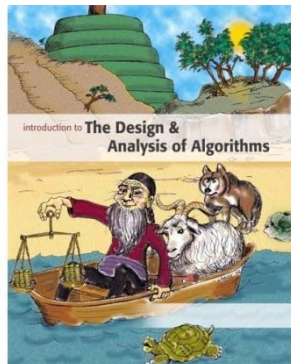




Introduction to

# *Algorithm Design and Analysis*

[13] Undirected Graph



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# In the Last Class...

- **Directed Acyclic Graph**
  - Topological Order
  - Critical Path Analysis
- **Strongly Connected Component**
  - Strong Component and Condensation
  - Finding SCC based on DFS



# DFS on Undirected Graph

- **Undirected Graph**
  - Symmetric Digraph
  - Undirected Graph DFS Skeleton
- **Biconnected Components**
  - *Articulation Points* and 2-point connectedness
  - *Bridge* and 2-edge connectedness
- **Other undirected graph problems**
  - Orientation of an undirected graph
  - Warm up: Minimum Spanning Tree based on DFS



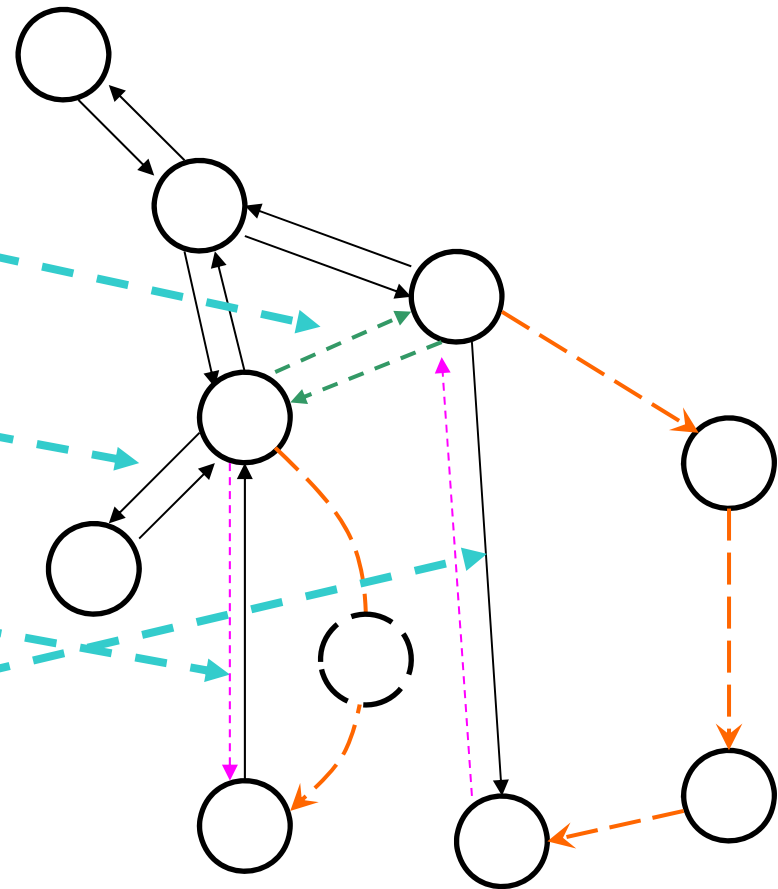
# What is Different for “Undirected”

- **Characteristics of undirected graph traversal**
  - One edge may be traversed for **two times** in opposite directions.
- **For an undirected graph, DFS provides an orientation for each of its edges**
  - Oriented in the direction in which they are first encountered.



# Edges in DFS

- **Cross edge**
  - Not existing
- **Back edge**
  - Back to the direct parent:  
second encounter
  - Otherwise: **first encounter**
- **Forward edge**
  - Always second encounter, *and first time as back edge*



# Modifications to the DFS Skeleton

- All the **second encounter** are **bypassed**.
- So, the *only substantial modification* is for the possible back edges leading to an ancestor, but not direct parent.
- We need know the *parent*, that is, the direct ancestor, for the vertex to be processed.



# DFS Skeleton for Undirected Graph

- `int dfsSweep(IntList[] adjVertices, int n, ...)`
- `int ans;`
- **<Allocate color array and initialize to white>**
- For each vertex  $v$  of  $G$ , in some order
- `if (color[v]==white)`
- `int vAns=dfs(adjVertices, color, v, -1, ...);`
- **<Process vAns>**
- `// Continue loop`
- `return ans;`



Recording the parent

# DFS Skeleton for Undirected Graph

- `int dfs(IntList[] adjVertices, int[] color, int v, int p, ...)`
- `int w; IntList remAdj; int ans;`
- `color[v]=gray;`
- **<Preorder processing of vertex v>**
- `remAdj=adjVertices[v];`
- `while (remAdj≠nil)`
- `w=first(remAdj);`
- `if (color[w]==white)`
- **<Exploratory processing for tree edge vw>**
- `int wAns=dfs(adjVertices, color, w, v ...);`
- **< Backtrack processing for tree edge vw , using wAns>**
- `else if (color[w]==gray && w≠p)`
- **<Checking for nontree edge vw>**
- `remAdj=rest(remAdj);`
- **<Postorder processing of vertex v, including final computation of ans>**
- `color[v]=black;`
- `return ans;`





# Complexity of Undirected DFS

- $\Theta(m+n)$ 
  - If each inserted statement for specialized application runs in constant time
  - The same with directed graph DFS
- **Extra space  $\Theta(n)$** 
  - For array *color*, or activation frames of recursion.



