Weight Uncertainty in Neural Networks

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기존 Neural Network

- Overfitting
- Uncertainty를 반영하지 못한다.

• 새로운 Neural Network 제시

Bayes by Backprop(BBB)

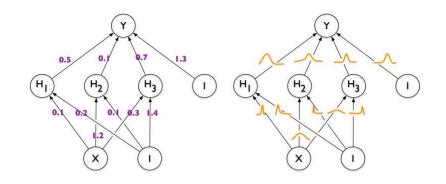


Figure 1. Left: each weight has a fixed value, as provided by classical backpropagation. Right: each weight is assigned a distribution, as provided by Bayes by Backprop.

- 각 weight는 하나의 값이 아닌 하나의 분포 를 갖는다.
- Parameter 수를 2배로 늘리면서 무한개의 ensemble 효과를 얻을 수 있다.

● Data에 대한 uncertainty를 얻을 수 있다.

Maximum likelihood estimation(MLE)

$$\begin{split} w^{MLE} &= \arg\max_{w} \log P(D|w) \\ &= \arg\max_{w} \sum_{i=1}^{N} \log P(y_{i}|\mathbf{x}_{i}, \mathbf{w}) = \arg\max_{w} \sum_{i=1}^{N} \log \frac{1}{\sqrt{2\pi\sigma^{2}}} \exp\left(-\frac{(y_{i} - f_{\mathbf{w}}(\mathbf{x}_{i}))^{2}}{2\sigma^{2}}\right) \\ &= \arg\max_{w} \sum_{i=1}^{N} \left(-\frac{(y_{i} - f_{\mathbf{w}}(\mathbf{x}_{i}))^{2}}{2\sigma^{2}}\right) \\ &= \arg\min_{w} \sum_{i=1}^{N} (y_{i} - f_{\mathbf{w}}(\mathbf{x}_{i}))^{2} \end{split}$$

$P(w|D) = \frac{P(D|w)P(w)}{\int P(D|w)P(w)dw}$

Maximum A Posterior(MAP)

$$\begin{split} w^{MAP} &= \arg\max_{w} \log P(D|w) + \log P(w) \qquad (P(w) \sim N(0, \sigma_{w}^{2})) \\ &= \arg\max_{w} \sum_{i=1}^{N} \log \frac{1}{\sqrt{2\pi\sigma^{2}}} \exp\left(-\frac{(y_{i} - f_{w}(x_{i}))^{2}}{2\sigma^{2}}\right) + \log \frac{1}{\sqrt{2\pi\sigma_{w}^{2}}} \exp\left(-\frac{(w)^{2}}{2\sigma_{w}^{2}}\right) \\ &= \arg\max_{w} \sum_{i=1}^{N} \left(-\frac{(y_{i} - f_{w}(x_{i}))^{2}}{2\sigma^{2}}\right) + -\frac{(w)^{2}}{2\sigma_{w}^{2}} \\ &= \arg\min_{w} \sum_{i=1}^{N} (y_{i} - f_{w}(x_{i}))^{2} + w^{2} \end{split}$$

Being Bayesian by Backpropagation

Bayesian Neural Network에서 사용하는 방법은 무엇인가?

Posterior(P(w|D)) 분포를 구해서 unknown X에 대한 unknown label y의 기댓값을 구하자

-> 무수히 많은 network 앙상블 시킨 효과

$$P(\hat{\mathbf{y}}|\hat{\mathbf{x}}) = \mathbb{E}_{P(\mathbf{w}|\mathcal{D})}[P(\hat{\mathbf{y}}|\hat{\mathbf{x}},\mathbf{w})]$$

문제점

Posterior를 구하는 것이 intractable하다.

$$p(w|D) = \underbrace{\frac{p(D|w)p(w)}{\int p(D|w)p(w)dw}}_{\text{DE w}} \longrightarrow \underbrace{\frac{p(D|w)p(w)dw}{\text{LE w}}}_{\text{UH W}} + \underbrace{\frac{p(D|w)p(w)dw}{\text{LE w}}}_{\text{UH W}}$$

