

V: Reader's Guide & Contract Layer (v1.2)

thermodynamic $\Delta S \geq 0$, kinematic $\mathbf{U}^{(4)} = 0$, reciprocity $\mathbf{B}(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V}$, conservation $\nabla \cdot \mathbf{T} = 0$

Verification Tensor (V)

October 13, 2025

Abstract

This note declares the shared *contracts* (G1–G5), an index-free *Numerics Rosetta* for matrix-free Newton–Krylov with a multigrid preconditioner, and a compact *interpretation layer* for physical meaning. All handles are title-safe (`\ensuremath`) and may be used in text, headings, and captions.

Contracts (G1–G5)

- **G1 thermodynamic closure:** $\Delta S \geq 0$.
- **G2 kinematic closure (strong):** $\mathbf{U}^{(4)} = 0$.
- **G2 weak/reciprocity:** $\mathbf{B}(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V}$; summarized by Discrete–continuum reciprocity via \mathbf{B} .
- **G4 conservation (index-free):** $\nabla \cdot \mathbf{J} = 0$; translational case via $\nabla \cdot \mathbf{T} = 0$.
- **G5 statistical invariants:** D_{KL} monotone under admissible coarsegraining and $\mathbb{E}[S] = 0$.

Shared symbols (continuum + statistics)

$\mathbf{U}, \mathbf{V}, \varphi \in \mathcal{V}, \nabla, \mathcal{C}, \mathbf{B}, S, \mathbf{U}^{(4)}, \Xi, \mathbf{N}[L, \mathbf{U}; \Xi], \mathbf{J}, \mathbf{T}, \nabla \mathbf{J}, \mathbb{E}, \text{Var}[\cdot], \hat{\cdot}, \mathcal{S}, \mathcal{I}, D_{\text{KL}}(P \| Q), \text{Inv}[\cdot], R$.

Numerics Rosetta (JFNK + MG, index-free)

Abstract Newton–Krylov with a multigrid preconditioner is referenced via:

$$\mathbf{R}(\mathbf{U}) := \mathbf{U}^{(4)}, \quad \mathbf{J}(\mathbf{U}) v \approx \frac{\mathbf{R}(\mathbf{U} + \varepsilon v) - \mathbf{R}(\mathbf{U})}{\varepsilon}, \quad \delta \mathbf{U} \text{ from } \mathcal{K}[\mathbf{J}, \text{MG}].$$

Discrete alignment (G3) supplies the hierarchy:

$$\Delta_h^{(2)}, \Delta_h^{(4)}, \mathbf{B}_h, \mathbf{R}, \mathbf{P}, S, \text{MG}, h.$$

(Handles only; no stencil/indices are fixed in V.)

Interpretation layer (structure \rightarrow meaning)

- **Coercivity \rightarrow stability:** The symmetric, positive bilinear form \mathbf{B} guarantees existence and uniqueness of the weak solution. Operationally, this implies *stability and well-posedness*: small perturbations in the input or data induce small, predictable changes in the solution.
- **Kernel significance:** The four-dimensional kernel $\text{span}\{1, x, x^2, x^3\}$ represents gauge freedom (position, slope, and constant acceleration) in the absence of external constraints. Fixed nodes together with the natural boundary conditions lock this gauge, ensuring the physical solution \mathbf{U}^* is unique and non-drifting.
- **DPI & irreversibility:** The monotonicity of the KL divergence $D_{\text{KL}}(P\|Q)$ under admissible coarse-graining is the statistical statement of thermodynamic irreversibility. Since measurement is an admissible map of the causal class \mathcal{C} , it can only collapse distinctions; thus predictive power cannot increase merely by running forward in time, cohering with $\Delta S \geq 0$.
- **Discrete \rightarrow continuum stability:** Discrete coercivity and consistency imply convergence (Lax equivalence). Physically, the numerical scheme is stable: finite resolution effects decay under refinement $h \rightarrow 0$, recovering the continuum behavior without spurious modes.

Usage notes (do & don't)

- Use statement handles directly in text: “By $(\mathbf{U}^{(4)} = 0)$ and $(\mathbf{B}(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V}) \dots$ ”
- Avoid `\left...\right` unless both sides are present.
- Do not redeclare \mathcal{V} handles in modules; add local aliases only when necessary.

Smoke test (text-mode safety)

In text: $\mathbf{B}(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V} \Rightarrow \text{IBP} \times 2 \Rightarrow \mathbf{U}^{(4)} = 0$; solve via $\mathbf{J}(\mathbf{U}) \delta \mathbf{U} = -\mathbf{R}(\mathbf{U})$ with $\delta \mathbf{U} = \mathbf{K}[\mathbf{J}, \text{MG}]$; conclude $\nabla \cdot \mathbf{T} = 0$.