# Biconnected Graph

- **Being connected**
  - Tree: acyclic, least (cost) connected
  - Node/edge connected: fault tolerant connectedness
- **Articulation point (2-node connected)**
  - $v$  is an articulation point if deleting  $v$  leads to disconnection
- **Bridge (2-edge connected)**
  - $uv$  is a bridge if deleting  $uv$  leads to disconnection

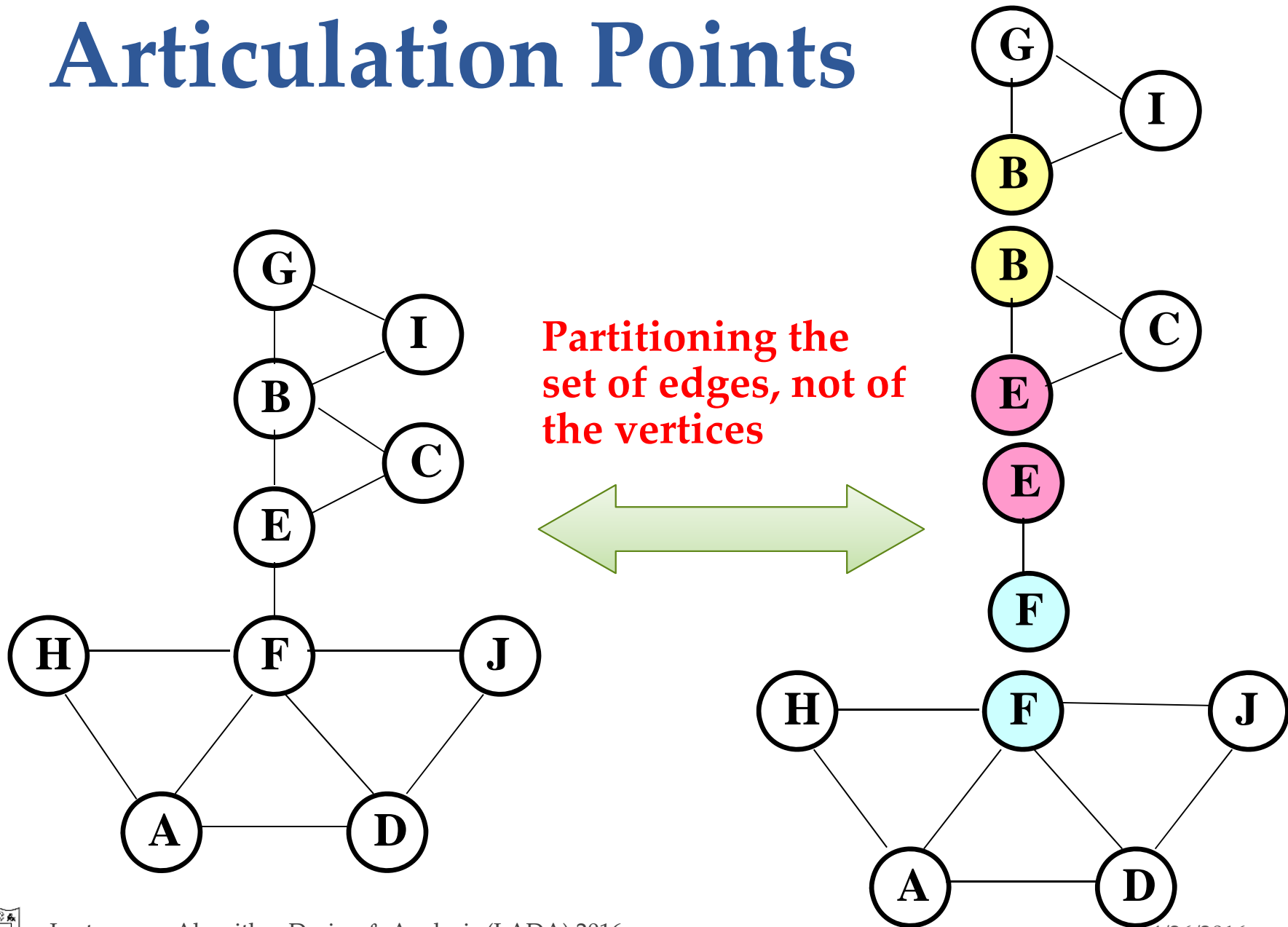


# Biconnected Graph

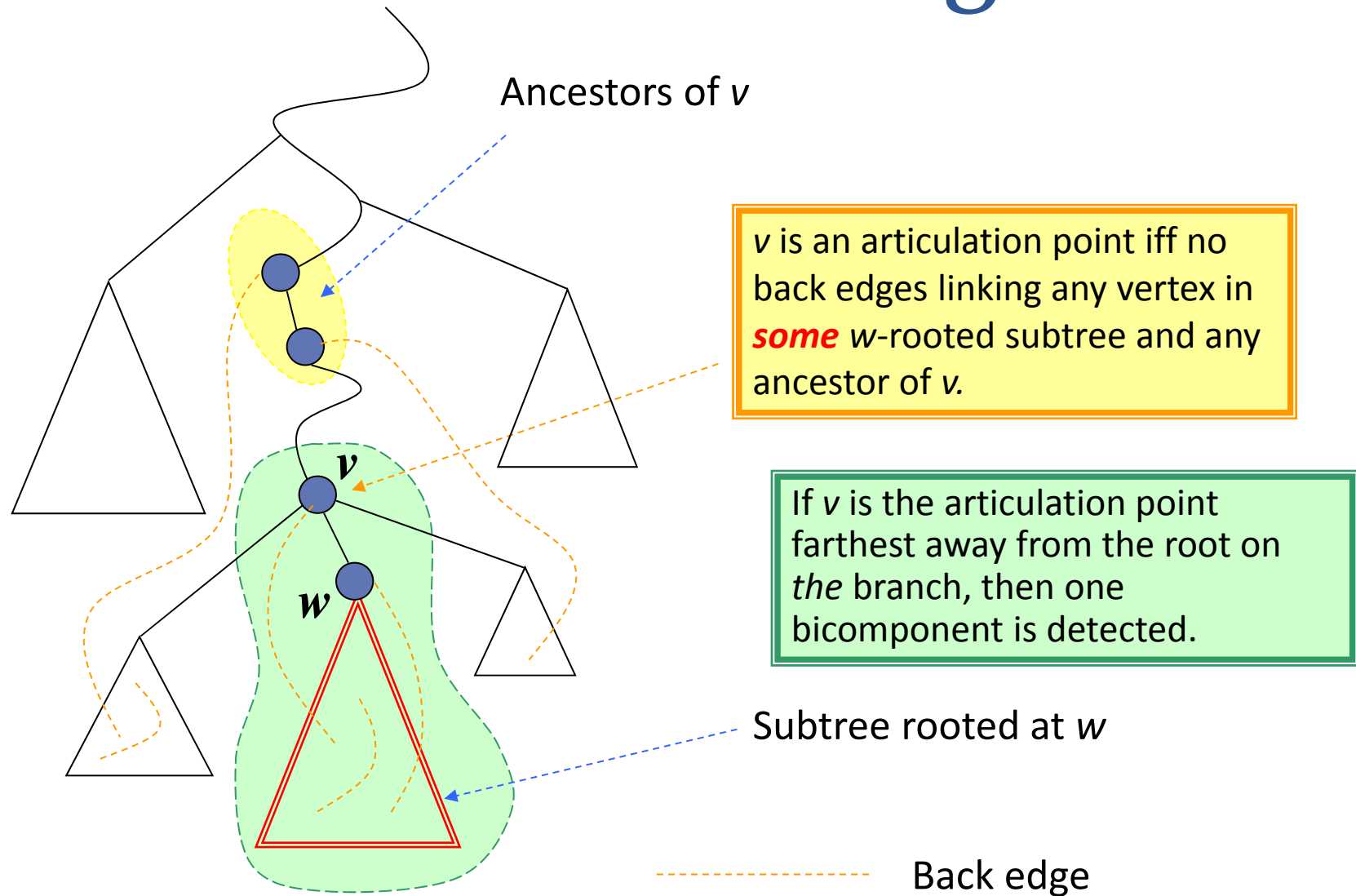
- **Articulation point**
  - $v$  is an articulation point if there **exist** nodes  $w$  and  $x$ , such that  $v$  is in **every** path from  $w$  to  $x$  ( $w$  and  $x$  are vertices different from  $v$ )
- **Bridge**
  - $uv$  is a bridge if node  $u$  and  $v$  are connected **only** by edge  $uv$
- **Bicomponent**
  - Maximal biconnected subgraph



