will correspond to the first time the layer was called.

Returns:

A shape tuple (or list of shape tuples if the layer has multiple outputs).

Raises:

- `RuntimeError` : If called in Eager mode.

## **get\_updates\_for**

```
get_updates_for(inputs)
```

Retrieves updates relevant to a specific set of inputs.

Arguments:

- `inputs` : Input tensor or list/tuple of input tensors. Must match the `inputs` argument passed to the `__call__` method at the time the updates were created. If you pass `inputs=None`, unconditional updates are returned.

Returns:

List of update ops of the layer that depend on `inputs`.

Raises:

- `RuntimeError` : If called in Eager mode.

## **zero\_state**

```
zero_state(  
    batch_size,  
    dtype  
)
```

Return zero-filled state tensor(s).

#### Args:

- `batch_size`: int, float, or unit Tensor representing the batch size.
- `dtype`: the data type to use for the state.

#### Returns:

If `state_size` is an int or TensorShape, then the return value is a **N-D** tensor of shape `[batch_size x state_size]` filled with zeros.

If `state_size` is a nested list or tuple, then the return value is a nested list or tuple (of the same structure) of **2-D** tensors with the shapes `[batch_size x s]` for each s in `state_size`.

---

*Except as otherwise noted, the content of this page is licensed under the [Creative Commons Attribution 3.0 License](#), and code samples are licensed under the [Apache 2.0 License](#). For details, see our [Site Policies](#). Java is a registered trademark of Oracle and/or its affiliates.*

*Last updated November 2, 2017.*

#### Stay Connected

[Blog](#)  
[GitHub](#)  
[Twitter](#)

#### Support

[Issue Tracker](#)  
[Release Notes](#)  
[Stack Overflow](#)

English

[Terms](#) | [Privacy](#)