# The interest of single-sensor ultrasound imaging

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Abstract—This document is a model and instructions for LaTeX. This and the IEEEtran.cls file define the components of your paper [title, text, heads, etc.]. \*CRITICAL: Do Not Use Symbols, Special Characters, Footnotes, or Math in Paper Title or Abstract.

Index Terms—ultrasound imaging, open source, hardware, ultrasound

## I. INTRODUCTION

Previous work was done on an arduino-like approach [1].

#### A. Ultrasound as part of medical imaging

Ultrasound is:

\* cost-efficiency. Signal generation uses a piezoelectric material, requiring much less than setting up for example a large magnetic field for an MRI scan. \* relatively safe: as there are no ionizing radiation, ultrasound devices do not need special safety equipment like shields, or expensive supplies. \* light: on the sense that compared to other imaging modalities, devices can be made relatively portable \* dynamic

See Kurjak

## B. Open source medical hardware

Open hardware lowers some barriers: having a full design under an open-source license provides the key to all to contribute and improve a design. This in turns allows a possible rapid spread of the design, customisation for specific uses, and ad-hoc modification. A design being open means that a higher number of contributors can help inspect and improve it.

Repairs are also easier with the code, with several types of impact (social, environmental and economics) that enhance the lifecycle of a product.

The open source movement has been facilitated by the numerous platforms and communication means, that allow these designs to be copied, but also for robust storage and distribution means.

[2]

Open source hardware can be a disruptive tool on the medical device market. Of course, a caveat has to be made on the non-certification of most of these devices, which in turn would hint at open-source being a major tool in innovation, leaving the industrialisation of such devices to professionals. Shorter development cycles, even for hardware, with open source permits quick iterations over a product.

A study by Niezen [2] lists a selection of open-source medical projects. Most are working with Arduino or Raspberry Pi, showing the importance of existing projects and the way open-source allows for reuse of previous projects. Dedicated hardware is developed for this project, leaving the specifics of the project to be developed by the contributor.

#### II. ULTRASOUND IMAGING

Α

## III. A-MODE IMAGING

This modality can be used for example in image free systems for evaluation of vascular stiffness. [3]

Probes [4] Systems

but these have not been open-sourced.

#### IV. ACQUISITION MODALITIES

## A. Pulse echo

1) NDE: [5] presents a very interesting design for single element FPGA-based NDE design. It migrates traditionally analog functions, like filtering and envelope extraction to the digital domain, as well as includes an EMI filteR. An interesting data compression scheme is also presented.

## B. Compressed sensing

Traditional 2-D and 3D ultrasound require the use of hundreds of delicates sensors, with matching hardware.

Ultrasound 2D arrays, or matrices, have developed available, however this also require more hardware (AFE, ADC units, cabling, etc..) and hence become more complex and expensive to produce, and require heavy data processing.

@todo add [?] thesis

It appears that classical sampling is challenged by the signal processing "compressive sensing" field. This shows that most signals have a sparse representation - a finite sparse signal can be reconstructed from a small set of linear, non-adaptive measurements.

The recent development of compressive sensing shows that one can encode individual voxels through a 'chaotic' intermediary (eg a lense), and allows to design simple ultrasound imaging equipment that can provide 3D imaging using a single-element ultrasound sensor.

Imaging is then offloaded to the processing domain supported by constantly growing electronic devices' capabilities (memory, GPU's). This open doors to simpler hardware - and new applications [6].

[7]

#### C. Time reversal focusing

@adapt N.Etaix et.al [19] presented an idea of a low-profile acoustic imaging device with only one transmit/receive element. According to the theory, if the medium is reciprocal and the channels impulse response is known, the latter can be re-emitted in time-reversed order. Mathematically, this results in the response auto-convolution [20]. Knowing that the auto-convolution has a peak in the origin, focusing is effectively achieved. The time reversal result is equivalent to matched filtering energy maximization at the desired location in space and time.

## D. Basics for US machine

1) specs from who: ref kurjak

In 1986, the specifications for a General Purpose Ultrasound Scanner were as follows:

- Have linear and sector types - Frequency of interest is 3.5MHz, possibly extensible to 5MHz. - Sector angle of 40 degrees or more - Depth of 18cm - rate of 5 to 10Hz for sector scanning - image to be frozen, displayed on a 512x512 image on 4 bits.

Minimal specifications for hardware can be infered:

- An ADC at at least 10MHz, running on 8bits - 18cm means 240us per acquisition, or 2400 points at 10Msps. Details can be around 0.5mm, that's then 480 points per line. Let's consider 512 for the image size. - Let's consider 60 degree. To have a 1mm resolution at 18cm means 180 lines per image, which will be fed into the 512x512 image. However, given the size of the image and characterics of the piezo, it seems reasonable to have 60 lines over 40 degrees. - Raw images are then 60x512x8bits, that's a memory of 30kB+ before scan conversion. - 60 lines of 240us means 14ms ofr an image, capping the framerate to close to 70fps - seems fine. However, mechanical overheads reduce this figure.