# Articulation Points



# Articulation Point Algorithm



# Updating the value of *back*

- $v$  first discovered

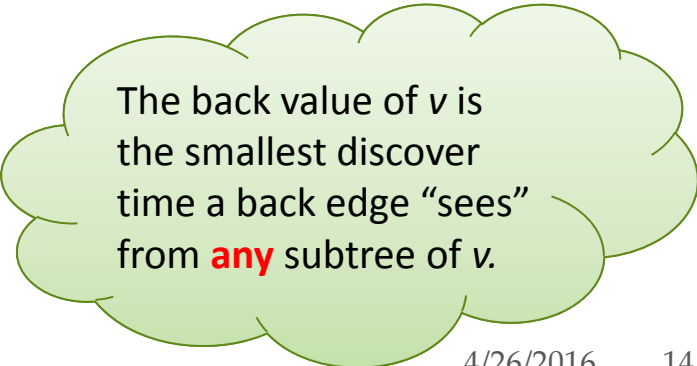
$back = discoverTime(v)$

- Trying to explore, but a back edge  $vw$  from  $v$  encountered

$back = \min(back, discoverTime(w))$

- Backtracking from  $w$  to  $v$

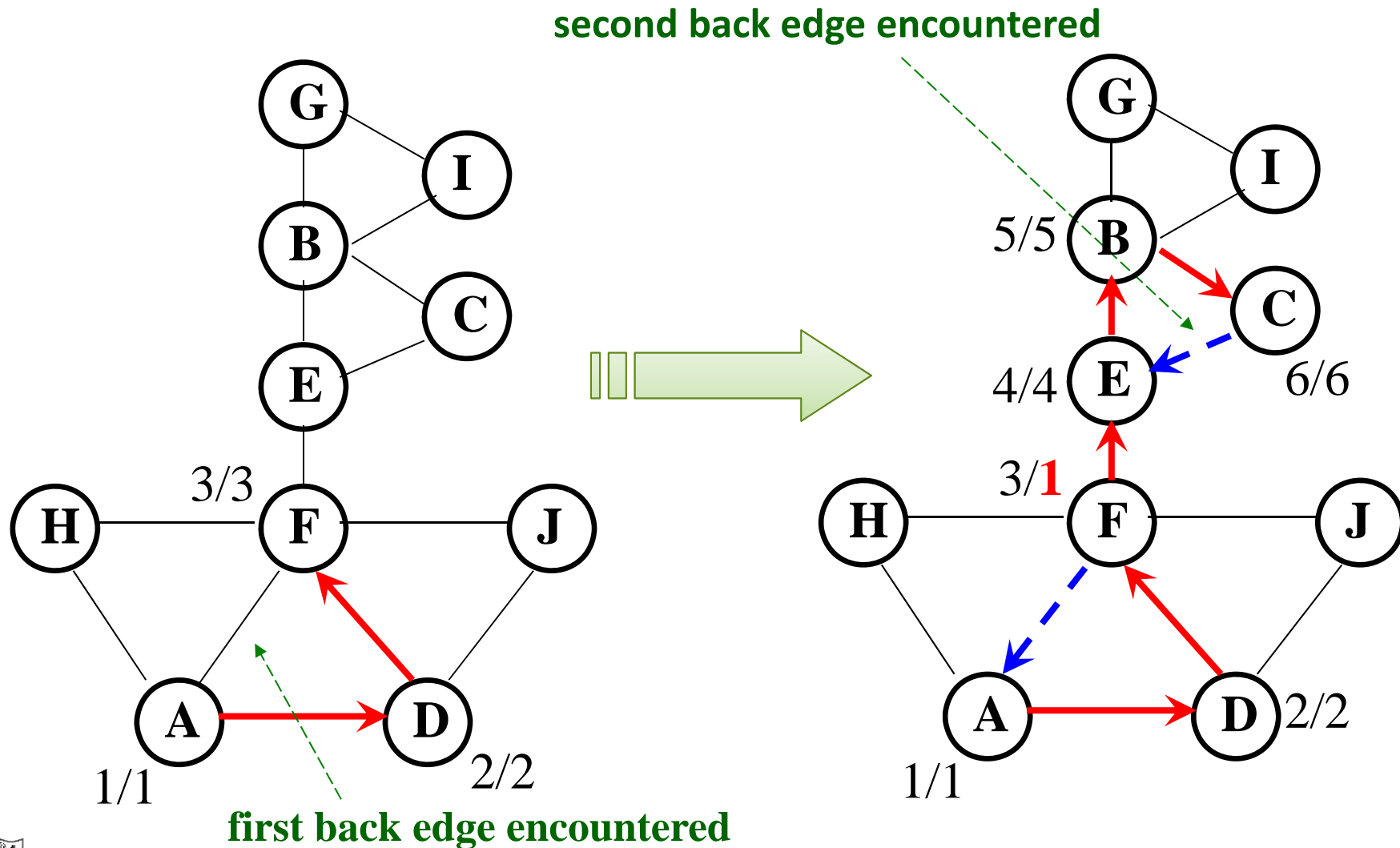
$back = \min(back, wback)$



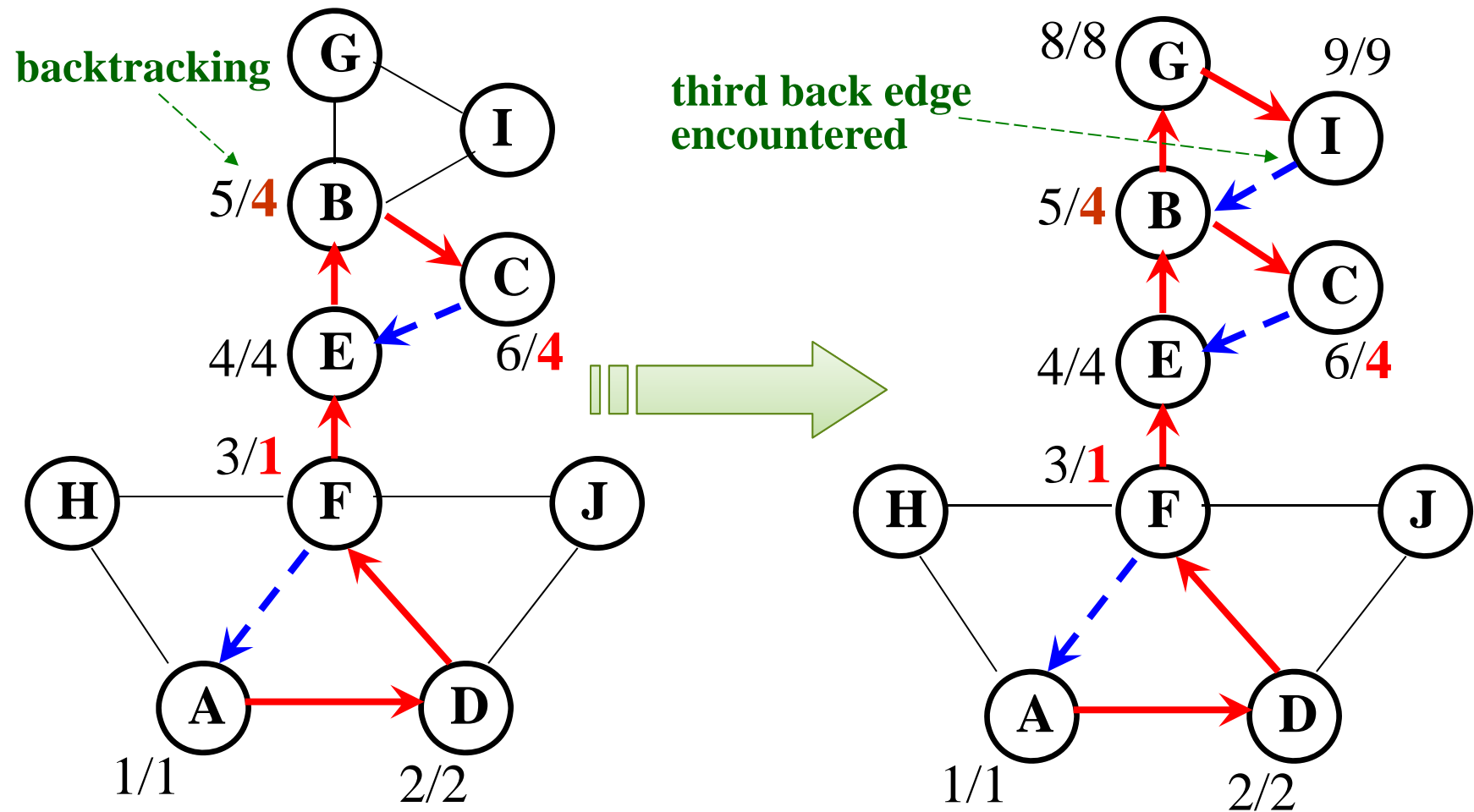
The back value of  $v$  is the smallest discover time a back edge “sees” from **any** subtree of  $v$ .



