

# V: Reader's Guide & Contract Layer (v1.1)

thermodynamic  $\Delta S \geq 0$ , kinematic  $\mathbf{U}^{(4)} = 0$ , reciprocity  $B(\mathbf{U}, \varphi) = 0 \forall \varphi \in \mathcal{V}$ , conservation  $\nabla \cdot \mathbf{T} = 0$

Verification Tensor (V)

October 13, 2025

## Abstract

This note declares the shared *contracts* (G1–G5) and an index-free *Numerics Rosetta* for matrix-free Newton–Krylov with a multigrid preconditioner. All handles are title-safe (`\ensuremath`) and may be used in text, headings, and captions.

## Contracts (G1–G5)

- **G1 thermodynamic closure:**  $\Delta S \geq 0$ .
- **G2 kinematic closure (strong):**  $\mathbf{U}^{(4)} = 0$  i.e.  $\mathbf{U}^{(4)} = 0$ .
- **G2 weak/reciprocity:**  $B(\mathbf{U}, \varphi) = 0 \forall \varphi \in \mathcal{V}$  i.e.  $B(\mathbf{U}, \varphi) = 0 \forall \varphi \in \mathcal{V}$ ; summarized by Discrete–continuum reciprocity via  $B$ .
- **G4 conservation (index-free):**  $\nabla \cdot \mathbf{J} = 0$ ; translational case via  $\nabla \cdot \mathbf{T} = 0$ .
- **G5 statistical invariants:**  $D_{KL}$  monotone under admissible coarsegraining and  $\mathbb{E}[S] = 0$ .

## Shared symbols (continuum + statistics)

$\mathbf{U}, \mathbf{V}, \varphi \in \mathcal{V}, \nabla, \mathcal{C}, \mathbf{B}, \mathbf{S}, \mathbf{U}^{(4)}, \Xi, \mathbf{N}[L, \mathbf{U}; \Xi], \mathbf{J}, \mathbf{T}, \nabla \mathbf{J}, \mathbb{E}, \text{Var}[\cdot], \hat{\cdot}, \mathcal{S}, \mathcal{I}, D_{KL}(P \| Q), \text{Inv}[\cdot], R$

## Numerics Rosetta (JFNK + MG, index-free)

Abstract Newton–Krylov with a multigrid preconditioner is referenced via:

$$R(\mathbf{U}) := \mathbf{U}^{(4)}, \quad J(\mathbf{U}) v \approx \frac{R(\mathbf{U} + \varepsilon v) - R(\mathbf{U})}{\varepsilon}, \quad \delta \mathbf{U} \text{ from } K[J, MG].$$

Discrete alignment (G3) supplies the hierarchy:

$$\Delta_h^{(2)}, \Delta_h^{(4)}, B_h, R, P, S, MG, h.$$

(Handles only; no stencil/indices are fixed in V.)

## Usage notes (do & don't)

- Use statement handles directly in text: “By  $(\mathbf{U}^{(4)} = 0)$  and  $(B(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V}) \dots$ ”
- Avoid `\left\dots\right` unless both sides are present.
- Do not redeclare V handles in modules; add local aliases only when necessary.

## Smoke test (text-mode safety)

In text:  $B(\mathbf{U}, \varphi) = 0 \ \forall \varphi \in \mathcal{V} \Rightarrow IBP \times 2 \Rightarrow \mathbf{U}^{(4)} = 0$ ; solve via  $J(\mathbf{U}) \delta \mathbf{U} = -R(\mathbf{U})$  with  $\delta \mathbf{U} = K[J, MG]$ ; conclude  $\nabla \cdot \mathbf{T} = 0$ .