Variational inference 사용

Variational inference $q(w|\theta) \sim p(w|D)$

$$\theta^* = \arg\min_{\theta} \text{KL}[q(\mathbf{w}|\theta)||P(\mathbf{w}|\mathcal{D})]$$

$$= \arg\min_{\theta} \int q(\mathbf{w}|\theta) \log \frac{q(\mathbf{w}|\theta)}{P(\mathbf{w})P(\mathcal{D}|\mathbf{w})} d\mathbf{w}$$

$$= \arg\min_{\theta} \text{KL}[q(\mathbf{w}|\theta)||P(\mathbf{w})] - \mathbb{E}_{q(\mathbf{w}|\theta)}[\log P(\mathcal{D}|\mathbf{w})]$$

$$\begin{split} \mathcal{F}(\mathcal{D}, \theta) &= \mathrm{KL}\left[q(\mathbf{w}|\theta) \mid\mid P(\mathbf{w})\right] <\text{- Complexity cost} \\ & \mathrm{Likelihood cost} \to -\mathbb{E}_{q(\mathbf{w}|\theta)}\left[\log P(\mathcal{D}|\mathbf{w})\right]. \end{split}$$

= ELBO/ variational free energy

 $q(w|\theta)$ = variational inference

P(w): prior

P(D|w): likelihood

Optimization

LOSS:
$$\mathcal{F}(\mathcal{D}, \theta) \approx \sum_{i=1}^{n} \log q(\mathbf{w}^{(i)}|\theta) - \log P(\mathbf{w}^{(i)})$$
$$-\log P(\mathcal{D}|\mathbf{w}^{(i)})$$

 $w^i = i \ th$ Monte Carlo random sample from $q(w^i | \theta)$

$$\theta = (\mu, \rho),$$
 $\sigma = \log(1 + \exp(\rho))$
 $w = \mu + \sigma \cdot \varepsilon$ $\varepsilon \sim N(0,1)$

• : pointwise multiplication

Optimization

Sample
$$\epsilon \sim \mathcal{N}(0, I)$$
.
Let $\mathbf{w} = \mu + \log(1 + \exp(\rho)) \circ \epsilon$.
Let $\theta = (\mu, \rho)$.
Let $f(\mathbf{w}, \theta) = \log q(\mathbf{w}|\theta) - \log P(\mathbf{w})P(\mathcal{D}|\mathbf{w})$

Update the variational parameters:

$$\mu \leftarrow \mu - \alpha \Delta_{\mu}$$
$$\rho \leftarrow \rho - \alpha \Delta_{\rho}.$$

Scale mixture prior

$$P(\mathbf{w}) = \prod_{j} \pi \mathcal{N}(\mathbf{w}_{j}|0, \sigma_{1}^{2}) + (1 - \pi)\mathcal{N}(\mathbf{w}_{j}|0, \sigma_{2}^{2}), \quad \sigma_{1} > \sigma_{2}$$

$$\sigma_{2} << 1$$

 π , σ 1, σ 2: hyperparameter

Gaussian 2개 더함 -> more uncertainty

Minibatches and KL re-weighting

2.
$$\mathcal{F}_{i}^{\pi}(\mathcal{D}_{i}, \theta) = \pi_{i} \text{KL} \left[q(\mathbf{w}|\theta) \mid\mid P(\mathbf{w}) \right] - \mathbb{E}_{q(\mathbf{w}|\theta)} \left[\log P(\mathcal{D}_{i}|\mathbf{w}) \right] \qquad \mathbb{E}_{M}[\sum_{i=1}^{M} \mathcal{F}_{i}^{\pi}(\mathcal{D}_{i}, \theta)] = \mathcal{F}(\mathcal{D}, \theta)$$

$$\pi \in [0,1]^M$$
 $\pi_i = \frac{2^{M-i}}{2^{M}-1}$ $\sum_{i=1}^M \pi_i = 1$

정리

- Posterior(P(w|D)) 분포를 구해서 unknown X에 대한 unknown label y의 기댓값을 구하자
- Posterior 구하기 힘들다
- -> variational inference $q(w|\theta) \sim p(w|D)$
- $q(w|\theta)$ 와 p(w|D)사이 거리를 줄이자
- Sampling을 통해 loss 구하자
- Minibatch loss
- μ , σ update
- Prior: scale mixture prior

$$P(\hat{\mathbf{y}}|\hat{\mathbf{x}}) = \mathbb{E}_{P(\mathbf{w}|\mathcal{D})}[P(\hat{\mathbf{y}}|\hat{\mathbf{x}},\mathbf{w})]$$

$$p(w|D) = \frac{p(D|w)p(w)}{\int p(D|w)p(w)dw}$$

$$\arg\min_{\theta} \mathrm{KL}[q(\mathbf{w}|\theta)||P(\mathbf{w}|\mathcal{D})]$$