# Example

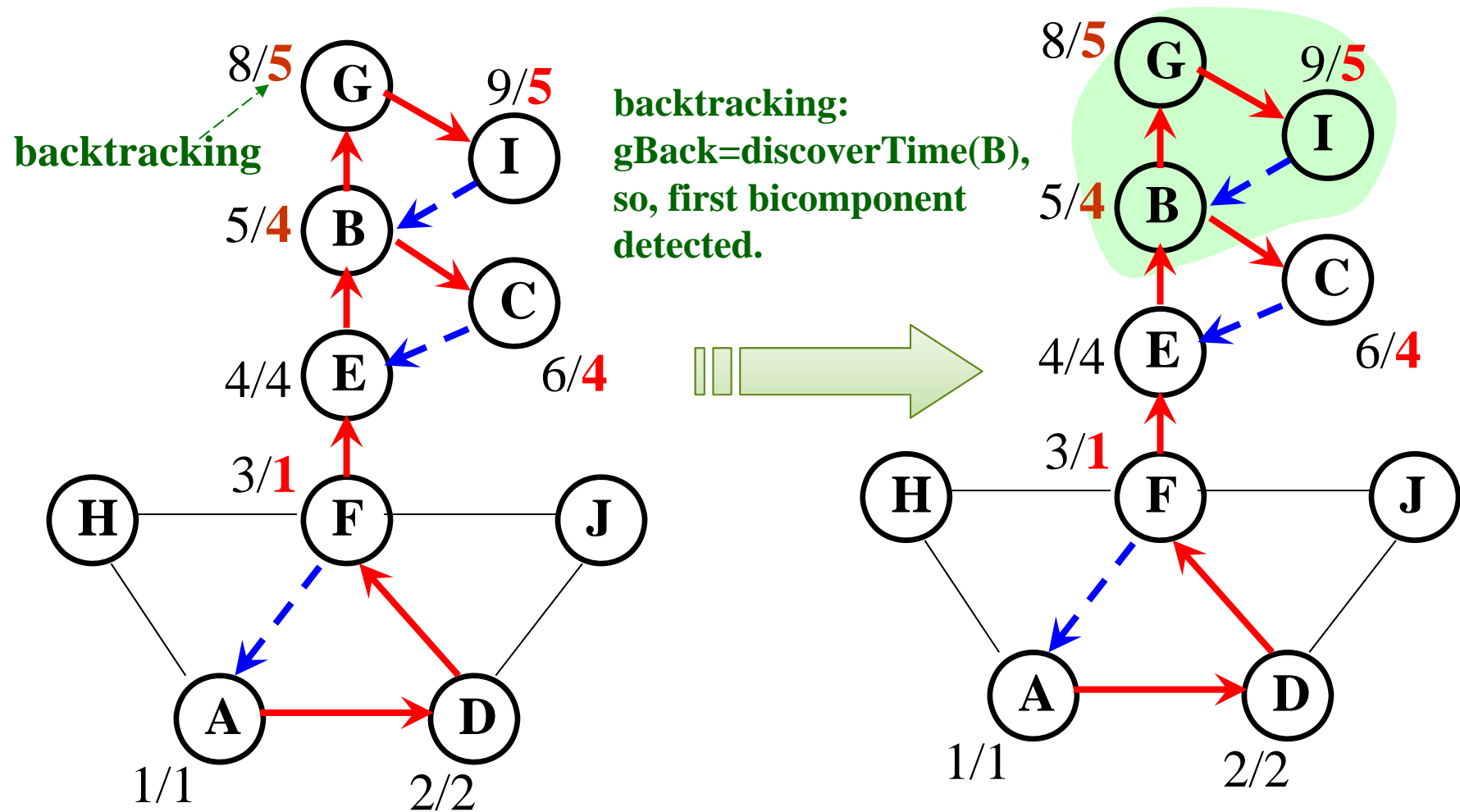


# Example





# Example



# Keeping the Track of Backing

- **Tracking data**
  - For each vertex  $v$ , a local variable  $back$  is used to store the required information, as the value of *discoverTime* of some vertex.
- **Testing for bicomponent**
  - At backtracking from  $w$  to  $v$ , the condition implying a bicomponent is:
    - $wBack \geq discoverTime(v)$   
(where  $wBack$  is the returned back value for  $w$ )

