

Lecture 1 - Review of Matrices & Vectors

Module 3 - Linear Algebra
CS/ISyE/ECE 524



Linear Algebra Module

Learning Outcomes

By the end of this module, you should be able to



- Define key concepts, such as:
 - Matrix
 - Transpose
 - Inner/outer product
 - Linear/affine functions
 - Affine combinations
 - Convex combinations
 - Hyperplane
 - Subspace
- Dimension
- Halfspace
- Polyhedron (polytope)
- Perform some simple linear algebra operations, such as:
 - Matrix multiplication
 - Write lists of linear/affine functions as matrices
- Start thinking about constraints as intersections of halfspaces

What is a matrix?

- The most general form of a matrix is as follows:

$$A = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}$$

- We can multiply matrices together if the **inner dimension** of both matrices are equal:

$$\begin{array}{ccc} C & \leftarrow & A \times B \\ (m \times p) & & (m \times n) \quad (n \times p) \end{array}$$

- The individual elements of the new matrix C are calculated with the formula:

A **matrix** is an array of numbers with m rows and n columns. We denote the space where a matrix "lives" by:

(Not that kind of matrix)



$$C = A \times B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \times \begin{bmatrix} 4 & 3 \\ 8 & 9 \end{bmatrix} = ?$$

$$c_{11} = \sum_{k=1}^2 a_{1k} b_{k1} = 1 \cdot 4 + 2 \cdot 8 = 4 + 16 = 20$$

$$C = \begin{bmatrix} 20 & 1 \cdot 4 + 2 \cdot 8 \\ 44 & 45 \\ 68 & 69 \end{bmatrix}$$

Matrix multiplication example

Basic Definitions: Transpose

The transpose operator has some important properties:

- The transpose of the transpose is the original matrix:
- The transpose of two matrices multiplied together is the transpose of the second matrix multiplied by the transpose of the first matrix:

The **transpose** operator swaps rows and columns of a matrix:

and

EXAMPLE:

Basic Definitions: Vector

- We typically write vectors as follows:

where

This is just an
matrix

- The transpose of a vector is a row matrix (or row vector):

A **vector** is a matrix with only one column (“column matrix”).

- The transpose of a row vector (row matrix) is a column vector (column matrix) or just a “vector.”

Basic Definitions: Inner and Outer Products

The **inner product** operator is a way to multiply two vectors and produce a scalar:

or

- Another way of writing an inner product operation:

The **outer product** operator is a way to multiply two vectors and produce a matrix:

- Another way of writing an outer product operation:

Note: These product operations are just special cases of...?

Basic Definitions: Linear and Affine Functions

A function is **linear** if there exist constants such that:

A function is **affine** if there exist constants such that:

Are these functions of affine, linear, or neither?

Line
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er
Affin
e

Matrix Notation for Lists of Functions

- If we have a list of several linear (or affine) functions of , we can "collect" them in matrices to write them in a more compact format:
- More simply, we can write:
- Now we can define terms related to *vector-valued functions*:

A vector-valued function is **linear** if there exists a **constant matrix** such that

A vector-valued function is **affine** if there exists a **constant matrix** and a vector such that