#### TencorFlow

TensorFlow API r1.4

# tf.contrib.distributions.Poisson

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# Class Poisson

Inherits From: Distribution

Defined in tensorflow/contrib/distributions/python/ops/poisson.py.

See the guide: Statistical Distributions (contrib) > Univariate (scalar) distributions

Poisson distribution.

The Poisson distribution is parameterized by an event rate parameter.

#### Mathematical Details

The probability mass function (pmf) is,

```
pmf(k; lambda, k >= 0) = (lambda^k / k!) / Z

Z = exp(lambda).
```

where rate = lambda and Z is the normalizing constant.

# **Properties**

# allow\_nan\_stats

Python bool describing behavior when a stat is undefined.

Stats return +/- infinity when it makes sense. E.g., the variance of a Cauchy distribution is infinity. However, sometimes the statistic is undefined, e.g., if a distribution's pdf does not achieve a maximum within the support of the distribution, the mode is undefined. If the mean is undefined, then by definition the variance is undefined. E.g. the mean for Student's T for df = 1 is undefined (no clear way to say it is either + or - infinity), so the variance = E[(X - mean)\*\*2] is also undefined.

#### Returns:

• allow\_nan\_stats: Python bool.

# batch\_shape

The DType of Tensor's handled by this Distribution.
event_shape
Shape of a single sample from a single batch as a <b>TensorShape</b> .
May be partially defined or unknown.
Returns:
• event_shape : TensorShape , possibly unknown.
log_rate
Log rate parameter.
name
Name prepended to all ops created by this <b>Distribution</b> .
parameters
Dictionary of parameters used to instantiate this <b>Distribution</b> .
rate
Rate parameter.
reparameterization_type
Describes how samples from the distribution are reparameterized.
Currently this is one of the static instances <b>distributions.FULLY_REPARAMETERIZED</b> or <b>distributions.NOT_REPARAMETERIZED</b> .
Returns:
An instance of ReparameterizationType.
validate_args

Shape of a single sample from a single event index as a TensorShape .

• batch\_shape: **TensorShape**, possibly unknown.

The batch dimensions are indexes into independent, non-identical parameterizations of this distribution.

May be partially defined or unknown.

Returns:

dtype

Python bool indicating possibly expensive checks are enabled.

# Methods

#### \_\_init\_\_

```
__init__(
    rate=None,
    log_rate=None,
    validate_args=False,
    allow_nan_stats=True,
    name='Poisson'
)
```

Initialize a batch of Poisson distributions.

# Args:

- rate: Floating point tensor, the rate parameter. rate must be positive. Must specify exactly one of rate and log\_rate.
- log\_rate: Floating point tensor, the log of the rate parameter. Must specify exactly one of rate and log\_rate.
- validate\_args: Python bool, default False. When True distribution parameters are checked for validity despite
  possibly degrading runtime performance. When False invalid inputs may silently render incorrect outputs.
- allow\_nan\_stats: Python bool, default True. When True, statistics (e.g., mean, mode, variance) use the value
   "NaN" to indicate the result is undefined. When False, an exception is raised if one or more of the statistic's batch members are undefined.
- name: Python str name prefixed to Ops created by this class.

#### Raises:

- ValueError: if none or both of rate, log\_rate are specified.
- TypeError: if rate is not a float-type.
- TypeError: if log\_rate is not a float-type.

## batch\_shape\_tensor

```
batch_shape_tensor(name='batch_shape_tensor')
```

Shape of a single sample from a single event index as a 1-D Tensor.

The batch dimensions are indexes into independent, non-identical parameterizations of this distribution.

## Args:

name: name to give to the op

## Returns:

• batch\_shape: Tensor.

# cdf

```
cdf(
   value,
   name='cdf'
)
```

Cumulative distribution function.

Given random variable X, the cumulative distribution function cdf is:

```
cdf(x) := P[X \le x]
```

Additional documentation from Poisson:

Note that the input value must be a non-negative floating point tensor with dtype dtype and whose shape can be broadcast with self.rate. x is only legal if it is non-negative and its components are equal to integer values.

# Args:

- value: float or double Tensor.
- name: The name to give this op.

#### Returns:

cdf: a Tensor of shape sample\_shape(x) + self.batch\_shape with values of type self.dtype.