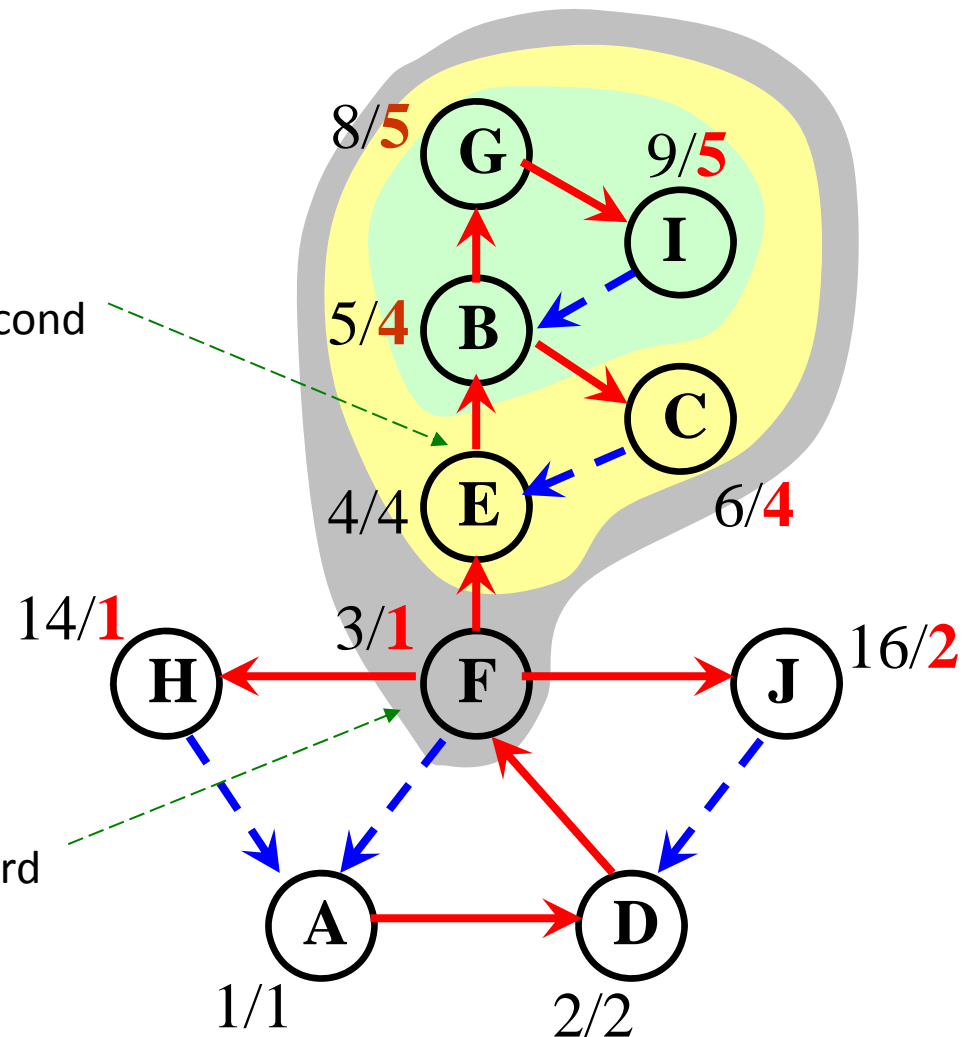
when  $back$  is no less than the discover time of  $v$ , there is at least one subtree of  $v$  connected to other part of the graph only by  $v$ .



# Example

Backtracking from B to E:  
bBack=discoverTime(E), so, the second  
bicomponent is detect

Backtracking from E to F:  
eBack>discoverTime(F), so, the third  
bicomponent is detect



# Articulation Point Algorithm

- `int bicompDFS(v)`
- `color[v]=gray; time++; discoverTime[v]=time;`
- `back=discoverTime[v];`
- `while (there is an untraversed edge vw)`
- `<push vw into edgeStack>`
- `if (vw is a tree edge)`
- `wBack=bicompDFS(w);`
- `if (wBack≥discoverTime[v])`
- `Output a new bicomponent`
- `by popping edgeStack down through vw ;`
- `back=min(back, wBack);`
- `else if (vw is a back edge)`
- `back=min(discoverTime[w], back);`
- `time++; finishTime[v]=time; color[v]=black;`
- `return back;`

## Outline of core procedure



# Correctness

- **We have seen that:**
  - If  $v$  is the articulation point farthest away from the root on the branch, then one bicomponent is detected.
- **So, we need only prove that:**
  - In a DFS tree, a vertex(not root)  $v$  is an articulation point **if and only if** (1)  $v$  is not a leaf; (2) **some** subtree of  $v$  has **no back edge** incident with a proper ancestor of  $v$ .

