# **Minjun Chang**

Department of Mechanical Engineering, Yonsei University, Republic of Korea

E-mail: wkdalswns0427@yonsei.ac.kr Phone: (+82)10-2876-0427

# **Education**

#### Yonsei University, Seoul, Republic of Korea

Mar 2019 - Feb 2025 (Expected)

- B.S., Mechanical Engineering
- GPA: 3.21/4.3
- Senior Thesis: Not Yet

#### **Research Interest**

Robotics, Smart Factory, Autonomous Driving

# **Publications and Conferences**

#### **First Author**

- 1. Hyeongwoo Nam\*, Seoyeon Choi\*, <u>Minjun Chang</u>\*, Joonho Yang\*, Jaehyeon Lim, Jongeun Choi, "State prediction based control input delay compensation for autonomous driving systems", *The 18th Korea Robotics Society Annual Conference (KRoC 2023, Feb. 15-18, 2023)* \*equal contribution
  - Oral presentation in a special session, "Autonomous Driving Robot Racing Technics"

# **Research Experiences**

# Dynamic Robot System Laboratory, Seoul National University

Jul 2024 - Presnet

Undergraduate Intern. Supervisor: Prof. Jaeheung Park

Reinforcement Learning based bipedal locomotion

**Soft Computing Laboratory,** Yonsei University Participating Researcher. Mar 2023 – Aug 2023

Supervisor: Prof. Sungbae Cho

Probabilistic Diffusion-based Signal Augmentation for CNN-Transformer

# Mechanobiology and Soft Materials Laboratory, Yonsei University

Jul 2020 - Jun 2021

Undergraduate Intern. Supervisor: Prof. Hyungseok Lee

Handheld Standing Surface Acoustic Wave(SSAW) Cell Alignment Device

Bridged glass hold design for SSAW cell alignment and simultaneous UV reactive angiogenesis proposal

#### **Biomedical and Energy System Laboratory**, Yonsei University

Dec 2019 - Feb 2020

Undergraduate Intern. Supervisor: Prof. Wonhyung Ryu

Cardiovascular micro stent structure design.

# **Work Experiences**

#### **GOLE Robotics (Robotics Engineer, Path Planning & SLAM)**

Apr 2024 - Jun 2024

- Global(A\*) and Local(sMPC) Path Planning algorithm implementation on ROS2 Humble environment and real-world robot
- Prediction based LiDAR Localization model development
- Robot controller package python-binding

**DRIMAES (Embedded Software Engineer, Research Engineer)** 

Oct 2022 - Mar 2024

- Linux, ARM MCU SW&FW programming, Communication(Serial, MQTT, REST, CAN)
- Container management, Integration with robotic system(HD Hyundai Robotics)

# ToysMyth (Embedded Software Engineer, Research Engineer)

Feb 2022 - Oct 2022

- Embedded Software for Mediatek, ESP chipsets, OpenWRT OS kernel
- \* for fulfillment of military service

### Alsemy (Al Lab Intern, Intern)

Jun 2021 - Oct 2021

- Data Smoothness Verification metric development
- \* Yonsei Summer Startup internship program

# **Project Experiences**

Cartrasche: Autonomous Human Following Manufacture Assistant	Mar 2024 –Jun 2024
<ul> <li>https://github.com/Cartrasche-CreativeProductDesign</li> </ul>	
Leafeon Cluster: Indoor Atmospheric Environment Observer	Feb 2023 –Sep 2023
<ul> <li>https://github.com/wkdalswns0427/LeafeonIOTProject</li> </ul>	
FennecBot: Industrial Anomaly Detection Mobile Robot	Mar 2023 – Aug 2023
• https://universe.roboflow.com/fennecbot-yonsei/fennecbot-yonsei	
Eye Tuner: A Personalized Digital Contents Reading Assistant	Mar 2022 – Dec 2022
• https://github.com/Eye-Tuner/Eye-Tuner	
SAJOGI: Boston Dynamics Spot Micro project	May 2022 – Nov 2022
<ul> <li>https://github.com/wkdalswns0427/SpotMicro_SAJOGI</li> </ul>	
MRI Spine Inage Segmentation with Unet:	Oct 2021 – Dec 2021

https://github.com/wkdalswns0427/Spine-Segmentation-with-Pytorch-Modified-UNet

# Compensation Box(funded by CJ EnM)

Dec 2020 - Jan 2021

https://www.youtube.com/watch?v=bn3E7PXLIBw

# **Extracurricular Activities and Leadership**

Bit	Crab, Embedded SW group, Yonsei University	Mar 2022 – Present
•	Digital Sessions (2 <sup>nd</sup> )	
YAI	Artificial Intelligence Club, Yonsei University	Mar 2022 – Present
•	Research Member (9th)	
Rol	oin, Robotics Club, Yonsei University	May 2020 – Present
•	President, Vice President (2021,2022)	

# **Honors and Awards**

1st place, 2022 Autonomous Driving Robot Racing Contest	Nov 2022
Selection, Hanium Contest	Nov 2021
2 <sup>nd</sup> place, Medical Hack 2021	Oct 2021
Impact Solution Award, Yonsei IHEI Workstation (Team: Vision Catcher, Leader)	Jul 2021
2 <sup>nd</sup> place, KU Medical Hackathon	Nov 2020
6 <sup>th</sup> place, EDISON CAD Competition	Aug 2020
2 <sup>nd</sup> place, Yonsei IHEI Workstation (Team: ACUOUS, Member)	Jul 2020

<sup>\*</sup> for fulfillment of military service

# **Patent**

Patent application number: KR 10-2020-0176792 (under patent prosecution)	Nov 2023	
Software Copyrights		
<b>Eye Tuner:</b> Media Literacy Program based on Pupil Tracking by Computer Vision Korea Copyright Commission (C-2021-050308)	Nov 2021	
Licenses		
Engineer Information Processing, HRDK	Sep 2023	
Pilot of an Ultra-Light Vehicle, Korea Transportation Safety Authority	Nov 2021	
Advanced Diver, PADI	May 2016	
Underwater Diver, PADI	Mar 2015	
Skills Summary		

Languages: Korean (Native), English (Fluent, iBT TOEFL 103 / exp Oct 2025)

**Programming Languages**: Python, C/C++, MATLAB

Frameworks/Tools: ROS(Noetic, Humble), Docker, PyTorch, FastAPI, MySQL, COMSOL, Solidworks

ETC: Linux, Robotics, MCU(ATMega, ESP32, STM32), Embedded Software, Communication, CAD