# Operating Systems Practice

Scheduler

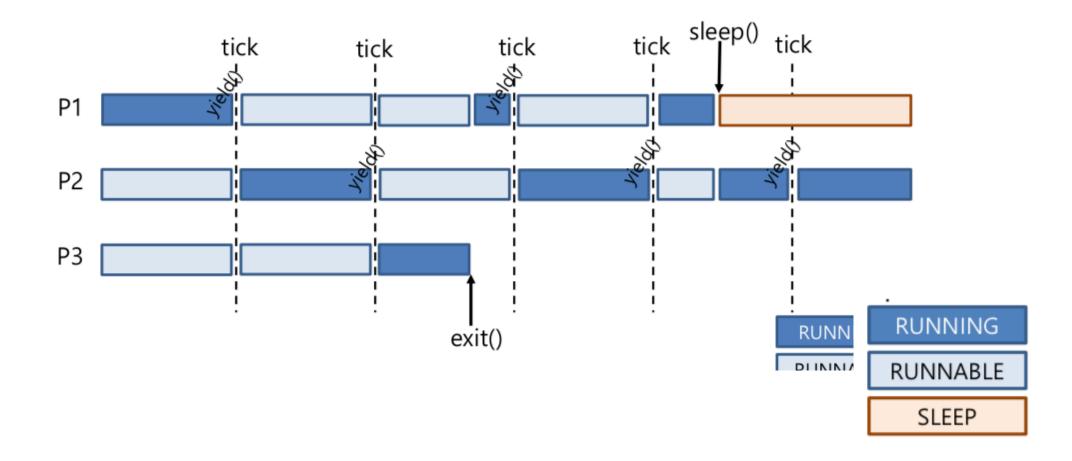
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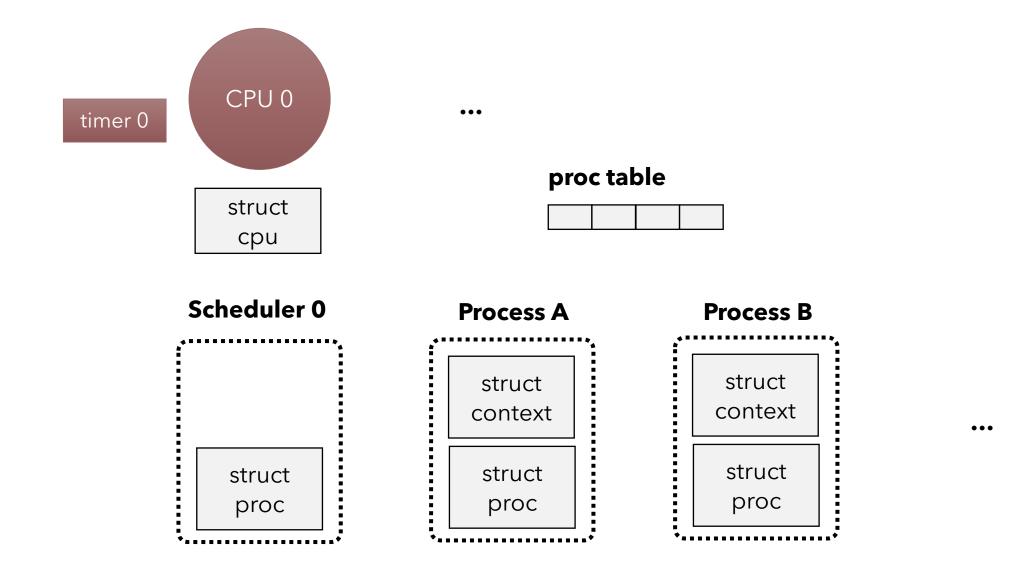


## XV6 Scheduler – Round Robin

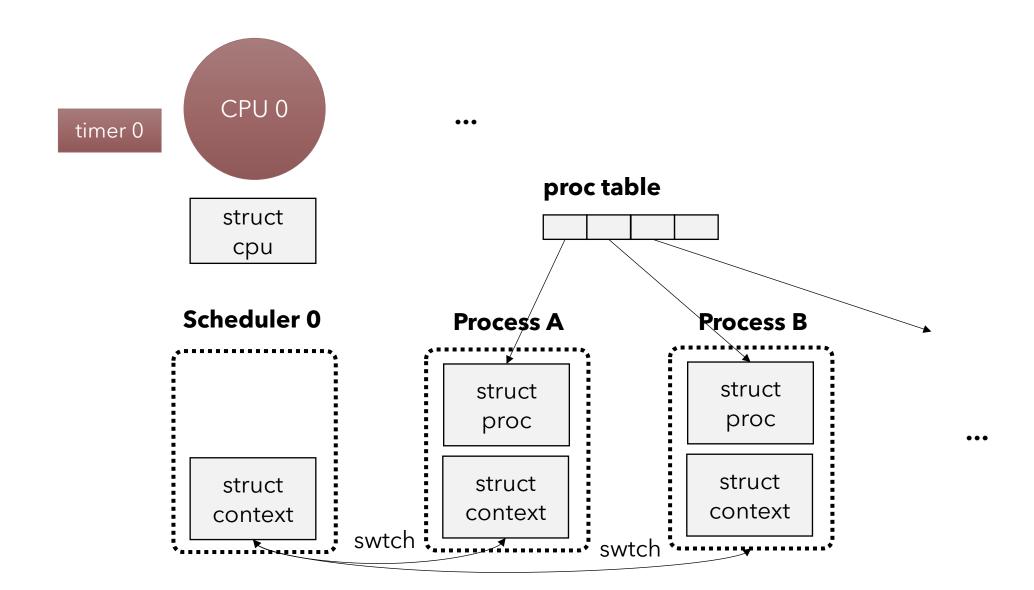
- Timer's interrupt request (IRQ) enforces an yield of a CPU
- A "RUNNABLE" process is chosen to be run in a round-robin manner