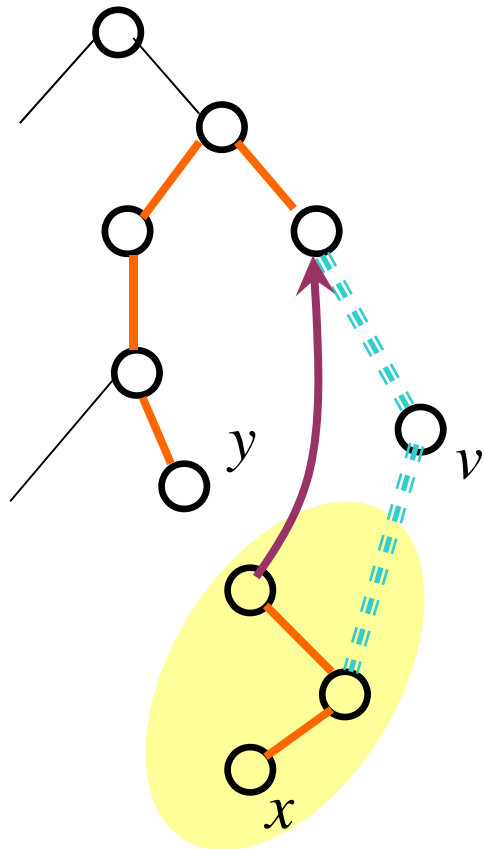


# Characteristics of Articulation Point

- In a DFS tree, a vertex(not root)  $v$  is an articulation point **if and only if** (1) $v$  is not a leaf; (2) **some** subtree of  $v$  has **no back edge** incident with a proper ancestor of  $v$ .
- $\Leftarrow$  Trivial
- $\Rightarrow$ 
  - By definition,  $v$  is on **every** path between some  $x,y$ (different from  $v$ ).
  - At least one of  $x,y$  is a proper descendent of  $v$ (otherwise,  $x \leftrightarrow \text{root} \leftrightarrow y$  not containing  $v$ ).
  - By **contradiction**, suppose that **every** subtree of  $v$  has a back edge to a proper ancestor of  $v$ , we can find a  $xy$ -path not containing  $v$  for all possible cases(only 2 cases)



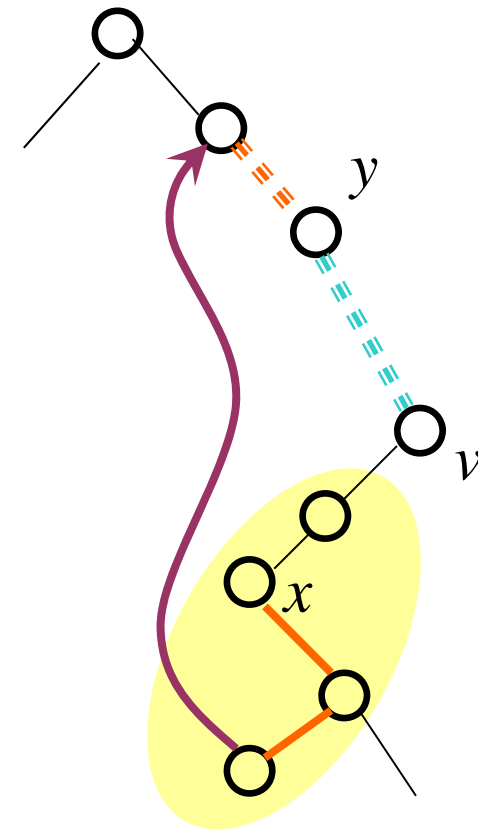
# Case 1



Case 1.1: another is not an ancestor of  $v$

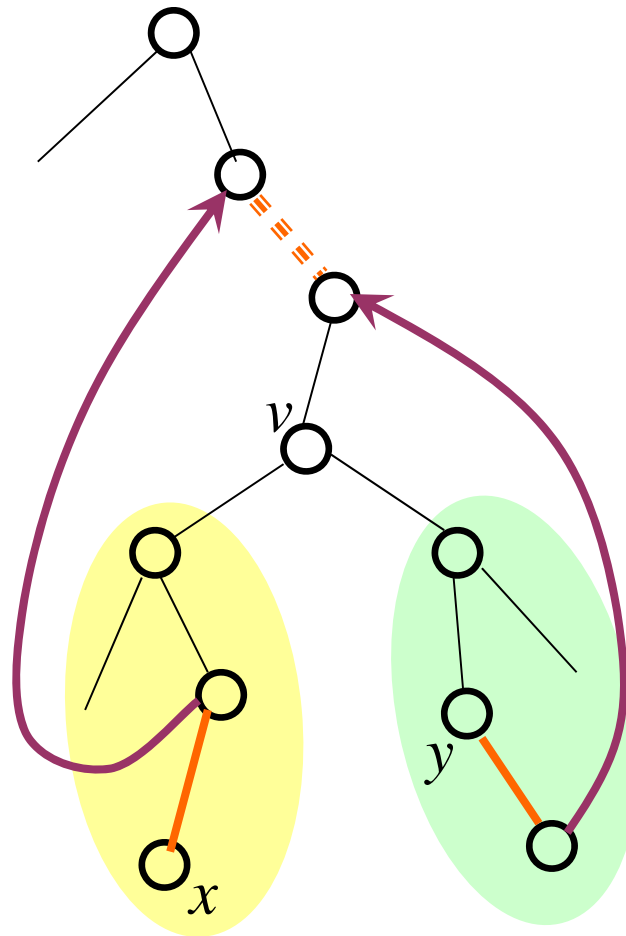
suppose that **every** subtree of  $v$  has a back edge to a proper ancestor of  $v$ , and, exactly one of  $x, y$  is a descendant of  $v$ .

