TopogrElow

TensorFlow API r1.4

tf.estimator.RunConfig

Contents
Class RunConfig
Properties
cluster_spec
evaluation_master

Class RunConfig

Defined in tensorflow/python/estimator/run_config.py.

This class specifies the configurations for an <code>Estimator</code> run.

Properties

```
cluster_spec
evaluation_master
is_chief
keep_checkpoint_every_n_hours
keep_checkpoint_max
log_step_count_steps
master
model_dir
num_ps_replicas
num_worker_replicas
save_checkpoints_secs
save_checkpoints_steps
```

service

save_summary_steps

Returns the platform defined (in TF_CONFIG) service dict.

session_config

task_id

task_type

tf_random_seed

Methods

__init__

```
__init__(
    model_dir=None,
    tf_random_seed=None,
    save_summary_steps=100,
    save_checkpoints_steps=_USE_DEFAULT,
    save_checkpoints_secs=_USE_DEFAULT,
    session_config=None,
    keep_checkpoint_max=5,
    keep_checkpoint_every_n_hours=10000,
    log_step_count_steps=100
)
```

Constructs a RunConfig.

All distributed training related properties <code>cluster_spec</code>, <code>is_chief</code>, <code>master</code>, <code>num_worker_replicas</code>, <code>num_ps_replicas</code>, <code>task_id</code>, and <code>task_type</code> are set based on the <code>TF_CONFIG</code> environment variable, if the pertinent information is present. The <code>TF_CONFIG</code> environment variable is a JSON object with attributes: <code>cluster</code> and <code>task</code>.

cluster is a JSON serialized version of **ClusterSpec** 's Python dict from **server_lib.py**, mapping task types (usually one of the **TaskType** enums) to a list of task addresses.

task has two attributes: type and index, where type can be any of the task types in cluster. When TF_CONFIG` contains said information, the following properties are set on this class:

- **cluster_spec** is parsed from **TF_CONFIG['cluster']**. Defaults to {}. If present, must have one and only one node in the **chief** attribute of **cluster_spec**.
- task_type is set to TF_CONFIG['task']['type']. Must set if cluster_spec is present; must be worker (the default value) if cluster_spec is not set.
- task_id is set to TF_CONFIG['task']['index']. Must set if cluster_spec is present; must be 0 (the default value) if cluster_spec is not set.
- master is determined by looking up task_type and task_id in the cluster_spec. Defaults to ".
- num_ps_replicas is set by counting the number of nodes listed in the ps attribute of cluster_spec. Defaults to 0.
- num_worker_replicas is set by counting the number of nodes listed in the worker and chief attributes of cluster_spec. Defaults to 1.
- is_chief is determined based on task_type and cluster.

There is a special node with <code>task_type</code> as <code>evaluator</code>, which is not part of the (training) <code>cluster_spec</code>. It handles the distributed evaluation job.

Example of non-chief node:

Example of chief node:

Example of evaluator node (evaluator is not part of training cluster):

N.B.: If save_checkpoints_steps or save_checkpoints_secs is set, keep_checkpoint_max might need to be adjusted accordingly, especially in distributed training. For example, setting save_checkpoints_secs as 60 without adjusting keep_checkpoint_max (defaults to 5) leads to situation that checkpoint would be garbage collected after 5 minutes. In distributed training, the evaluation job starts asynchronously and might fail to load or find the checkpoint due to race condition.

Args:

model_dir: directory where model parameters, graph, etc are saved. If None, will use a default value set by the
Estimator.

- tf_random_seed: Random seed for TensorFlow initializers. Setting this value allows consistency between reruns.
- save_summary_steps: Save summaries every this many steps.
- save_checkpoints_steps: Save checkpoints every this many steps. Can not be specified with save_checkpoints_secs.
- save_checkpoints_secs: Save checkpoints every this many seconds. Can not be specified with
 save_checkpoints_steps. Defaults to 600 seconds if both
 save_checkpoints_steps and save_checkpoints_secs
 are not set in constructor. If both save_checkpoints_steps and save_checkpoints_secs are None, then checkpoints
 are disabled.
- session_config: a ConfigProto used to set session parameters, or None.
- keep_checkpoint_max: The maximum number of recent checkpoint files to keep. As new files are created, older files are deleted. If None or 0, all checkpoint files are kept. Defaults to 5 (that is, the 5 most recent checkpoint files are kept.)
- keep_checkpoint_every_n_hours: Number of hours between each checkpoint to be saved. The default value of 10,000 hours effectively disables the feature.
- log_step_count_steps: The frequency, in number of global steps, that the global step/sec will be logged during training.

Raises:

ValueError: If both save_checkpoints_steps and save_checkpoints_secs are set.

replace

```
replace(**kwargs)
```

Returns a new instance of RunConfig replacing specified properties.

Only the properties in the following list are allowed to be replaced: - model_dir . - tf_random_seed , - save_summary_steps , - save_checkpoints_steps , - save_checkpoints_secs , - session_config , - keep_checkpoint_max , - keep_checkpoint_every_n_hours , - log_step_count_steps ,

In addition, either save_checkpoints_steps or save_checkpoints_secs can be set (should not be both).

Args:

**kwargs: keyword named properties with new values.

Raises:

 ValueError: If any property name in kwargs does not exist or is not allowed to be replaced, or both save_checkpoints_steps and save_checkpoints_secs are set.

Returns:

a new instance of RunConfig.

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