

Will Clingan
CIS 657, Midterm
Dr. Mo
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#Q1

```
/* xsh_create.c - xsh_create */
```

```
#include <xinu.h>
```

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <string.h>
```

```
extern process runforever(void);
```

```
/*-----  
 * xsh_create - Shell command to create a new process. *  
 *-----  
*/
```

```
shellcmd xsh_create(int nargs, char *args[]) {
```

```
    int priority;
```

```
    pid32 pid;
```

```
    /* Print help menu and system utilization. */
```

```
    if (nargs == 2 && strcmp(args[1], "--help") == 0) {
```

```
        printf("Usage: create <priority>\n");
```

```
        printf("Creates a new process at the specified priority which loops forever.\n");
```

```
        printf("If priority is less than 20, a warning will be displayed.\n");
```

```
        printf("If priority is less than 10, the process may make the shell unresponsive.
```

```
\n");
```

```
        return 0;
```

```
    }
```

```
    if (nargs != 2) {
```

```
        fprintf(stderr, "Usage: create <priority>\n");
```

```
        return 1;
```

```
    }
```

```
    /* Validate user input. */
```

```
    priority = atoi(args[1]);
```

```
    if (priority <= 0) {
```

```
        fprintf(stderr, "Invalid priority: %s\n", args[1]);
```

```
        return 1;
```

```
    }
```

```
    /* Prompt user w/ WARNING respective of process' priority. */
```

```

    if (priority < 20 && priority >= 10) {
        printf("WARNING: Priority values lower than 20 are typically reserved for
shell/system processes.\n");
        printf("        Creating a user process at this priority may interfere with shell
responsiveness.\n");
    }
    if (priority < 10) {
        printf("WARNING: Priority values lower than 10 are reserved for critical system
processes.\n");
        printf("        Creating a user process at this priority may make the shell or
system unresponsive.\n");
    }

    /* Create a process that prints its PID and loops forever */
    pid = create(runforever, 1024, priority, "runforever", 0);
    if (pid == SYSERR) {
        fprintf(stderr, "Failed to create process.\n");
        return 1;
    }
    resume(pid);
    printf("Created process with PID %d at priority %d\n", pid, priority);

    return 0;
}

```

#Q2

```

/* xsh_createsleep.c - xsh_createsleep */

#include <xinu.h>
extern process runafterwait(void);

/*-----
 * xsh_createsleep - Shell command to sleep a process. *
 *-----
 */

shellcmd xsh_createsleep(int nargs, char *args[]) {
    int prio = 20;
    if (nargs == 2) {
        prio = atoi(args[1]);
    }
    resume(create((void *)runafterwait, 1024, prio, "runafterwait", 0));
    return 0;
}

```

#Q3

```
/* xsh_psready.c - xsh_psready */

#include <xinu.h>

/*-----
 * xsh_psready - Shell command to print the PID Table. *
 *-----
 */

shellcmd xsh_psready(int nargs, char *args[]) {
    int32 i;
    struct procent *prptr;

    kprintf("Ready Processes:\n");
    kprintf("%-10s %-10s %-10s\n", "PID", "State", "Priority");
    for (i = 0; i < NPROC; i++) {
        prptr = &proctab[i];
        if (prptr->prstate == PR_READY) {
            kprintf("%-10d %-10s %-10d\n", i, "READY", prptr->prprio);
        }
    }
    return 0;
}
```

#Q4

```
/* xsh_wait.c - xsh_wait */

#include <xinu.h>
extern sid32 globalsemaphore;
extern process waiter(void);

/*-----
 * xsh_wait - Shell command to put a process into the wait pattern. *
 *-----
 */

shellcmd xsh_wait(int nargs, char *args[]) {
    resume(create((void *)waiter, 1024, 20, "waiter", 0));
    return 0;
}
```

#Q5:

```
/* xsh_signaln.c - xsh_signaln */
```

```

#include <xinu.h>
extern pid32 globalsemaphore;

/*-----
 * xsh_signaln - Shell command to signal a semaphore. *
 *-----
 */

shellcmd xsh_signaln(int nargs, char *args[]) {
    int n = 1;
    if (nargs == 2) {
        n = atoi(args[1]);
    }
    signaln(globalsemaphore, n);
    kprintf("Signaled semaphore %d times\n", n);
    return 0;
}

```

#Q6

```

/* xsh_resumen.c - xsh_resumen */

#include <xinu.h>

/*-----
 * xsh_resumen - Shell command to resume process. *
 *-----
 */

shellcmd xsh_resumen(int nargs, char *args[]) {
    int i;
    pid32 maxprio_pid = -1;
    int maxprio = -1;
    struct procent *prptr;

    if (nargs < 2) {
        kprintf("Usage: resumen <pid1> <pid2> ...\n");
        return 1;
    }

    for (i = 1; i < nargs; i++) {
        pid32 pid = atoi(args[i]);
        prptr = &proctab[pid];
        if (prptr->prprio > maxprio) {
            maxprio = prptr->prprio;
            maxprio_pid = pid;
        }
    }
}

```

```
    resume(pid);  
}
```

```
    if (maxprio_pid != -1 && proctab[maxprio_pid].prstate == PR_READY) {  
        resched();  
    }  
    return 0;  
}
```