# XV6 Data Structures for Scheduling



# XV6 Data Structures for Scheduling



### **Process**

- proc.h
- procstate
- struct proc

```
35 enum procstate { UNUSED, EMBRYO, SLEEPING, RUNNABLE, RUNNING, ZOMBIE };
37 // Per-process state
38 struct proc {
    uint sz:
                                // Size of process memory (bytes)
    pde t* pgdir;
                                // Page table
    char *kstack;
                                // Bottom of kernel stack for this process
    enum procstate state;
                                // Process state
    int pid;
                                // Process ID
    struct proc *parent;
                                // Parent process
    struct trapframe *tf;
                                // Trap frame for current syscall
                                // swtch() here to run process
    struct context *context;
    void *chan;
                                // If non-zero, sleeping on chan
    int killed:
                                // If non-zero, have been killed
    struct file *ofile[NOFILE]; // Open files
    struct inode *cwd;
                                // Current directory
    char name[16];
                         // Process name (debugging)
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                                // Process priority
    int priority;
53 };
```

#### **Proc State**

- UNUSED: Not used
- EMBRYO: Newly allocated (not ready for running yet)
- SLEEPING: Waiting for I/O, child process, or time
- RUNNABLE: Ready to run
- RUNNING: Running on CPU
- ZOMBIE: Exited

## **Process**

- proc.h
- struct context

```
16 //PAGEBREAK: 17
17 // Saved registers for kernel context switches.
18 // Don't need to save all the segment registers (%cs, etc),
19 // because they are constant across kernel contexts.
20 // Don't need to save %eax, %ecx, %edx, because the
21 // x86 convention is that the caller has saved them.
22 // Contexts are stored at the bottom of the stack they
23 // describe; the stack pointer is the address of the context.
24 // The layout of the context matches the layout of the stack in swtch.S
25 // at the "Switch stacks" comment. Switch doesn't save eip explicitly,
26 // but it is on the stack and allocproc() manipulates it.
27 struct context {
    uint edi;
    uint esi;
     uint ebx;
     uint ebp;
     uint eip;
```

## Scheduler

- proc.h
- struct cpu

```
1 // Per-CPU state
 2 struct cpu {
    uchar apicid;
                                 // Local APIC ID
    struct context *scheduler;
                                // swtch() here to enter scheduler
    struct taskstate ts;
                                 // Used by x86 to find stack for interrupt
    struct segdesc gdt[NSEGS];
                                 // x86 global descriptor table
    volatile uint started;
                                 // Has the CPU started?
                                 // Depth of pushcli nesting.
    int ncli;
                                 // Were interrupts enabled before pushcli?
    int intena;
    struct proc *proc;
                                 // The process running on this cpu or null
11 };
13 extern struct cpu cpus[NCPU];
14 extern int ncpu;
```

## Scheduler

#### main.c

```
17 int
18 main(void)
19 {
    kinit1(end, P2V(4*1024*1024)); // phys page allocator
    kvmalloc();
                     // kernel page table
    mpinit();
                     // detect other processors
    lapicinit();
                     // interrupt controller
                     // segment descriptors
    seginit();
    picinit();
                     // disable pic
    ioapicinit();
                     // another interrupt controller
    consoleinit(); // console hardware
    uartinit();
                     // serial port
    pinit();
                     // process table
    tvinit():
                     // trap vectors
    binit();
                     // buffer cache
    fileinit();
                    // file table
    ideinit();
                     // disk
    startothers(); // start other processors
    kinit2(P2V(4*1024*1024), P2V(PHYSTOP)); // must come a
    userinit();
                     // first user process
    mpmain();
                     // finish this processor's setup
```

#### proc.c

```
22 void
 323 scheduler(void)
      struct proc *p;
      struct cpu *c = mycpu();
      c->proc = 0;
      for(;;){
        // Enable interrupts on this processor.
        sti();
        // Loop over process table looking for process to run.
        acquire(&ptable.lock):
        for(p = ptable.proc; p < &ptable.proc[NPROC]; p++){</pre>
          if(p->state != RUNNABLE)
             continue;
          // Switch to chosen process. It is the process's job
          // to release ptable.lock and then reacquire it
          // before jumping back to us.
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          c->proc = p;
          switchuvm(p);
          p->state = RUNNING;
                                                     Start to execute
          swtch(&(c->scheduler), p->context);
                                                     chosen process
          switchkvm();
          // Process is done running for now.
          // It should have changed its p->state before coming back.
          c\rightarrow proc = 0;
        release(&ptable.lock);
```

