WEIYU LIU

weiyuliu.com

wliu88@gatech.edu

RESEARCH INTEREST

My research focuses on semantic reasoning for robotics, including leveraging knowledge extraction, representation, and reasoning to facilitate robotic operations in diverse real-world environments.

2017 - Present

EDUCATION

Ph.D. in Robotics
Advisor: Sonia Chernova

Georgia Institute of Technology, Atlanta, GA

Bachelor of Science, Electrical Engineering with Distinction
GPA: 3.96

RESEARCH EXPERIENCE

Georgia Institute of Technology, Atlanta, GA

Georgia Institute of Technology, Atlanta, GA Graduate Research Assistant	2017 – Present
Georgia Institute of Technology, Atlanta, GA Undergraduate research with Prof. Sonia Chernova	2016 - 2017
Georgia Institute of Technology, Atlanta, GA Undergraduate research with Prof. Fumin Zhang	2014 - 2016

PUBLICATIONS

Preprints

- A Survey of Semantic Reasoning Frameworks for Robotic Systems
 Weiyu Liu, Angel Daruna, and Sonia Chernova.
 Under review, Robotics and Autonomous Systems (RAS), 2020
- Leveraging Semantics for Incremental Learning in Multi-Relational Embeddings Angel Daruna, Weiyu Liu, Zsolt Kira, and Sonia Chernova. arXiv, 2019

Conference and Journal Papers

- Same Object, Different Grasps: Data and Semantic Knowledge for Task-Oriented Grasping Adithya Murali, Weiyu Liu, Kenneth Marino, Sonia Chernova, and Abhinav Gupta. Conference on Robot Learning (CoRL), 2020
- CAGE: Context-Aware Grasping Engine Weiyu Liu, Angel Daruna, and Sonia Chernova. International Conference on Robotics and Automation (ICRA), 2020.
- Path Ranking with Attention to Type Hierarchies

Weiyu Liu, Angel Daruna, Zsolt Kira, and Sonia Chernova. Conference on Artificial Intelligence (AAAI), 2020.

• Taking Recoveries to Task: Recovery-Driven Development for Recipe-based Robot Tasks Siddhartha Banerjee, Angel Daruna, David Kent, **Weiyu Liu**, Jonathan Balloch, Abhinav Jain, Akshay Krishnan, Muhammad Asif Rana, Harish Ravichandar, Binit Shah, Nithin Shrivatsav, and Sonia Chernova.

International Symposium on Robotics Research (ISRR), 2019.

Autonomous flying blimp interaction with human in an indoor space
 Ningshi Yao, Qiuyang Tao, Weiyu Liu, Zhen Liu, Ye Tian, Peiyu Wang, Timothy Li, and Fumin Zhang.

• RoboCSE: Robot Common Sense Embedding Angel Daruna, **Weiyu Liu**, Zsolt Kira, and Sonia Chernova.

Frontiers of Information Technology & Electronic Engineering, 20, 2019.

International Conference on Robotics and Automation (ICRA), 2018.

• SiRoK: Situated Robot Knowledge - Understanding the Balance Between Situated Knowledge and Variability

Sonia Chernova, Vivian Chu, Angel Daruna, Haley Garrison, Meera Hahn, Priyanka Khante, **Weiyu** Liu, and Andrea Thomaz.

AAAI Spring Symposium Series (AAAI-SSS), 2018.

• Situated Bayesian Reasoning Framework for Robots Operating in Diverse Everyday Environments Sonia Chernova, Vivian Chu, Angel Daruna, Haley Garrison, Meera Hahn, Priyanka Khante, **Weiyu Liu**, and Andrea Thomaz.

International Symposium on Robotics Research (ISRR), 2017.

Teaching Experience

Georgia Institute of Technology, Atlanta, GA Spring 2018

Graduate Teaching Assistant

CS 3630 Introduction to Robotics and Perception, Instructor: Prof. Sonia Chernova

Georgia Institute of Technology, Atlanta, GA

Fall 2014

Peer Tutor

Learning Assistance Program, Best Tutor Award

LEADERSHIP and PROFESSIONAL SERVICE

Georgia Institute of Technology, Vice President Academic, RoboGrads

Reviewer: ICRA, RA-L

2019 – 2020

2019 – 2020

AWARDS and HONORS

Fetch it! The Mobile Manipulation Challenge, First Place

Georgia Institute of Technology, Dean's List

2019
2019