

Covariance estimation using generalized fiducial inference

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August 5, 2013

Motivation

- Estimation of Σ is a fundamental problem.
- Distribution for Σ is appealing.
- Fixed zeros in A is a different type of sparsity.
- Sparse A makes sense in some biological/genetic context.
- Choosing priors can be infeasible when the sparse structure of A is unknown.

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- $r(\theta) = \frac{f(x, \theta) J(x, \theta)}{\int_{\Theta} f(x, \theta') J(x, \theta') d\theta'}$, where

$$J(x, \theta) = \sum_{\substack{\mathbf{i}=(i_1, \dots, i_p) \\ 1 \leq i_1 < \dots < i_p \leq p}} \left| \det \left[\left(\frac{d}{d\theta} G(u, \theta) \right) \Big|_{u=G^{-1}(x, \theta)} \right]_{\mathbf{i}} \right|.$$

GFD for covariate A

Data generating function:

$$Y_i = AZ_i, \quad i = 1, \dots, n,$$

where $Z_i \stackrel{\text{iid}}{\sim} N(0, I)$.

\Rightarrow GFD of A :

$$r(A) \propto J(\mathbf{Y}, A) f(\mathbf{Y}, A),$$

where

$$f(\mathbf{Y}, A) = (2\pi)^{-\frac{np}{2}} |\det(A)|^{-n} \exp \left[-\frac{1}{2} \text{tr} \{ n S_n (A A^T)^{-1} \} \right],$$

S_n is the sample covariance matrix.

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What about $J(\mathbf{Y}, A)$?

Simplified Jacobian

$$J(\mathbf{Y}, A) = \prod_{i=1}^p \binom{p}{p_i} \cdot \prod_{i=1}^p \overline{\left| \det \left[(V_i)_{\mathbf{i}_i} \right] \right|},$$

where

- p_i = number of non fixed zeros in row i ;
- V_i = a submatrix of V , uniquely determined by the fixed zeros in the i^{th} row of A ;
- $V = (Y_1, \dots, Y_n)^T$;
- $\mathbf{i}_i = (i_1, \dots, i_{p_i p})$, s.t. $1 \leq i_1 < \dots < i_{p_i p} \leq np$;
- $\overline{\left| \det \left[(V_i)_{\mathbf{i}_i} \right] \right|}$ = average absolute determinant of all possible expressions of $(V_i)_{\mathbf{i}_i}$ for a fixed i .

GFD of Σ ?

- If there is no fixed zero in A ,

$$J(\mathbf{Y}, A) = \left(\sum_{\substack{\mathbf{i}=(i_1, \dots, i_p) \\ 1 \leq i_1 < \dots < i_p \leq p}} |\det [(V)_{\mathbf{i}}]| \right)^p |\det(A)|^{-p}$$

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- If there are fixed zeros in A , the fiducial distribution of Σ is usually complicated!

Estimate A and infer $\Sigma = AA^T$

Recall

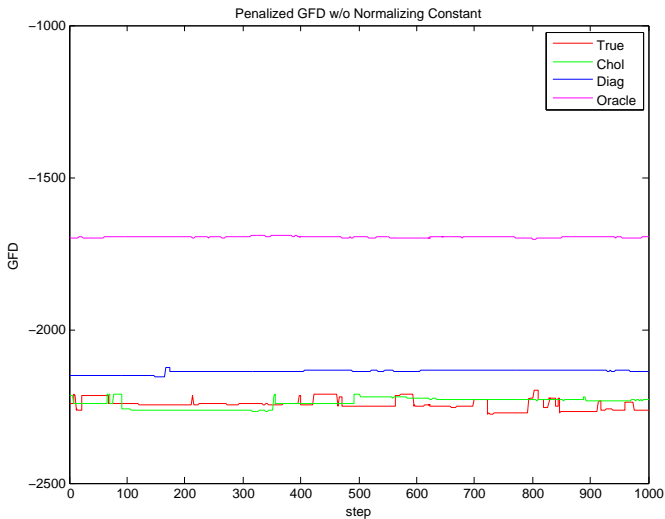
$$r(A) \propto J(\mathbf{Y}, A)f(\mathbf{Y}, A),$$
$$\Sigma = AA^T.$$

Covariate A can be estimated using

- reversible jump MCMC with moves: *birth*, *death*, *update*,
+
- Minimum Description Length (MDL) as penalty:

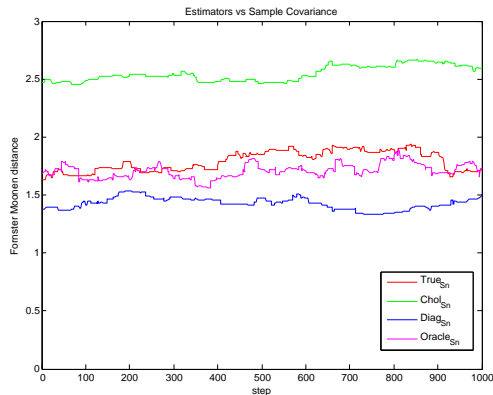
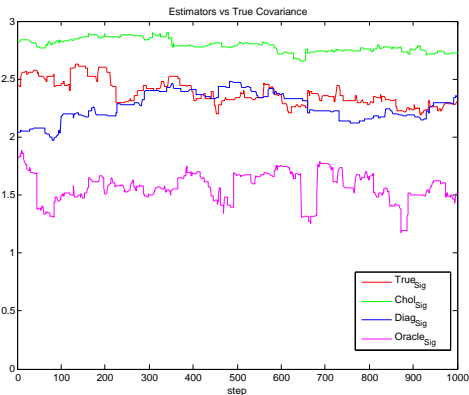
$$p(A) = \sum_{i=1}^n \frac{p_i^2}{2} \log n$$

Penalized GFD trace plot



Forstner & Moonen (1999):

$$\mathbf{d}(M, N) = \sqrt{\sum_{i=1}^n \ln^2 \lambda_i(M, N)}.$$



Conclusion and future work

- GFI approach to covariance estimation is feasible.
- Implement geometric structure on A .
- Improve the efficiency of the reversible jump MCMC's.

The End.

Thank you!

Questions/suggestions?