#### TencorFlow

TensorFlow API r

 $tf. contrib. kfac. fisher\_factors. Inverse Providing Factor\\$ 

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\_\_init\_\_

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# Class InverseProvidingFactor

Inherits From: FisherFactor

Defined in tensorflow/contrib/kfac/python/ops/fisher\_factors.py.

Base class for FisherFactors that maintain inverses, powers, etc of \_cov.

Assumes that the \_cov property is a square PSD matrix.

Subclasses must implement the \_compute\_new\_cov method, and the \_var\_scope and \_cov\_shape properties.

## Methods

\_\_init\_\_

\_\_init\_\_()

#### get\_cov

get\_cov()

## get\_eigendecomp

get\_eigendecomp()

## get\_inverse

get\_inverse(damping)

### get\_matpower

```
get_matpower(
    exp,
    damping
)
```

### instantiate\_covariance

```
instantiate_covariance()
```

Instantiates the covariance Variable as the instance member \_cov.

## make\_covariance\_update\_op

```
make_covariance_update_op(ema_decay)
```

Constructs and returns the covariance update Op.

#### Args:

• ema\_decay: The exponential moving average decay (float or Tensor).

#### Returns:

An Op for updating the covariance Variable referenced by \_cov.

### make\_inverse\_update\_ops

```
make_inverse_update_ops()
```

Create and return update ops corresponding to registered computations.

### register\_damped\_inverse

```
register_damped_inverse(damping)
```

Registers a damped inverse needed by a FisherBlock.

### Args:

• damping: The damping value (float or Tensor) for this factor.

## register\_eigendecomp

```
register_eigendecomp()
```

Registers that an eigendecomposition is needed by a FisherBlock.

### register\_matpower

```
register_matpower(
    exp,
    damping
)
```

Registers a matrix power needed by a FisherBlock.

## Args:

- exp: The exponent (float or Tensor) to raise the matrix to.
- damping: The damping value (float or Tensor).

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