## When to Schedule

- exit(), sleep()
- timer interrupt (yield())

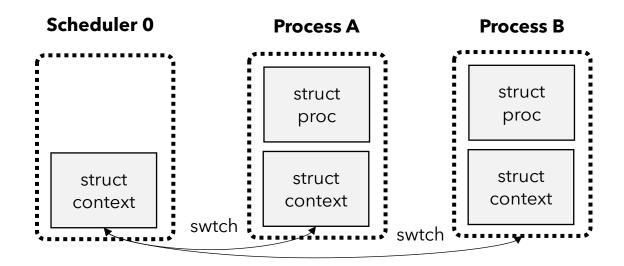
#### trap.c

```
36 void
37 trap(struct trapframe *tf)
38 {
```

```
// Force process to give up CPU on clock tick.
// If interrupts were on while locks held, would need to check nlock.
if(myproc() && myproc()->state == RUNNING &&
    tf->trapno == T_IRQ0+IRQ_TIMER)
yield();
```

## How Scheduler works

```
void
    sched(void)
      int intena;
      struct proc *p = myproc();
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      if(!holding(&ptable.lock))
372
        panic("sched ptable.lock");
      if(mycpu()->ncli != 1)
        panic("sched locks");
374
      if(p->state == RUNNING)
        panic("sched running");
376
      if(readeflags()&FL_IF)
        panic("sched interruptible");
      intena = mycpu()->intena;
      swtch(&p->context, mycpu()->scheduler);
      mycpu()->intena = intena;
382 }
   // Give up the CPU for one scheduling round.
385 void
386 yield(void)
      acquire(&ptable.lock); //DOC: yieldlock
      myproc()->state = RUNNABLE;
      sched();
      release(&ptable.lock);
```



## How Scheduler works

```
322 void
323 scheduler(void)
   struct proc *p;
    struct cpu *c = mycpu();
     c->proc = 0;
     for(;;){
      // Enable interrupts on this processor.
      sti();
       // Loop over process table looking for process to run.
       acquire(&ptable.lock);
       for(p = ptable.proc; p < &ptable.proc[NPROC]; p++){</pre>
        if(p->state != RUNNABLE)
           continue;
         // Switch to chosen process. It is the process's job
         // to release ptable.lock and then reacquire it
         // before jumping back to us.
        c->proc = p;
         switchuvm(p);
         p->state = RUNNING;
         swtch(&(c->scheduler), p->context);
Return from here
         switchkvm();
         // Process is done running for now.
        // It should have changed its p->state before coming back.
         c->proc = 0;
       release(&ptable.lock);
```

# Project 2. Priority Scheduling

- Implement priority scheduler in xv6
  - The lower nice value, the higher priority
  - The highest priority process should be chosen for next running
    - Tiebreak: Arbitrary
- Scheduler runs only when a change occurs in process priorities
  - DO NOT call the scheduler on the timer interrupt
  - When a process calls fork(), the nice value of child process is set to 5.

## test\_sched.c

- Add test sched.c
- ./test\_sched

```
2 #include "stat.h"
 3 #include "user.h"
 6 int main(int argc, char** argv)
        int pid;
        int mypid;
        // Change the priority of init processes.
        setnice(1, 10);
       // Change the priority of current processes.
        setnice(getpid(), 2);
       // Create a child process
        pid = fork();
        if(pid == 0) {
            printf(1, "#### State 2 ####\n");
        } else {
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37 }
            printf(1, "#### State 1 ####\n");
            // Change the priority of parent process.
            setnice(pid, 10);
            wait(); // Yield CPU
            printf(1, "#### State 3 ####\n");
        mypid = getpid();
        printf(1, "PID %d is finished\n", mypid);
        exit();
```

\$ test\_sched
#### State 1 ####
#### State 2 ####
PID 4 is finished
#### State 3 ####
PID 3 is finished

# Hand-in Procedures (1/2)

- Download template
  - https://github.com/eunjicious/xv6-ssu.git (pull or clone)
  - tar xvzf xv6 ssu syscall.tar.gz

- Rename directory
  - mv xv6\_ssu\_syscall xv6\_ssu\_sched
- Add test\_sched.c to your codes and modify Makefile properly
- Build with CPUS=1 flag
  - Makefile

```
ifndef CPUS
CPUS := 1
endif
```

# Hand-in Procedures (2/2)

- Compress your code (ID: 20201234)
  - \$tar cvzf xv6\_ssu\_sched\_20201234.tar.gz xv6\_ssu\_sched
  - Please command \$make clean before compressing
- Submit your tar.gz file through myclass.ssu.ac.kr
- NO DELAY is allowed !!
- PLEASE DO NOT COPY !!