2) key figures:

#### E. Use case

Even if relatively simple, the A-mode enables not imaging, but rather measurements, enabling the examination of paranasal sinuses, transkull fluid detection, sinus pathology, skeletal muscle detection in the guided wrist extension, automatic measurement of lumen diameter of carotid artery [8], or bone porosit [9].

F. Results

G. Tomorgraphy

[10]

H. Use case

1) Sleep Apnea: [?]

#### V. B-MODE IMAGING

- A. Basics for US machine
  - 1) specs from who:
  - 2) key figures:

#### B. Architecture

Configurable hardware makes the system resilient to future changes. Beyond this hardware designs can be adjusted without reprinting the circuit board.

FPGAs improve the ability for ultrasound imaging systems to create small form factor and high-performance products with reduced power consumption [11]. In the latter case, it enables the control of a 8 channels platform.

Others use an additional microcontroler is set up between the FPGA and the USB and provide configuration on the fly, providing access to the platform through Matlab. It can interface to an array using several Octal Ultrasound ADC/LNA/VGA/AAF (AD9272) [12], [13].

## C. 2D imaging ..

1) Sweeping means: mechanical sweeping example [14].

One would note however, that for power-uses, plane wave imaging, made possible because of GPUs [15], would limit the formation of an image to a single pulse/receive event.

With high frequency transducers (c. 50 MHz), imaging transducers are relatively smaller, which makes mechanical scanning a great solution. This implies however strong positionning control and motors [4]. In this article, a piezoelectric motor is used in conjunction with an optical encoder.

2) Arrays: However, the need heavier setup, for example to use up to 128 channels setups [16].

## D. MSAS/MFFS

[17]

[18]

In 1974, [19] showed that using a synthetic aperture design as an hybrid between holography and B scan offers a higher lateral resolution as well as better detection of tilted specular reflectors.

## E. Use case

1) Ultrasound capsule: Swallowable capsule: capsule endoscopy using high frequency microultrasound (US). This is a great example of miniaturisation fitting all in a 10 mm diameter 30 mm long capsule, with all the constraints discussed above [20].

further develops mechanics used in such a capsule [21].

2) Fingers movement: [22]

#### F. Results

#### G. To go further

[23] proposes a design usable on a smartphone, connected through USB. Plane-wave acquisition, mentioned earlier [15] also enables smarter captures.

Proof of concept for a portalbe 32-channel ultrasound unit [24]

#### VI. DOCUMENTATION

#### A. Why documenting

Open source = documentation

#### B. How to document

On this project, a set of documenting tools was created. Documentation is based on the constitution of a project body of knowledge, which consists in code files, documentation files, images, and other files being tagged with structured information.

The concept used has been to store information only once, and closest to the source of the documentation. The main objective is to avoid redundancy and to allow for tracking outdated information, for elimination.

Tags cover for example date and time, type of file, experiment related to the file, probes being used, description of the file, author, ... "Template files", that have "includes" of parts of documentation, also dynamically generate files.

This way, a script parses the whole, possibly unstructured repository and builds a body of knowledge, which in turn is used to generate static pages, that can cover:

- List of experiment and descriptions - List of probes - List of modules - Jupyter notebooks - Readme pages

The structured data and produced static pages are also pushed on a gitbook, so that documentation is easily accessible and searchable. Even Jupyter notebooks are converted to markdown for ease of browsing.

Moreover, a worklog is used to generate a lab-log of research, published on a github-page structure. Presentations are dynamically generated as well from markdown files, and a log of the documentation compilation is generated, tracking broken links, unused/unreferenced files, and untagged documents.

C. Results

## VII. BYPRODUCTS

#### A. ADCs

For such an analog signal processing project, a Digital Acquisition (DAQ) tool was required. Most AFEs do include ADCs, but starting from scratch required efficient and fast ADCs.

However, due to the speed of acquisition higher than raw data throughput exceed a around 230MB/s, real time was never really achieved and corresponding storage buffer was needed. Several options where explored, including using a BeagleBone Black DAQ at 40Msps, a STM32 onboard DAQ up to 7.2Msps. Finally, the choice was to develop a high-speed acquisition extension for a omnipresent raspberry pi.

The limitation of the raspberry pi meant that the duration of captures was limited, and that acquisition was limited to around 22Msps, being the rate to which GPIO state was copied to memory.

Interestingly enough, such a polyvalent byproduct was deemed of interest by some researchers.

B. phantoms

[25] from SPAM

C. Suppliers

## D. Materials

On most designs, an acoustic window is needed to seal the scanhead while minimizing signal loss.