Case 1.2: another is an ancestor of  $v$



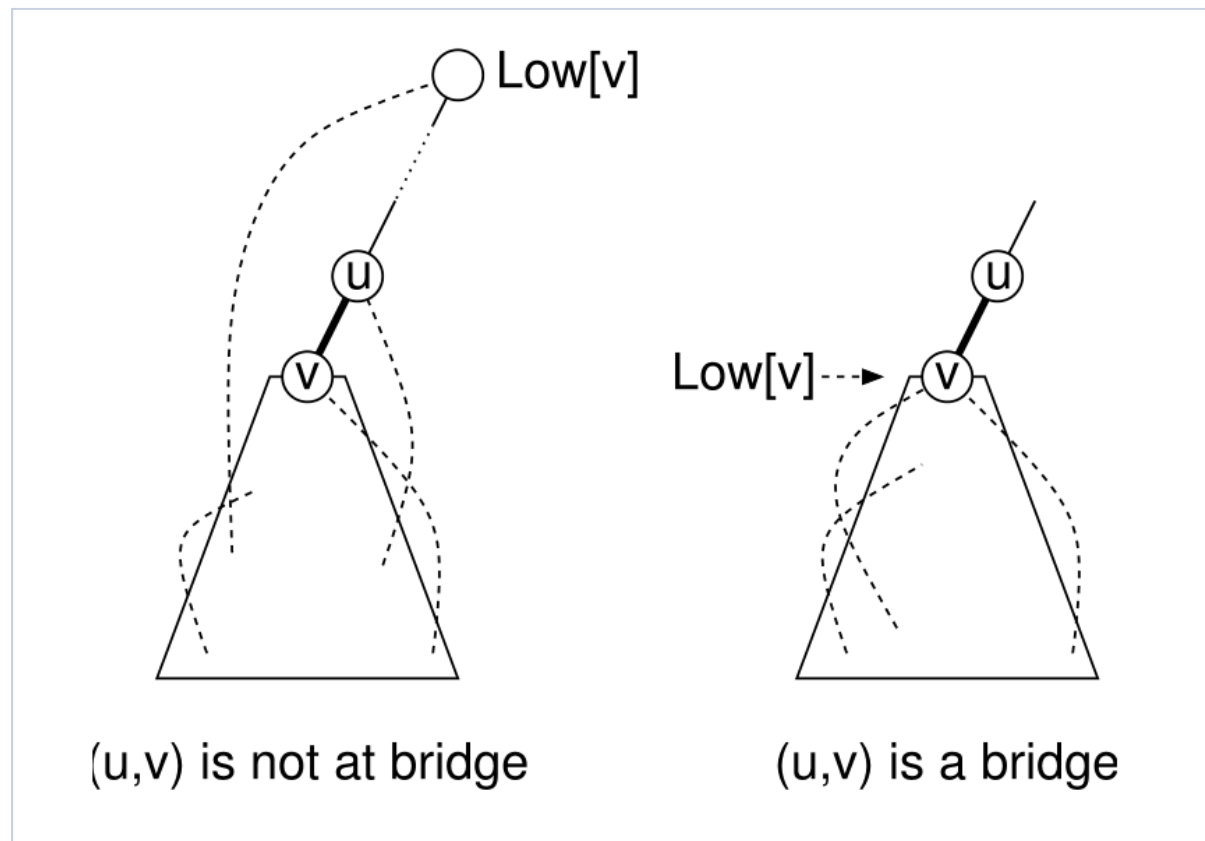
# Case 2

suppose that **every** subtree of  $v$  has a back edge to a proper ancestor of  $v$ , and, both  $x$ ,  $y$  are descendants of  $v$ .





# Finding the Bridge



# Finding the Bridge

- Edge  $uv$  is a bridge iff
  - (assuming that  $u$  is the parent and  $v$  is the child)
- a) Edge  $uv$  is a tree edge in DFS
- b) There is **no subtree rooted at  $v$**  to a proper ancestor of  $v$  (including  $u$ )



# Edge Finding Algorithm

Bridge Finding by DFS

```
findBridges(u) {  
    color[u] = gray;  
    Low[u] = d[u] = ++time;          // set discovery time and init Low  
    for each (v in Adj(u)) {  
        if (color[v] == white) {    // (u,v) is a tree edge  
            pred[v] = u;             // v's parent is u  
            findBridges(v);  
            Low[u] = min(Low[u], Low[v]) // update Low[u]  
            if (Low[v] > d[u]) Report that (u,v) is a bridge  
        }  
        else if (v != pred[u])      // (u,v) is a back edge  
            Low[u] = min(Low[u], d[v]) // update Low[u]  
    }  
}
```



# Orientation for Undirected Graphs

- **Orientation**
  - Give each edge a direction
  - Satisfying pre-specified constraints
    - E.g., the “in-degree of each vertex is at least 1”
- **Possible or not?**
  - If possible, how to?
- **As for “in-degree  $\geq 1$ ”**
  - Orientation possible iff. the graph has at least a circle
    - Find the end point of some back edge
    - A second DFS from this end point



# Warm Up for MST

MST: Minimum  
Spanning Tree

- **Get MST in  $O(m+n)$  time**
  - Given that edges weights are only 1 and 2
- **Graph traversal is sufficient**
  - DFS over “weight 1 edges” only
  - DFS over “weight 2 edges” only



*Thank you!*

*Q & A*

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