

# V: Reader's Guide & Contract Layer (v1.2)

thermodynamic  $\Delta S \geq 0$ , kinematic  $\mathbf{U}^{(4)} = 0$ , reciprocity  $B(\mathbf{U}, \varphi) = 0 \forall \varphi \in \mathcal{V}$ , conservation  $\nabla \cdot \mathbf{T} = 0$

Verification Tensor (V)

October 13, 2025

## Abstract

This note declares the shared *contracts* (G1–G5), an index-free *Numerics Rosetta* for matrix-free Newton–Krylov with a multigrid preconditioner, and a compact *interpretation layer* for physical meaning. All handles are title-safe (`\ensuremath`) and may be used in text, headings, and captions.

## Contracts (G1–G5)

- **G1 thermodynamic closure:**  $\Delta S \geq 0$ .
- **G2 kinematic closure (strong):**  $\mathbf{U}^{(4)} = 0$ .
- **G2 weak/reciprocity:**  $B(\mathbf{U}, \varphi) = 0 \forall \varphi \in \mathcal{V}$ ; summarized by Discrete–continuum reciprocity via  $B$ .
- **G4 conservation (index-free):**  $\nabla \cdot \mathbf{J} = 0$ ; translational case via  $\nabla \cdot \mathbf{T} = 0$ .
- **G5 statistical invariants:**  $D_{KL}$  monotone under admissible coarsegraining and  $\mathbb{E}[S] = 0$ .

## Shared symbols (continuum + statistics)

$\mathbf{U}, \mathbf{V}, \varphi \in \mathcal{V}, \nabla, \mathcal{C}, \mathbf{B}, S, \mathbf{U}^{(4)}, \Xi, N[L, \mathbf{U}; \Xi], \mathbf{J}, \mathbf{T}, \nabla \mathbf{J}, \mathbb{E}, \text{Var}[\cdot], \hat{\cdot}, \mathcal{S}, \mathcal{I}, D_{KL}(P \| Q), \text{Inv}[\cdot], R$ .

## Numerics Rosetta (JFNK + MG, index-free)

Abstract Newton–Krylov with a multigrid preconditioner is referenced via:

$$R(\mathbf{U}) := \mathbf{U}^{(4)}, \quad J(\mathbf{U}) v \approx \frac{R(\mathbf{U} + \varepsilon v) - R(\mathbf{U})}{\varepsilon}, \quad \delta \mathbf{U} \text{ from } K[J, MG].$$

Discrete alignment (G3) supplies the hierarchy:

$$\Delta_h^{(2)}, \Delta_h^{(4)}, B_h, R, P, S, MG, h.$$

(Handles only; no stencil/indices are fixed in V.)

## Interpretation layer (structure → meaning)

- **Coercivity → stability:** The symmetric, positive bilinear form  $B$  guarantees existence and uniqueness of the weak solution. Operationally, this implies *stability and well-posedness*: small perturbations in the input or data induce small, predictable changes in the solution.
- **Kernel significance:** The four-dimensional kernel  $\text{span}\{1, x, x^2, x^3\}$  represents gauge freedom (position, slope, and constant acceleration) in the absence of external constraints. Fixed nodes together with the natural boundary conditions lock this gauge, ensuring the physical solution  $\mathbf{U}^*$  is unique and non-drifting.
- **DPI & irreversibility:** The monotonicity of the KL divergence  $D_{\text{KL}}(P \parallel Q)$  under admissible coarse-graining is the statistical statement of thermodynamic irreversibility. Since measurement is an admissible map of the causal class  $\mathcal{C}$ , it can only collapse distinctions; thus predictive power cannot increase merely by running forward in time, cohering with  $\Delta S \geq 0$ .
- **Discrete → continuum stability:** Discrete coercivity and consistency imply convergence (Lax equivalence). Physically, the numerical scheme is stable: finite resolution effects decay under refinement  $h \rightarrow 0$ , recovering the continuum behavior without spurious modes.

## Usage notes (do & don't)

- Use statement handles directly in text: “By  $(\mathbf{U}^{(4)} = 0)$  and  $(B(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V}) \dots$ ”
- Avoid `\left\dots\right` unless both sides are present.
- Do not redeclare V handles in modules; add local aliases only when necessary.

## Smoke test (text-mode safety)

In text:  $B(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V} \Rightarrow \text{IBP } \times 2 \Rightarrow \mathbf{U}^{(4)} = 0$ ; solve via  $J(\mathbf{U}) \delta \mathbf{U} = -R(\mathbf{U})$  with  $\delta \mathbf{U} = K[J, MG]$ ; conclude  $\nabla \cdot \mathbf{T} = 0$ .