An oftne used material is the TPX (polymethylpentene), used for example on an hand-held high frequency ultrasound scanner [26] or on another bimorph design [27]. In the latter, the scanhead is located inside a 3D printed plastic probe housing and filled with de-ionized water.

## VIII. OPEN SOURCE HARDWARE COMMUNITY

A. Hackaday

B. ice40

C. Business-like

- 1) Certification:
- 2) Tindie:

#### D. Slack

Communication is key for open-source projects. Part of it goes through documentation, which enables the constitution of an asynchronous base of knowledge.

However, real-time chat tools, such as slack, is useful for real time interactions, calls around a community, ...

#### IX. EASE OF USE

## A. Maintaining the Integrity of the Specifications

The IEEEtran class file is used to format your paper and style the text. All margins, column widths, line spaces, and text fonts are prescribed; please do not alter them. You may note peculiarities. For example, the head margin measures proportionately more than is customary. This measurement and others are deliberate, using specifications that anticipate your paper as one part of the entire proceedings, and not as an independent document. Please do not revise any of the current designations.

#### X. PREPARE YOUR PAPER BEFORE STYLING

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Keep your text and graphic files separate until after the text has been formatted and styled. Do not number text heads— LATEX will do that for you.

#### A. Abbreviations and Acronyms

Define abbreviations and acronyms the first time they are used in the text, even after they have been defined in the abstract. Abbreviations such as IEEE, SI, MKS, CGS, ac, dc, and rms do not have to be defined. Do not use abbreviations in the title or heads unless they are unavoidable.

#### B. Units

- Use either SI (MKS) or CGS as primary units. (SI units are encouraged.) English units may be used as secondary units (in parentheses). An exception would be the use of English units as identifiers in trade, such as "3.5-inch disk drive".
- Avoid combining SI and CGS units, such as current in amperes and magnetic field in oersteds. This often leads to confusion because equations do not balance dimensionally. If you must use mixed units, clearly state the units for each quantity that you use in an equation.
- Do not mix complete spellings and abbreviations of units: "Wb/m²" or "webers per square meter", not "webers/m²".
   Spell out units when they appear in text: ". . . a few henries", not ". . . a few H".
- Use a zero before decimal points: "0.25", not ".25". Use "cm<sup>3</sup>", not "cc".)

## C. Equations

Number equations consecutively. To make your equations more compact, you may use the solidus ( / ), the exp function, or appropriate exponents. Italicize Roman symbols for quantities and variables, but not Greek symbols. Use a long dash rather than a hyphen for a minus sign. Punctuate equations with commas or periods when they are part of a sentence, as in:

$$a + b = \gamma \tag{1}$$

Be sure that the symbols in your equation have been defined before or immediately following the equation. Use "(1)", not "Eq. (1)" or "equation (1)", except at the beginning of a sentence: "Equation (1) is . . ."

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Please use "soft" (e.g., \eqref{Eq}) cross references instead of "hard" references (e.g., (1)). That will make it possible to combine sections, add equations, or change the order of figures or citations without having to go through the file line by line.

Please don't use the {eqnarray} equation environment. Use {align} or {IEEEeqnarray} instead. The {eqnarray} environment leaves unsightly spaces around relation symbols.

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- The word "data" is plural, not singular.
- The subscript for the permeability of vacuum  $\mu_0$ , and other common scientific constants, is zero with subscript formatting, not a lowercase letter "o".
- In American English, commas, semicolons, periods, question and exclamation marks are located within quotation marks only when a complete thought or name is cited, such as a title or full quotation. When quotation marks are used, instead of a bold or italic typeface, to highlight a word or phrase, punctuation should appear outside of the quotation marks. A parenthetical phrase or statement at the end of a sentence is punctuated outside of the closing parenthesis (like this). (A parenthetical sentence is punctuated within the parentheses.)
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- The prefix "non" is not a word; it should be joined to the word it modifies, usually without a hyphen.
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An excellent style manual for science writers is .

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## G. Identify the Headings

Headings, or heads, are organizational devices that guide the reader through your paper. There are two types: component heads and text heads.

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## TABLE I TABLE TYPE STYLES

Table	Table Column Head		
Head	Table column subhead	Subhead	Subhead
copy	More table copy <sup>a</sup>		
<sup>a</sup> Sample of a Table footnote.			

Fig. 1. Example of a figure caption.

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#### ACKNOWLEDGMENT

The preferred spelling of the word "acknowledgment" in America is without an "e" after the "g". Avoid the stilted expression "one of us (R. B. G.) thanks ...". Instead, try "R. B. G. thanks...". Put sponsor acknowledgments in the unnumbered footnote on the first page.

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For papers published in translation journals, please give the English citation first, followed by the original foreign-language citation [28].

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