# copy

```
copy(**override_parameters_kwargs)
```

Creates a deep copy of the distribution.



Note: the copy distribution may continue to depend on the original initialization arguments.

# Args:

• \*\*override\_parameters\_kwargs : String/value dictionary of initialization arguments to override with new values.

## Returns:

 distribution: A new instance of type(self) initialized from the union of self.parameters and override\_parameters\_kwargs, i.e., dict(self.parameters, \*\*override\_parameters\_kwargs).

#### covariance

```
covariance(name='covariance')
```

#### Covariance.

Covariance is (possibly) defined only for non-scalar-event distributions.

For example, for a length-k, vector-valued distribution, it is calculated as,

```
Cov[i, j] = Covariance(X_i, X_j) = E[(X_i - E[X_i]) (X_j - E[X_j])]
```

where Cov is a (batch of)  $k \times k$  matrix,  $0 \leftarrow (i, j) \leftarrow k$ , and E denotes expectation.

Alternatively, for non-vector, multivariate distributions (e.g., matrix-valued, Wishart), **Covariance** shall return a (batch of) matrices under some vectorization of the events, i.e.,

```
Cov[i, j] = Covariance(Vec(X)_i, Vec(X)_j) = [as above]
```

where Cov is a (batch of)  $k' \times k'$  matrices,  $0 \le (i, j) \le k' = reduce\_prod(event\_shape)$ , and Vec is some function mapping indices of this distribution's event dimensions to indices of a length-k' vector.

# Args:

• name: The name to give this op.

#### Returns:

covariance: Floating-point Tensor with shape [B1, ..., Bn, k', k'] where the first n dimensions are batch coordinates and k' = reduce\_prod(self.event\_shape).

# entropy

```
entropy(name='entropy')
```

Shannon entropy in nats.

## event\_shape\_tensor

```
event_shape_tensor(name='event_shape_tensor')
```

Shape of a single sample from a single batch as a 1-D int32 Tensor.

## Args:

• name: name to give to the op

#### Returns:

event\_shape: Tensor.

# is\_scalar\_batch

```
is_scalar_batch(name='is_scalar_batch')
```

Indicates that batch\_shape == [].

## Args:

name: The name to give this op.

## Returns:

is\_scalar\_batch: bool scalar Tensor.

## is\_scalar\_event

```
is_scalar_event(name='is_scalar_event')
```

Indicates that event\_shape == [].

# Args:

• name: The name to give this op.

## Returns:

• is\_scalar\_event: bool scalar Tensor.

# log\_cdf

```
log_cdf(
    value,
    name='log_cdf'
)
```

Log cumulative distribution function.

Given random variable X, the cumulative distribution function cdf is:

```
log\_cdf(x) := Log[P[X \leftarrow x]]
```

Often, a numerical approximation can be used for  $log_cdf(x)$  that yields a more accurate answer than simply taking the logarithm of the cdf when x << -1.

Additional documentation from Poisson:

Note that the input value must be a non-negative floating point tensor with dtype dtype and whose shape can be broadcast with self.rate . x is only legal if it is non-negative and its components are equal to integer values.

#### Args:

- value: float or double Tensor.
- name: The name to give this op.

#### Returns:

• logcdf: a Tensor of shape sample\_shape(x) + self.batch\_shape with values of type self.dtype.

# log\_prob

```
log_prob(
   value,
   name='log_prob'
)
```

Log probability density/mass function.

Additional documentation from Poisson:

Note that the input value must be a non-negative floating point tensor with dtype dtype and whose shape can be broadcast with self.rate. x is only legal if it is non-negative and its components are equal to integer values.

# Args:

- value: float or double Tensor.
- name: The name to give this op.

#### Returns:

• log\_prob: a Tensor of shape sample\_shape(x) + self.batch\_shape with values of type self.dtype.

# log\_survival\_function

```
log_survival_function(
    value,
    name='log_survival_function'
)
```

Log survival function.

Given random variable X, the survival function is defined:

```
log\_survival\_function(x) = Log[ P[X > x] ]
= Log[ 1 - P[X \le x] ]
= Log[ 1 - cdf(x) ]
```

Typically, different numerical approximations can be used for the log survival function, which are more accurate than 1 - cdf(x) when x >> 1.