$$w = \mu + \sigma \circ \varepsilon$$
, $\varepsilon \sim N(0,1)$

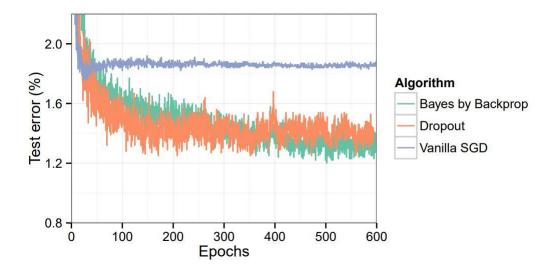
$$\mathcal{F}_{i}^{\pi}(\mathcal{D}_{i}, \theta) = \pi_{i} \text{KL} \left[q(\mathbf{w}|\theta) \mid\mid P(\mathbf{w}) \right] - \mathbb{E}_{q(\mathbf{w}|\theta)} \left[\log P(\mathcal{D}_{i}|\mathbf{w}) \right]$$

$$P(\mathbf{w}) = \prod_{j} \pi \mathcal{N}(\mathbf{w}_{j}|0, \sigma_{1}^{2}) + (1 - \pi)\mathcal{N}(\mathbf{w}_{j}|0, \sigma_{2}^{2})$$

Experiments

Table 1. Classification Error Rates on MNIST. ★ indicates result used an ensemble of 5 networks.

| Method | # Units/Layer | # Weights | Test Error |
|--|---------------|-----------|-----------------|
| SGD, no regularisation (Simard et al., 2003) | 800 | 1.3m | 1.6% |
| SGD, dropout (Hinton et al., 2012) | | | $\approx 1.3\%$ |
| SGD, dropconnect (Wan et al., 2013) | 800 | 1.3m | $1.2\%^{\star}$ |
| SGD | 400 | 500k | 1.83% |
| | 800 | 1.3m | 1.84% |
| | 1200 | 2.4m | 1.88% |
| SGD, dropout | 400 | 500k | 1.51% |
| | 800 | 1.3m | 1.33% |
| | 1200 | 2.4m | 1.36% |
| Bayes by Backprop, Gaussian | 400 | 500k | 1.82% |
| | 800 | 1.3m | 1.99% |
| | 1200 | 2.4m | 2.04% |
| Bayes by Backprop, Scale mixture | 400 | 500k | 1.36% |
| | 800 | 1.3m | 1.34% |
| | 1200 | 2.4m | 1.32 % |



Experiments

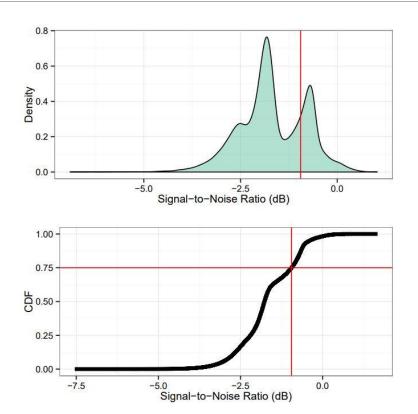


Figure 4. Density and CDF of the Signal-to-Noise ratio over all weights in the network. The red line denotes the 75% cut-off.

Table 2. Classification Errors after Weight pruning

| Proportion removed | # Weights | Test Error |
|---------------------------|-----------|------------|
| 0% | 2.4m | 1.24% |
| 50% | 1.2m | 1.24% |
| 75% | 600k | 1.24% |
| 95% | 120k | 1.29% |
| 98% | 48k | 1.39% |

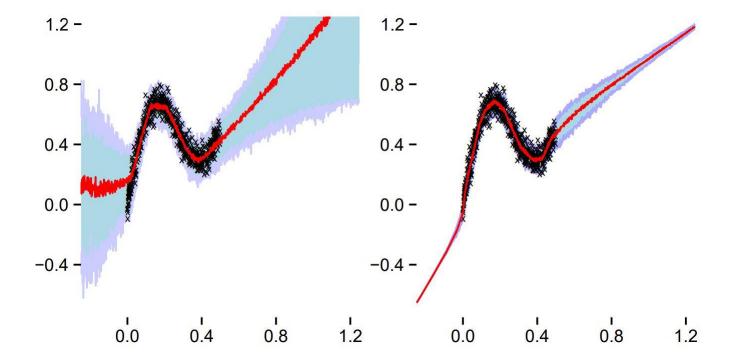
2 layers of 1200 units

Weight마다 signal-to-noise ratio (|µi |/ơi)를 계산해서 작은 것부터 지움 (posterior를 0으로 설정)

-> pruning을 통해 더 가벼운 모델로 만들 수 있음

Experiments

$$y = x + 0.3\sin(2\pi(x+\epsilon)) + 0.3\sin(4\pi(x+\epsilon)) + \epsilon$$



$$\epsilon \sim \mathcal{N}(0, 0.02)$$

왼쪽: Bayesian 오른쪽: Ordinary

Black: data

Red: median predictions

Blue/purple: interquartile range