## Args:

- value: float or double Tensor.
- name: The name to give this op.

## Returns:

Tensor of shape sample\_shape(x) + self.batch\_shape with values of type self.dtype.

#### mean

```
mean(name='mean')
```

Mean.

#### mode

```
mode(name='mode')
```

Mode.

Additional documentation from Poisson:



Note: when rate is an integer, there are actually two modes: rate and rate - 1. In this case we return the larger, i.e., rate.

# param\_shapes

```
param_shapes(
    cls,
    sample_shape,
    name='DistributionParamShapes'
)
```

Shapes of parameters given the desired shape of a call to sample().

This is a class method that describes what key/value arguments are required to instantiate the given **Distribution** so that a particular shape is returned for that instance's call to **sample()**.

Subclasses should override class method \_param\_shapes .

# Args:

- sample\_shape: Tensor or python list/tuple. Desired shape of a call to sample().
- name: name to prepend ops with.

## Returns:

dict of parameter name to Tensor shapes.

## param\_static\_shapes

```
param_static_shapes(
    cls,
    sample_shape
)
```

param\_shapes with static (i.e. TensorShape ) shapes.

This is a class method that describes what key/value arguments are required to instantiate the given **Distribution** so that a particular shape is returned for that instance's call to **sample()**. Assumes that the sample's shape is known statically.

Subclasses should override class method \_param\_shapes to return constant-valued tensors when constant values are fed.

## Args:

• sample\_shape: TensorShape or python list/tuple. Desired shape of a call to sample().

Returns:

dict of parameter name to TensorShape.

#### Raises:

• ValueError: if sample\_shape is a TensorShape and is not fully defined.

# prob

```
prob(
   value,
   name='prob'
)
```

Probability density/mass function.

# Args:

- value: float or double Tensor.
- name: The name to give this op.

#### Returns:

• prob: a Tensor of shape sample\_shape(x) + self.batch\_shape with values of type self.dtype.

## quantile

```
quantile(
   value,
   name='quantile'
)
```

Quantile function. Aka "inverse cdf" or "percent point function".

Given random variable X and p in [0, 1], the quantile is:

```
quantile(p) := x such that P[X \le x] == p
```

# Args:

- value: float or double Tensor.
- name: The name to give this op.

# Returns:

• quantile: a Tensor of shape sample\_shape(x) + self.batch\_shape with values of type self.dtype.

# sample

```
sample(
    sample_shape=(),
    seed=None,
    name='sample'
)
```

Generate samples of the specified shape.

Note that a call to sample() without arguments will generate a single sample.

# Args:

- sample\_shape: 0D or 1D int32 Tensor. Shape of the generated samples.
- seed: Python integer seed for RNG
- name: name to give to the op.

#### Returns:

samples: a Tensor with prepended dimensions sample\_shape.

## stddev

```
stddev(name='stddev')
```

Standard deviation.

Standard deviation is defined as,

```
stddev = E[(X - E[X])**2]**0.5
```

where **X** is the random variable associated with this distribution, **E** denotes expectation, and **stddev.shape** = **batch\_shape** + **event\_shape** .

## Args:

• name: The name to give this op.

## Returns:

stddev: Floating-point Tensor with shape identical to batch\_shape + event\_shape, i.e., the same shape as self.mean().

# survival\_function

```
survival_function(
   value,
   name='survival_function'
)
```

Survival function.

Given random variable X, the survival function is defined:

```
survival\_function(x) = P[X > x]
= 1 - P[X <= x]
= 1 - cdf(x).
```

# Args:

- value: float or double Tensor.
- name: The name to give this op.

#### Returns:

**Tensor** of shape  $sample\_shape(x) + self.batch\_shape$  with values of type self.dtype.

#### variance

```
variance(name='variance')
```

Variance.

Variance is defined as,

```
Var = E[(X - E[X])**2]
```

where X is the random variable associated with this distribution, E denotes expectation, and Var.shape = batch\_shape + event\_shape.

## Args:

• name: The name to give this op.

#### Returns:

variance: Floating-point Tensor with shape identical to batch\_shape + event\_shape , i.e., the same shape as self.mean().

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